# Operating Instructions **Turbimax CUS71D**

Ultrasonic interface sensor Immersion sensor for interface measurement





## About this document

## Notes on safety icons

The structure, signal words and safety colors of the signs comply with the specifications of ANSI Z535.6 ("Product safety information in product manuals, instructions and other collateral materials").

Safety message structure	Meaning
▲ DANGER Cause (/consequences) Consequences if safety message is not heeded ► Corrective action	This symbol alerts you to a dangerous situation. Failure to avoid the situation <b>will</b> result in a fatal or serious injury.
▲ WARNING Cause (/consequences) Consequences if safety message is not heeded ► Corrective action	This symbol alerts you to a dangerous situation. Failure to avoid the situation <b>can</b> result in a fatal or serious injury.
▲ CAUTION Cause (/consequences) Consequences if safety message is not heeded ► Corrective action	This symbol alerts you to a dangerous situation. Failure to avoid this situation can result in minor or medium injury.
NOTICE Cause/situation Consequences if safety message is not heeded ► Action/note	This symbol alerts you to situations that can result in damage to property and equipment.

### Symbols

- Additional information, tips
- Permitted or recommended
- **×** Forbidden or not recommended

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## 1 Basic safety instructions

### 1.1 Requirements for the personnel

- Installation, commissioning, operation and maintenance of the measuring system must only be carried out by trained technical personnel.
- The technical personnel must be authorized by the plant operator to carry out the specified activities.
- The electrical connection may only be performed by an electrical technician.
- The technical personnel must have read and understood these Operating Instructions and must follow the instructions they contain.
- Measuring point faults may only be rectified by authorized and specially trained personnel.
- Repairs not described in the enclosed Operating Instructions may only be carried out directly at the manufacturer's or by the service organization.

## 1.2 Designated use

CUS71D is an immersion sensor designed for interface measurement in water and wastewater.

The sensor is particularly suited for use in the following applications:

- Wastewater treatment: primary clarifier, sludge thickener, secondary clarifier
- Water purification: settling basin after flocculant dosage, sludge height in contact sludge process
- Static separation process: With / without slow stirring and without air inclusion.

Any other use than the one described here compromises the safety of persons and the entire measuring system and is not permitted.

The manufacturer is not liable for damage caused by improper or non-designated use.

#### NOTICE

#### Use outside specification

Incorrect measurements, malfunctions and even measuring point failure are possible

- Only operate the product in line with the product specifications.
- Pay particular attention to the technical data of the sensor.

### 1.3 Workplace safety

As the user, you are responsible for complying with the following safety conditions:

- Regulations for explosion protection
- Installation instructions
- Local standards and regulations

### 1.4 Operational safety

- Before commissioning the entire measuring point, make sure all the connections are correct. Ensure that electrical cables and hose connections are not damaged.
- Do not operate damaged products, and safeguard them to ensure that they are not operated inadvertently. Mark the damaged product as defective.
- If faults cannot be rectified, the products must be taken out of service and secured against unintentional commissioning.

### 1.5 Product safety

The product is designed to meet state-of-the-art safety requirements, has been tested and left the factory in a condition in which it is safe to operate. Relevant regulations and European standards have been observed.

## 2 Incoming acceptance and product identification

### 2.1 Incoming acceptance

- Make sure the packaging is undamaged!
- Inform the supplier about any damage to the packaging. Keep the damaged packaging until the matter has been settled.
- Make sure the contents are undamaged!
- Inform the supplier about damage to the contents. Keep the damaged products until the matter has been settled.
- Check that the order is complete and agrees with your shipping documents.
- The packaging material used to store or to transport the product must provide shock protection and humidity protection. The original packaging offers the best protection. Also, keep to the approved ambient conditions (see "Technical data").
- ► If you have any questions, please contact your supplier or your local sales center.

## 2.2 Nameplate

Compare the order code indicated on the nameplate to the product structure and your order.

The nameplate contains the following information:

- Manufacturer data
- Order code (device version)
- Extended order code
- Serial number

To discover what sensor version you have, enter the order code on the nameplate into the search screen at the following address: www.products.endress.com/order-ident

## 2.3 Scope of delivery

The scope of delivery comprises:

- 1 sensor Turbimax CUS71D in the ordered version
- 1 Operating Instructions BA00490C/07/EN

If you have any questions, please contact your supplier or your local sales center.

## 2.4 Certificates and approvals

#### Declaration of conformity

The product meets the requirements of the harmonized European standards. It thus complies with the legal requirements of the EC directives.

