

LEINE  LINDE



AN INPUT TO ACHIEVE

**FUNCTIONAL SAFETY**





# Safety first

**Leine & Linde – an important part in designing a safe machine for the operators.**

Our encoders are some of the most robust rotary encoders on the market, and combined with high accuracy they can be a part in creating a functional safety system for usage in extreme environments where temperature differences, dirt, shock and vibration are common.





# The functional safety concept

To protect workers and to be able to sell a machine within the European market it is mandatory that the machine complies with the machinery directive, 2006/42/EC, and by that fulfills the part concerning functional safety. Functional safety is about reducing hazardous risks to maintain a safe machine for the operator.

## Performance level and safety integrity level

To show conformance to the machinery directive the machine manufacturer has to comply to a standard from the list of harmonized standards ([www.newapproach.org](http://www.newapproach.org)). Unlike the machinery directive, fulfillment of the standards is not legally mandated. However, if the harmonized standards are fulfilled, it is considered that all safety requirements of the machinery directive are as well.

The harmonized standards for showing compliance to the machinery directive, regarding functional safety, are either EN ISO 13849 or EN IEC 62061. EN ISO 13849 derives from EN 954-1 and is used for safety solutions where the safety is classified according to performance level PL a, b, c, d or e in ascending safety-related effectiveness. For functional safety of safety-related electrical, electronic and programmable electronic control systems, EN IEC 62061 is the choice. Note, in EN IEC 62061 the

functional safety system is composed of subsystems certified according to IEC 61508 which classifies the various safety categories in safety integrity levels (SIL 1, 2, 3 and 4). IEC 61508 also shows a probabilistic view of dangerous failures. Each of the various SIL levels describes a maximum permissible residual risk for a dangerous failure ( $PFH_d$ ) of a machine or machine system.

The standards above are correlating to each other in some aspects; if low-complexity subsystems are designed according to EN IEC 62061 the standard refers to EN ISO 13849. It is similar for the performance level e within EN ISO 13849 which is referring to IEC 61508-3 because it covers safety-related embedded software for components with  $PL_r = e$ .

## Risk assessment and risk reduction

When designing a machine, it is mandatory for the machine builder to estimate how dangerous the machine will be, if a loss of the safety function occurs. This is done according to EN ISO 12100, by analyzing the risks and evaluating how to eliminate or minimize them. By performing the risk analysis a required risk reduction level is established (according to either PL or SIL) and this is the level of safety that the functional safety system has to fulfill in order to be considered as a human safe machine.

Furthermore the system has to be calculated based on the values of its containing components in order to meet the risk reduction level. It is within this calculation the reliability value of the encoder is needed.

## SIL2 or PLd

The Leine & Linde encoders are to be used as input components in a functional safety system. Therefore we can offer either  $MTTF_d$  (EN ISO 13849) or  $PFH_d$  (IEC 61508) values, for calculation of the safety in the system and thereby make sure it meets the requirements of the risk reduction level. For most industrial applications where our encoders are used, SIL2/PLd is enough to meet the safety requirements. However it is possible to achieve different levels of risk reduction depending on the encoder input and the system architecture, from a minimum level of SIL1/PLc to a maximum level SIL3/PLe.

## Abbreviations

$MTTF_d$  = Mean time to dangerous failure [years]

$PFH_d$  = Probability of a dangerous failure per hour [ $h^{-1}$ ]