The manufacturer confirms successful testing of the product by affixing the CE symbol.

## 3 Installation

## 3.1 Dimensions



Fig. 1: Dimensions of standard sensor

Fig. 2: Dimensions of sensor with wiper

### 3.2 Installation instructions

#### 3.2.1 Measuring system

A complete measuring system comprises:

- Ultrasonic sensor Turbimax CUS71D
- Multi-channel transmitter Liquiline CM44x

and optional:

- Weather protection roof CYY101
- Holder system Flexdip CYH112
- Fixed or rotatable immersion pipe Flexdip CYA112



5

6

7

Fig. 3: Ultrasonic sensor with holder system and multi-channel transmitter

- 1 Holder system Flexdip CYH112
- 2 Multi-channel transmitter Liquiline CM44x
- *3* Weather protection roof
- 4 Assembly Flexdip CYA112

- Ultrasonic sensor Turbimax CUS71D
- Perpendicularly from all sides
- Splash protection cap



#### 3.2.2 Measuring system with pendulum holder

Fig. 4: Measuring system with pendulum adapter

CYH112

- Cross clamp of holder system Flexdip CYH112
   Pendulum adapter of holder system Flexdip
- 3 Assembly Flexdip CYA112 with CUS71D
- Pendulum adapter of holder system Flexdip 4 PVC
- 4 PVC sensor protector

The PVC sensor protector protects the ultrasonic sensor from getting damaged by the surface skimmer.

When using surface skimmer do not use sensors with wiper.

#### 3.3 Installation conditions

#### **Basin configuration**



Fig. 5: Basin configuration

- A Sensor
- B Minimum distance of sensor to basin wall = 45 cm (1.48 ft.)
- C Reference point e.g. water surface
- D Zero point E Basin depth
- *F* Opening angle of ultrasonic cone, 6°

#### Installation instructions

Look at the construction drawing of the basin for a suitable position for the sensor. In doing so, you must take the following factors into account:

- The minimum distance between the basin wall and the sensor is 45 cm (1.48 ft.) (sensor emits ultrasound in conical form).
- There should not be any basin wall protrusions or piping in the measuring range below the sensor. Scrapers that are only temporarily in this area are permitted.
- Do not install the sensor in zones in which air bubbles, turbulence, high levels of turbid material or suspended matter or foam formation occur (e.g. inlet).
- Using an immersion tube, install the sensor 20 cm (0.66 ft.) beneath the surface of the water.
- The transmitter may not be installed in a second enclosure (heat accumulation).
- If possible, do not install the transmitter near high voltage sources. In addition, also avoid sources of magnetic fields, e.g. large transformers or frequency converters.
- The system can only detect a separation zone if there is a clear transition between the zones. Unclear transition from the liquid to the solid phase cannot be detected.

#### **Circular Clarifier**



Fig. 6: Basin configuration in circular clarifier

А	View from top

- 1 Surface skimmer
- 2 Walk way
- 3 Sensor mounting
- 4 Bottom rake

5 Rake direction

- В Cross section 11 Sensor
  - Hand rail
- 12 Surface skimmer
- 13 Bottom rake 14

#### Post-installation check 3.4

- Sensor and cable undamaged?
- ► Cap undamaged?
- Compliance with permissible sensor installation position?
- ▶ Is the sensor installed in an assembly and is not suspended from the cable?
- Avoid moisture by rain by putting the protective cap on the assembly?

## 4 Electrical connection

#### **A** WARNING

#### Device is energized

Improper connection can cause injury or death.

- The electrical connection must only be carried out by a certified electrician.
- Technical personnel must have read and understood the instructions in this manual and must adhere to them.
- **Prior to beginning** any wiring work, make sure voltage is not applied to any of the cables.

### 4.1 Connecting to the transmitter

You can connect only one sensor to the transmitter Liquiline CM442. You can connect up to four sensors to the transmitters Liquiline CM444 and CM448.

The sensor is connected to the transmitter as follows:



Fig. 7: Sensor connection

The maximum cable length is 100 m (328 ft).