SIL = Safety integrity level

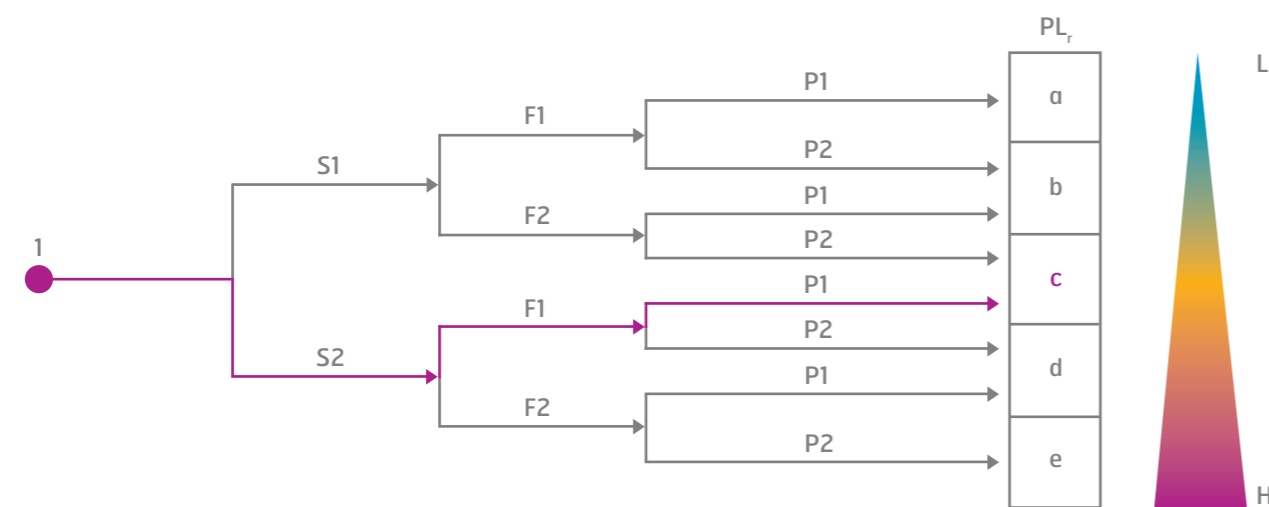
PL = Performance level

# Evaluation of performance level

The evaluation is required to make sure that the designed system has a performance level that is equivalent or higher than the required performance level  $c$  ( $PL_r=c$ ) on this page. This to be sure that the machine will be safe for the operator.

## Risk graph for determining required $PL_r$ according to EN ISO 13849-1

This graph contains the three factors that are used within the risk assessment to determine how high the risk of injury can get if loss of the safety function.



### Key

- 1 Starting point for evaluation of safety function's contribution to risk reduction.
- L Low contribution to risk reduction
- H High contribution to risk reduction
- $PL_r$  Required performance level

### Risk parameters

- S Severity of injury
- S1 Slight (normally reversible injury)
- S2 Serious (normally irreversible injury or death)
- F Frequency and/or exposure to hazard
- F1 Seldom-to-less-often and/or exposure time is short
- F2 Frequency-to-continuous and/or exposure time is long
- P Possibility of avoiding hazard or limiting harm
- P1 Possible under specific conditions
- P2 Scarcely possible

## Tables from EN ISO 13849-1 to establish the performance level

The relationship between  $MTTF_d$ , Diagnostic coverage (DC) and the category of the system results in the performance level of it.

Denotation of each channel	$MTTF_d$
Low	$3 \text{ years} \leq MTTF_d < 10 \text{ years}$
Medium	$10 \text{ years} \leq MTTF_d < 30 \text{ years}$
High	$30 \text{ years} \leq MTTF_d < 100 \text{ years}$

### Key

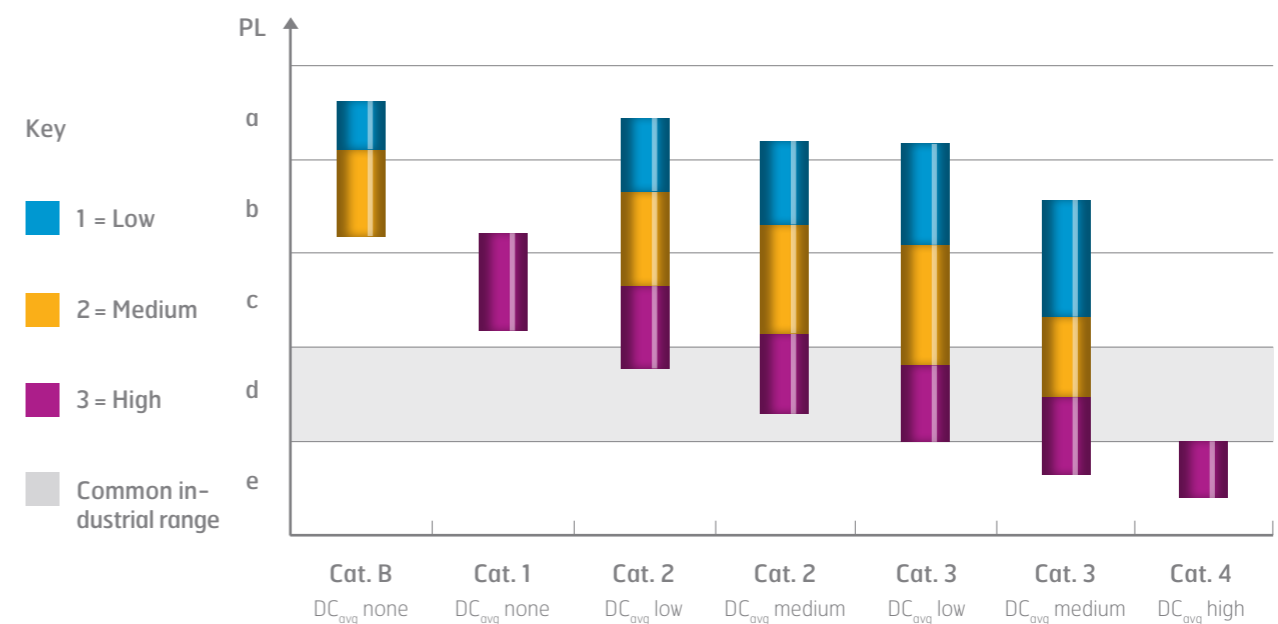
PL performance level

1  $MTTF_d$  of each channel = low

2  $MTTF_d$  of each channel = medium

3  $MTTF_d$  of each channel = high

Denotation	Range
None	$DC < 60\%$
Low	$60\% \leq DC < 90\%$
Medium	$90\% \leq DC < 99\%$
High	$99\% \leq DC$



How to meet the required performance level on page 6 with our encoders, examples are given on pages 8-9. Depending on the design of the functional safety system it is possible to achieve different performance levels.



# System solutions

With Leine & Linde encoders you can design a suitable functional safety system for your application. Depending on the system components as well as the system category, DC and  $MTTF_d$ , different levels of risk reduction can be achieved.

## PLc achieved with system category 1 according to EN ISO 13849-1

For some applications it is enough using a single channel system due to either other combinations of safety equipments or due to the low hazardous risks. This safety system cuts the current supply to the motor to make sure a stop.



1. Encoder 1 Vpp,  $MTTF_d > 100$  years,  $DC^* = 99\%$
2. Logic  $MTTF_d > 100$  years,  $DC = 90\%$
3. Output  $MTTF_d > 100$  years,  $DC = 90\%$

\* The diagnostic coverage (DC) is based on the monitoring of the logic.

$$\frac{1}{\frac{1}{MTTF_{d\_encoder}} + \frac{1}{MTTF_{d\_logic}} + \frac{1}{MTTF_{d\_output}}} = MTTF_{d\_system} \text{ [years]}$$

This results in a  $MTTF_d$  value  $> 100$  years.

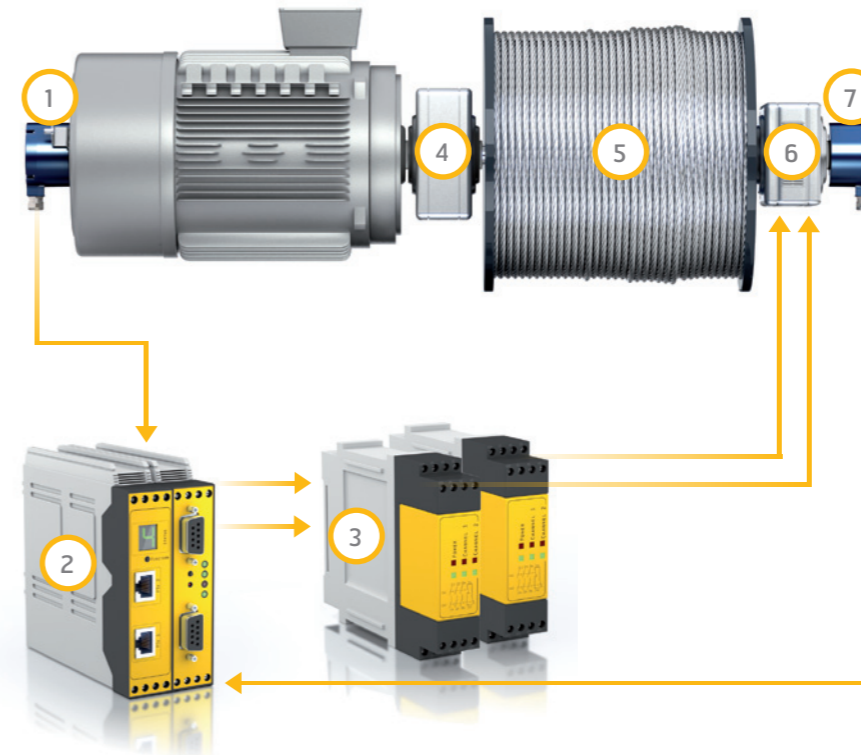
$$\frac{\frac{DC_{encoder}}{MTTF_{d\_encoder}} + \frac{DC_{logic}}{MTTF_{d\_logic}} + \frac{DC_{output}}{MTTF_{d\_output}}}{\frac{1}{MTTF_{d\_encoder}} + \frac{1}{MTTF_{d\_logic}} + \frac{1}{MTTF_{d\_output}}} = DC_{avg\ system} \text{ [%]}$$