To extend the sensor cable, the following accessories are recommended:

- Measuring cable CYK11 with ferrules and
- Junction box "cable / cable"

## 4.2 Post-connection check

Instrument status and specifications	Remarks	
Are the sensor, assembly, junction box or cable damaged?	Visual inspection	
Electrical connection	Remarks	
Does the supply voltage of the transmitter match the specifications on the nameplate?		
Are the installed cables strain-relieved and not twisted ?		
Is the cable type route completely isolated ?	Power cable/weak current cable	
Are the power supply and signal cable correctly connected to the transmitter ?	Use the connection diagram of the transmitter.	
Long enough length of cable core stripped and correct in terminal?	Check seating (pull slightly)	
Are all the screws terminals properly tightened ?	Tighten	
Are all the cable entries installed, tightened and sealed ?	For cable entries lateral: cable loops	
Are all the cable entries installed downwards or lateral ?	downwards for water to be able to dr	

## 5 Device description

### 5.1 Sensor design

The sensor is designed for continuous in-situ determination of interfaces.

The sensor includes all necessary modules:

- Power supply
- Ultrasonic source sends the measurement signals.
- Ultrasonic receiver receives the measurement signals, digitalizes and converts the signals to a measurement value.
- The microcontroller of the sensor controls the internal operations and the data transmission.

All data - including calibration data - are stored in the sensor. That means:

- A pre-calibrated sensor can be used at the measuring point.
- The sensor can be calibrated externally.
- The sensor can be used at multiple measuring points with different calibration data.

### 5.2 Measuring principle

A piezoelectric crystal is integrated in a flat cylindrical plastic housing. When the crystal is excited by an electrical voltage, it generates a sonar signal. The ultrasonic waves are transmitted at a frequency of 657 kHz at an angle of 6° to scan the separation zones. The parameter measured is the time it takes for the transmitted ultrasonic signal to reach the solid particles in the separation zone and return to the receiver.

A sensor version with wiper avoids film formation at the sensor membrane.

### 5.3 Function

The speed of the sound varies according to the physical properties of the measuring medium and is affected by temperature and air pressure. The liquid zones and solids content of the medium also vary.

To obtain precise measurement results, it is therefore vital to adapt system variables to the process, e. g. pulselength and the speed of the sound.

The CM44x offers the following possibilities for signal evaluation:

- Mask out regions where the separation zone is not expected.
- Evaluate received signal strengths differently.
- Select leading or trailing signal edges in the evaluation.
- Amplify sensor signals at different rates, e. g. for floating sludge.
- Define a region (gate) above and below the separation zone. Signal evaluation only takes place in the defined region. The gate wanders with the separation zone. This makes smoothing algorithms unnecessary.

### 5.4 Sensor monitoring

The optical signals are continuously monitored und checked for plausibility. Discrepancies are reported via error messages by the transmitter.

The sensor check system of the Liquiline CM44x reports the following failure conditions:

- Implausible high or low measuring values
- Disturbed controlling due to erroneous measuring values

#### 5.5 Parametrization in the process

The settings are performed by inputs at Liquiline CM44x (see BA00451C/07/EN).

### 5.6 Factory settings

The sensor is initialized in the factory. After adjusting the tank parameters the sensor is ready for the standard applications without further adjustments. The factory settings are nonvolatile.

## 5.7 Cyclic cleaning

For cyclic cleaning a ultrasonic sensor with integrated wiper is available. The time interval is selectable via software.

## 6 Commissioning

### 6.1 Firmware update

Turbimax CUS71D needs a firmware version "01.02.02-0048" or later. Your current firmware version can be found at:

Menu/Diagnostics/System information/Software version

If your controller is equipped with an older firmware version you have to perform a firmware update.

First save your current setup on an SD card since a firmware update overwrites your settings with the factory settings. After updating the firmware, you can restore your setup by uploading it from the SD card.

To install a firmware update, you must have the update available on an SD card.

- 1. Insert the SD card into the controller card reader.
- 2. Go to: Menu/Setup/General settings/Extended setup/Data management/Firmware update.

--> The update files on the SD card are displayed.

3. Select the desired update and select yes when the following question is displayed: The current firmware will be overwritten. After this the device will reboot. Do you want to proceed?

--> The firmware is loaded and the device is then started with the new firmware.

### 6.2 Basic settings

After switching on the controller you have to perform some settings to get correct measurement

EH_CM442_C8024A056 CH1: 1:1 None	00 OK	After system initialization the adjacent display appears.
CH2: 1:2 None		
Current output 1:1	21.5 mA	
Current output 1:2	21.5 mA	
Current output 3:1	21.5 mA	
Current output 3:2	21.5 mA	
Alarm relay	On	
Relay 2:1	Off	
MENU CAL DIAG	HOLD	

#### Path: Menu/Setup/Inputs/CHx

Menu/Setup/Inputs OK Sensor type Ultrasonic interface > Ultrasonic interface ESC CAL DIAG ?	Select the sensor type: • UIS (Ultrasonic interface)
Menu/trasonic interface sensor       OK         Channel       On         Searching signal         Sensor operation       Current sensor         Manual hold       Off         Tank configuration         Extended setup         Channel assignment view         ESC       CAL         DIAG       ?	After a restart it takes several minutes (3 to 5) to start the signal processing. After this all menu points are visible.
Menu/trasonic interface sensor       OK         Channel       On         Sensor operation       Current sensor         Wiper function       On         Wiper timing       10 min         Manual hold       Off         > Tank configuration         > Sensor signal         > Extended setup         ESC       CAL	<ul> <li>For sensors with wiper you can select the wiper function and adjust the wiper time:</li> <li>Wiper function: On or Off Default: On</li> <li>Wiper timing: 1 to 240 minutes Default: 10 minutes</li> </ul>
Menu/trasonic interface sensor       OK         Channel       On         Sensor operation       Current sensor         Manual hold       Off         > Tank configuration       Sensor signal         > Sensor signal       Extended setup         > Channel assignment view       ESC	Select Scan for Memosens sensor.

Menu/trasonic interface sensor       OK         Channel       On         Sensor operation       Current sensor         Manual hold       Off         > Tank configuration         > Sensor signal         > Extended setup         > Channel assignment view         ESC       CAL	You can switch the channel to Manual hold • On • Off Default: Off
Display samples:	
EH_CM442_C8024A05G00OKCH1: 1:1 Ultrasonic i1.76 mCH2: 1:2 NoneCurrent output 1:121.5 mACurrent output 1:221.5 mACurrent output 3:121.5 mACurrent output 3:221.5 mAAlarm relayOnRelay 2:1OffMENUCALDIAGHOLD	Overview Push the navigator to switch to the next display (numeric display).
EH_CM442_C8024A05600 OK 05:38:09 06.05.2013 CH1: Ultrasonic interface 1.76 M	Numeric display Push the navigator to switch to the next display (graphic display).
CH1: Ultrasonic interface OK 8.00 m Sensor Sensor 0.00 m Tank bottom. MENU CAL DIAG HOLD	Graphic display Push the navigator to switch to the next display (overview).

#### The menu **Tank configuration** defines tank depth OK Menu/...trasonic interface sensor and zero adjust. The quality of the measuring Channel On results depends on the accuracy of these inputs. Sensor operation **Current** sensor Manual hold Off Tank configuration Sensor signal Extended setup Channel assignment view ESC CAL DIAG 2 Select the blanket definition: Menu/...ensor/Tank configuration OK Interface level Blanket definition Interface level The distance from bottom to blanket is displayed. Unit of measure m Interface range Tank depth 3.0 m The distance from waterline to blanket is Zero adjust 0.0 m displayed. **Blanking zone** Off ESC CAL DIAG ? 1. Reference point (e.g. waterline) 2. Clear water Г 3. Transmitted and reflected ultrasonic waves 4. Interface solids / clear water िंग 5. Sedimented sludge 6. Ultrasonic transmitter and -receiver 7. Interface level 8. Interface range Tank depth and Zero adjust have the same H reference point. m/ft 6 7 8 5 a0020254 a0019633

#### Path: Menu/Setup/Inputs/UIS/Tank configuration

Menu/ensor/Tank configuration       OK         Blanket definition       Interface level         Unit of measure       m         Tank depth       3.0 m         Zero adjust       0.0 m         Blanking zone       Off	Any change to the <b>Unit of measure</b> applies automatically to all other displays. Default: <b>m</b> Selection: m, cm, ft, inch	
Menu/ensor/Tank configuration       OK         Blanket definition       Interface level         Unit of measure       m         Tank depth       3.0 m         Zero adjust       0.0 m         Blanking zone       Off         ESC       CAL       DIAG	Enter the <b>Tank depth</b> (distance from the waterline to the bottom of the tank or vessel). The accurate value can be taken of the construction drawing or determined by sounding. Default: <b>3.0 m</b> Selection: 0 to 10 m 0 to 1000 cm 0 to 32.8 ft 0 to 393 inch	
Menu/ensor/Tank configuration OK Searching signal Unit of measure m	The value of the sensor memory changes. It will take several minutes (3 to 5) to restart the signal processing. During this routine the numeric display shows a hourglass, the graphic display shows "Rebooting sensor".	
Menu/ensor/Tank configuration       OK         Blanket definition       Interface level         Unit of measure       m         Tank depth       3.0 m         Zero adjust       0.0 m         Blanking zone       Off         ESC       CAL       DIAG	Enter the <b>Zero adjust</b> (distance from the waterline to the sensor diaphragm) Default: <b>0.0 m</b> Selection: 0 to max. tank depth	
For standard applications in wastewater treatment plants and water treatment plants no further settings are necessary. Push "ESC" to display or the measuring value as numeric display or graphic display.		