This calculation results in a  $DC_{avg} = 90,5\%$ .

With these values the performance level of the system is established as PLc according to the table on page 7.

## PLd achieved with system category 3 according to EN ISO 13849-1

In this example the use of two encoders creates a two channel system for redundancy to ensure functioning of the safety function: to stop the drum if a hazardous situation occurs.



1. Encoder 1 Vpp,  $MTTF_d > 100$  years,  $DC^* = 99\%$
2. Logic  $MTTF_d > 100$  years,  $DC = 90\%$
3. Outputs  $MTTF_d > 100$  years,  $DC = 90\%$
4. Gearbox (Failures of the gearbox has to be considered when designing the system)
5. Drum
6. Brake  $BIO_d = 6 \times 10^6$  (Redundant according to category 3)
7. Encoder 1 Vpp,  $MTTF_d > 100$  years,  $DC^* = 99\%$

\* The diagnostic coverage (DC) is based on the monitoring of the logic.

$$\frac{1}{\frac{1}{MTTF_{d\_encoder\ 1}} + \frac{1}{MTTF_{d\_logic}} + \frac{1}{MTTF_{d\_output}} + \frac{1}{MTTF_{d\_brake}}} = MTTF_{d\_channel\ 1}$$

$$\frac{1}{\frac{1}{MTTF_{d\_encoder\ 2}} + \frac{1}{MTTF_{d\_logic}} + \frac{1}{MTTF_{d\_output}} + \frac{1}{MTTF_{d\_brake}}} = MTTF_{d\_channel\ 2}$$

$$\frac{2}{3} \left( \frac{MTTF_{d\_ch\ 1} + MTTF_{d\_ch\ 2}}{MTTF_{d\_ch\ 1} + MTTF_{d\_ch\ 2}} - \frac{1}{\frac{1}{MTTF_{d\_ch\ 1}} + \frac{1}{MTTF_{d\_ch\ 2}}} \right) = MTTF_{d\_system} \text{ [years]}$$

This results in a  $MTTF_d$  value  $> 100$  years.

$$\frac{\frac{DC_{encoder\ 1}}{MTTF_{d\_encoder\ 1}} + \frac{DC_{encoder\ 2}}{MTTF_{d\_encoder\ 2}} + \frac{DC_{logic}}{MTTF_{d\_logic}} + \left(2x \frac{DC_{output}}{MTTF_{d\_output}}\right) + \left(2x \frac{DC_{brake}}{MTTF_{d\_brake}}\right)}{\frac{1}{MTTF_{d\_encoder\ 1}} + \frac{1}{MTTF_{d\_encoder\ 2}} + \frac{1}{MTTF_{d\_logic}} + \left(2x \frac{1}{MTTF_{d\_output}}\right) + \left(2x \frac{1}{MTTF_{d\_brake}}\right)} = DC_{avg\ system} \text{ [%]}$$

This calculation results in a  $DC_{avg} = 98,2\%$ .

Please note that this is only brief examples and therefore not to be used as guidance. For more detailed information regarding the calculation, please refer to EN ISO 13849-1.

With these values the performance level of the system is established as PLd according to the table on page 7.