Menu/ensor/Tank configu         Blanket definition       Int         Jnit of measure       m         Fank depth       3.0         Zero adjust       0.0         Blanking zone       On         Jpper window limit       0.3         .ower window limit       3.3	uration OK terface level ) m ) m } m } m	Outside the <b>Blanking zone</b> (above <b>Upper window</b> <b>limit</b> and below <b>Lower window limit</b> ) the permanent echo signals are blanked as interference signals. For upper and lower window limit enter the distance to the waterline. In the adjacent example the permanent echo signals are blanked outside the range of 0.3 to 3.3 m. Default: <b>Off</b>



Menu/trasonic interf Channel Sensor operation Manual hold Tank configuration Sensor signal Extended setup Channel assignment ESC CAL DIAG	ace sensor OK On Current sensor Off view	The parameters in the menu <b>Sensor signal</b> are factory preset. If measurement failures are observed the parameters can be adjusted.
Menu/ace sensor/Ser Acoustic control Current gain Gain control set point Refresh rate Damping ESC CAL DIAG	nsor signal OK Automatic 30 10 6 s 130 ?	<ul> <li>Acoustic control</li> <li>Automatic Automatic amplification control</li> <li>Manual Manual amplification control</li> <li>Default: Automatic</li> <li>The manual acoustic control is used for diagnostic purposes.</li> </ul>
Menu/ace sensor/Ser Acoustic control Current gain Gain control set point Refresh rate Damping ESC CAL DIAG	nsor signal OK Automatic 30 10 6 s 130 ?	In automatic mode you cannot modify the parameter <b>Current gain</b> . In standard applications the Current gain shows 20 to 60. At each "Rebooting sensor" the initial value will be automatically adjusted till the measured value is stable. In the manual mode you can modify the parameter <b>Current gain</b> in the range of 0 to 100.
Menu/ace sensor/Ser Acoustic control Current gain Gain control set point Refresh rate Damping ESC CAL DIAG	nsor signal OK Automatic 30 10 6 s 130 ?	The <b>Gain control set point</b> (automatic mode only) determines the relative signal strength. You can enter a value from 5 to 50. Increase this parameter to cause <b>Auto Gain</b> to seek a generally higher level of signal amplification. Decrease this parameter to cause <b>Auto Gain</b> to seek a generally lower level of signal amplification. Default: <b>10</b> Typical value: 10 to 20

#### Path: Menu/Setup/Inputs/UIS/Sensor signal

Menu/ace sensor/Ser Acoustic control Current gain Gain control set point Refresh rate Damping	nsor signal OK Automatic 30 10 6 s 130	The <b>Refresh rate</b> determines the time span to update the current measurement. Default: <b>6 s</b> Selection: 2, 4, 6, 8 s The numerical display will be refreshed every 12 s, the graphical display will be refreshed every 30 s.
ESC CAL DIAG	?	Damping
Menu/ace sensor/Ser Acoustic control Current gain Gain control set point Refresh rate Damping ESC CAL DIAG	nsor signal OK Automatic 30 10 6 s 130	This parameter establishes the number of updates that are averaged to determine the current measurement. It is used to remove the effects of random fluctuations caused by settling or disturbed material. Also it prevents sudden changes in the measurement resulting from the action of rakes and skimmers. For standard applications in wastewater treatment plants a higher value is recommended (e.g. 130). For standard applications in water treatment plants with fast changes in filter backflushing a low value is recommended (e.g. 50). Default: <b>130</b> Selection: 5 to 255.

### Path: Menu/Setup/Inputs/UIS/Extended Setup

Menu/e sensor/Extended setup       OK         Sensor signal       Tracking         Diagnostics settings       Restart sensor signal         Sensor change       Off         Factory default measurement processing       Factory default sensor         ESC       CAL       DIAG	For special applications the parameter <b>Sensor</b> <b>signal</b> can be adjusted to fit the measuring point. If the display does not show the expected value here are more adjustments and filters available.
Menu/nded setup/Sensor signal       OK         Speed of sound       1482 m/s         > Sedimentation area       >         > Bottom definition	<ul> <li>Before changing the parameter Sound speed contact E+H service.</li> <li>The sensor uses the sound velocity to calculate the correct measurement value.</li> <li>To change the sound velocity is only necessary when:</li> <li>Using under pressure</li> <li>Using in other medium than water</li> </ul>
Menu/nded setup/Sensor signal       OK         Speed of sound       1482 m/s         Sedimentation area       Setimentation         Bottom definition       Setimentation         ESC       CAL       DIAG       ?	You can change the parameter <b>Sedimentation</b> <b>area</b> (automatic gain control). If the display does not show the expected value here are more adjustments and filters available.
Menu/ignal/Sedimentation area       OK         Gain band       20         Gain increment       0.1         ESC       CAL       DIAG       ?	Gain band establishes the maximum amount that Current gain (with Automatic ON) can vary once the initial gain level has been established. At poor sedimentation the initial gain level will rise (e.g. from 40 up to 60). Default: <b>20</b> Selection: 5 to 30. Example: Initial gain level = 50, gain band = 20, possible range = 30 to 70.

Menu/ignal/Sedimentation area       OK         Gain band       20         Gain increment       0.1         ESC       CAL       DIAG       ?	<b>Gain increment</b> determines the change rate of the gain. A low value enables a slow adjustment of the automatic gain control. Default: 0.1 Selection: 0.1 to 5.
Menu/nded setup/Sensor signal OK Speed of sound 1482 m/s ▶ Sedimentation area ▶ Bottom definition	You can change the parameters of the <b>Bottom</b> <b>definition</b> . If the display does not show the expected value here are more adjustments and filters available.
ESC CAL DIAG ? Menu/r signal/Bottom definition OK Range above bottom 0.1 m Bottom signal set point 60	<b>Range above bottom</b> establishes a zone near the bottom of tank that permits special handling of a dominant signal that originates from the tank floor. This signal will be suppressed for the calculation of the measuring value. Default: <b>0.1 m</b> Selection: 0.0 to 1.0 m.
ESC CAL DIAG ? Menu/r signal/Bottom definition OK Range above bottom 0.1 m Bottom signal set point 60	Bottom signal set point limits gain amplification when the primary signal is a reflection from the tank bottom. It prevents over-amplification of the signal in applications with low density material, or when the tank is empty. A higher value represents a higher gain limit. Default: <b>60</b> Selection: 0 to 100.
ESC CAL DIAG ?	

Menu/e sensor/Exte Sensor signal Tracking Diagnostics settings Restart sensor sign Sensor change Factory default mea Factory default sen ESC CAL DIA	nded setup OK s hal Off asurement processing isor	In <b>Tracking</b> you can change the interface parameters (automatic gain control). If the display does not show the expected value here are more adjustments and filters available.
Menu/Extended setu Interface Interface window Above interface Below interface Gate response rate Threshold ESC CAL DIA	up/Tracking OK Top layer On 0.6 m 0.6 m 1 0	<ul> <li>Top layer Measures an interface consisting of light-density material that is at a higher elevation in the tank.</li> <li>Lower layer Measures an interface consisting of denser material that is nearer the bottom of the tank.</li> <li>If the process contains multiple interfaces you can determine the optimal measuring points.</li> <li>Default: Top layer</li> </ul>
Menu/Extended setu Interface Interface window Above interface Below interface Gate response rate Threshold ESC CAL DIA	up/Tracking OK Top layer On 0.6 m 0.6 m 1 20 G ?	Around the interface you can define a <b>window</b> entering a distance above and below the interface. The signal that is inside the window is given preferential consideration. A signal outside the window must persist in order to be considered valid. Default: <b>On</b> Selection: On / Off, 0.0 to 10.0 m.
Menu/Extended setu Interface Interface window Above interface Below interface Gate response rate Threshold ESC CAL DIA	up/Tracking OK Top layer On 0.6 m 0.6 m 1 20	Gate response rate determines the response time with respect to the dynamic movements of the window. Increase Gate response rate to cause the gate to open faster. Default: 1 Selection: 1 to 50

Menu/Extended setup/Tracking       OK         Interface       Top layer         Interface window       On         Above interface       0.6 m         Below interface       0.6 m         Gate response rate       1         Threshold       20         ESC       CAL       DIAG	<b>Treshold</b> is a signal filter for consideration. Increase this parameter to allow calculation of strong signals. Lower this parameter to allow calculation of softer signals. Default: <b>20</b> Selection: 0 to 100.
Menu/e sensor/Extended setup       OK         > Sensor signal       > Tracking         > Diagnostics settings       >         > Restart sensor signal       Sensor change       Off         > Factory default measurement processing       >       Factory default sensor         ESC       CAL       DIAG       ?	<b>Diagnostics settings</b> allows to adjust the diagnostics performance.
Menu/tup/Diagnostics settings OK Alarm delay echo loss 60 min > Diag. behavior ESC CAL DIAG ?	Alarm delay echo loss establishes the amount of time that the sensor must experience a loss of echo before initiating the echo loss action. O turns the function off. Default: <b>60 minutes</b> Selection 0 to 255 minutes The graphic display shows the echo loss without delay.
Menu/e sensor/Extended setup       OK         > Sensor signal       Tracking         > Diagnostics settings       >         > Restart sensor signal       Sensor change       Off         > Factory default measurement processing       >       Factory default sensor         ESC       CAL       DIAG       ?	Restart sensor signal performs a new initialization of the sensor. The sensor starts in automatic mode and seeks the interface. It takes 3 to 5 minutes for the first measuring value.

Menu/e sensor/Extended setup       OK         Sensor signal       Tracking         Diagnostics settings       Destart sensor signal         Sensor change       Off         Factory default measurement processing       Destart sensor         ESC       CAL       DIAG	If <b>Sensor change</b> is set to "on", the measured value at the current output is set to hold. In this way you avoid an error being reported at the process control system if the sensor is replaced on site.
Menu/e sensor/Extended setup       OK         > Sensor signal       Tracking         > Diagnostics settings       >         > Restart sensor signal       Sensor change       Off         > Factory default measurement processing       >       >         > Factory default sensor       ESC       CAL       DIAG       ?	<ul> <li>Factory default measurement processing Reset transmitter parameters to factory default settings.</li> <li>Factory default sensor Reset sensor parameters to factory default settings.</li> </ul>

## 7 Diagnostics and troubleshooting

You must take the entire measuring point into account when troubleshooting:

- Transmitter
- Electrical connections and cables
- Assembly
- Sensor

The possible causes of error indicated in the table below primarily refer to the sensor.

Problem	Check	Remedial measures
Nothing displayed, no reaction from the sensor	Power supplied to the transmitter? Sensor connected correctly? Buildup on sensor membrane?	Connect the mains voltage Connect sensor correctly Clean sensor
Display value too high or too low	Buildup on sensor membrane? Check basin configuration.	Clean Adjust
Display value fluctuates a lot	Check mounting location. Buildup on sensor membrane? Check basin configuration.	Select other mounting location Clean Adjust

Please observe the troubleshooting instructions provided in the transmitter operating manual. Examine the transmitter if necessary.

## 8 Maintenance

You have to perform maintenance tasks at regular intervals.

We recommend setting the maintenance times in advance in an operations journal or log. The maintenance cycle primarily depends on the system, the installation conditions and the medium in which measurement takes place.

#### 8.1 Cleaning the sensor

#### Sensor without wiper

Sensor fouling can affect the measurement results and even cause a malfunction. The sensor must be cleaned at regular intervals to ensure reliable measurement results. The frequency and intensity of the cleaning process depends on the medium.

Clean the sensor:

- As specified in the maintenance schedule
- Before every calibration
- Before returning the sensor for repair

You must rinse the sensor thoroughly with water after cleaning.

#### Sensor with wiper

The time interval is selectable via software. The cleaning time interval depends on the medium. It is recommended to replace the wiper once a year.

## 9 Repair

#### 9.1 Spare parts

The following spare part kits are available for the sensor with wiper:

Description and kit content	Order number
Wiper assembly	71156817
<ul><li>rubber blade</li><li>plastic housing</li></ul>	
Motor assembly	71156830
<ul><li>gear motor</li><li>motor cable</li></ul>	
Coupler assembly	71156832
<ul><li>set screw</li><li>non-metallic coupler</li></ul>	
Shaft assembly	71156833
<ul> <li>bushing</li> <li>o-ring</li> <li>shaft</li> <li>washer/spacer</li> </ul>	

### 9.2 Return

The device must be returned if repairs or a factory calibration are required, or if the wrong device has been ordered or delivered. According to legal regulations, Endress+Hauser, as an ISO-certified company, is required to follow certain procedures when handling returned products that are in contact with medium.

To ensure swift, safe and professional device returns, please read the return procedures and conditions on the internet site:

www.services.endress.com/return-material

### 9.3 Disposal

The device contains electronic components and must therefore be disposed of in accordance with regulations on the disposal of electronic waste. Please observe local regulations.

## 10 Accessories

#### 10.1 Assemblies

Wastewater assembly Flexdip CYA112

- Modular assembly system for sensors in open basins, channels and tanks
- Versions in stainless steel or PVC
- Ordering per product structure (--> Online configurator: www.products.endress.com/ cya112)
- Technical Information TI00432C/07/EN

PVC protector for flexible mounting of CUS71D

- The PVC protector protects the ultrasonic sensor from getting damaged by the surface skimmer.
- Order number: 71178584



Fig. 10: PVC protector for CUS71D

- 1 Assembly CYA112
- 2 PVC-protector 3 Ultrasonic sensor CUS71D

### 10.2 Holder

Holder system Flexdip CYH112 for water

- Modular holder system for sensors and assemblies in open basins, channels and tanks
- The holder system CYH112 works for nearly any type of fixing fixing on the floor, wall or directly on a rail.
- Material: stainless steel
- Ordering acc. to product structure (--> Online configurator: www.products.endress.com/ cyh112)
- Technical Information TI00430C/07/EN

#### 10.3 Transmitter

Liquiline CM442/CM444/CM448

- Multiple-channel transmitter for the connection of digital sensors with Memosens technology
- Power supply: 100 to 230 V AC, 24 V AC/DC
- Universally upgradeable
- SD card slot
- Alarm relay
- IP 66, IP67, NEMA 4X
- Ordering per product structure (--> Online configurator on product page)

### 10.4 Cable extension

CYK11 Memosens data cable

- Extension cable for digital sensors with Memosens protocol
- Ordering as per product structure (--> Online configurator, www.products.endress.com/ cyk11)

Junction box cable/cable

- Material: aluminum, painted
- Cable extension: Memosens sensors, Liquiline
- Order no. 71145499

## 11 Technical Data

## 11.1 Input

Measured variable	Standard sensor	Interface
	Sensor with wiper	Interface
Measuring ranges	Standard sensor	0.3 to 10.0 m (1.0 to 32 ft)
	Sensor with wiper	0.3 to 10.0 m (1.0 to 32 ft)

## 11.2 Performance characteristics

Measured error	Interface	35 mm at 3.0 m
Wavelength	Interface	3 mm at 3.0 m
Measuring interval	Sensor internal	adjustable
	Sensor to transmitter	12 s
Calibration	The sensor is factory calibrated delivered. The "speed of sound" is adjustable and pre-programmed for the application "water".	

## 11.3 Environment

Storage temperature	-20 to 50 °C (-4 to 122 °F)
Degree of protection	IP 68 (test conditions: 1 m (3.3 ft) water column during 60 days, 1 mol/l KCl)

### 11.4 Process

Process temperature range	1 to 50 °C (34 to 122 °F)
Process pressure	0.0 to 6 bar (0 to 87 psi) absolute

### 11.5 Mechanical construction

Dimensions	See "Installation conditions"	
Weight	Standard sensor	1.02 kg (2.25 lb)
	Sensor with wiper	1.25 kg (2.75 lb)
Materials	Sensor	ABS and epoxy plastic
	Wiper	Rubber
Process connections	G1 and NPT ¾"	

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People for Process Automation

### CUS71D parameter list

Customer: \_\_\_\_\_

Date

Location : \_\_\_\_\_

Technician: \_\_\_\_\_

	Cm44x	CUS71D
Serial No		
Order code ext.		
Software version		

#### Menu/Setup/Inputs/UIS

Wiper function	Wiper timing

#### Menu/Setup/Inputs/UIS/Tank Configuration

Blanket	Unit of	Tank	Zero	Blanking	Upper	Lower
definition	measure	depth	adjust	zone	window limit	window limit

#### Menu/Setup/Inputs/UIS/Sensor signal

Acoustic control	Current gain	Gain control set point	Refresh rate	Damping

#### Menu/Setup/Inputs/UIS/Extended setup/Sensor signal

#### Sedimentation area

#### Bottom definition

Sound speed	Gain band	Gain increment	Range above bottom	Bottom signal set point
1482 m/s				

#### Menu/Setup/Inputs/UIS/Extended setup/Tracking

Interface	Interface window	Above interface	Below interface	Gate response rate	Treshold

#### Menu/Setup/Inputs/UIS/Extended setup/Diagnostics settings

Alarm delay echo loss

Remarks:



www.addresses.endress.com