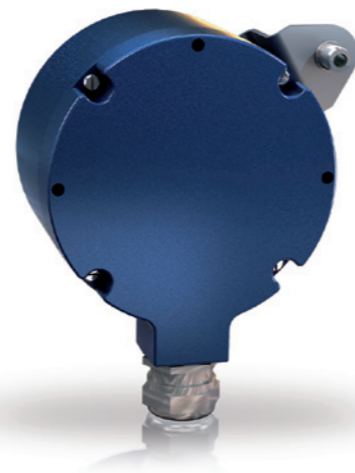
# Encoders for your system

This spread offers an overview of our encoder series available with reliability values. Please contact your nearest Leine & Linde office or visit our website [www.leinelinde.com](http://www.leinelinde.com) for the reliability values for your specific encoder model.

## The 800 series heavy duty encoder

Available with 1 Vpp for use in more demanding safety system where the required risk reduction is high.

Output signal	1 Vpp, TTL, HTL or HCHTL
Encapsulation	IP67 (IP66 at shaft inlet)
Rotation speed max	6000 rpm
Force (radial / axial)	300 N / 100 N
Vibration	≤ 200 m/s <sup>2</sup>
Shock	≤ 1500 m/s <sup>2</sup>
MTTF <sub>d</sub> value	1 Vpp, 5 V: 770 years, terminal connection HCHTL, 9-30 V: 421 years, terminal connection
PFH <sub>d</sub> value	1 Vpp, 5 V: 4,173E-7 h <sup>-1</sup> , terminal connection HCHTL, 9-30 V: 7,425E-7 h <sup>-1</sup> , terminal connection



In the 800 series we can offer a dual encoder solution with redundant scanning sensors.

The 862 encoder is available with a slip free hollow shaft to obtain fault exclusion for the mechanical connection.

Please contact Leine & Linde for more information and datasheets.

## The 600 series industrial encoder

The inductive 600 series absolute encoder with SSI interface has a 1 Vpp output signal for use within functional safety applications.

Output signal	SSI, 1 Vpp, 32 ppr
Encapsulation	IP67
Rotation speed max	12000 rpm
Force (radial / axial)	125 N / 100 N
Vibration	≤ 300 m/s <sup>2</sup>
Shock	≤ 2000 m/s <sup>2</sup>
MTTF <sub>d</sub> value	1 Vpp, 9-30 V: 715 years, M23 connector
PFH <sub>d</sub> value	9-30 V: 3,555E-7 h <sup>-1</sup> , M23 connector



## The 500 series robust encoder

When looking for a Ø58 mm encoder with unrivalled performance. With its HTL output the encoder can be used in environment where the cable distances are long and electronic signals are required.

Output signal	HTL
Encapsulation	IP67 (IP66 at shaft inlet)
Rotation speed max	6000 rpm
Force (radial / axial)	60 N / 50 N
Vibration	≤ 300 m/s <sup>2</sup>
Shock	≤ 2000 m/s <sup>2</sup>
MTTF <sub>d</sub> value	HTL, 6 channel, 9-30 V: 773 years
PFH <sub>d</sub> value	HTL, 6 channel, 9-30 V: 5,853E-7 h <sup>-1</sup>



For more information about our encoder series please visit our website [www.leinelinde.com](http://www.leinelinde.com).

# Electronics

## Square waves

Square waves are the most common signal type for an incremental encoder. Leine & Linde's products are supplied as standard with 6 channels. Signal S00 is followed by signal S90, which is displaced 90 electrical degrees. The two inverted signals S00\ and S90\ enable differential transmission, which reduces the sensitivity of the signals to electrical interference. To check the position of the shaft, a reference pulse is produced once per revolution, Sref with its inverse Sref\.

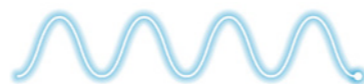


There are several variations of electrical interface with different supply voltages and signal levels. When choosing an interface, it is necessary to take into account factors in the motor's operating environment. The exact properties of the interface is affected by frequency, cable length and temperature.

Interface	TTL	HTL	HCHTL
Supply	5 Vdc	9-30 Vdc	9-30 Vdc
Output signal	5 Vdc	9-30 Vdc	9-30 Vdc
Suitable for	Low frequencies over short cables	High frequencies over medium-length cables	Medium frequencies over long cables
Max cable length	50 m at 50 kHz	100 m at 100 kHz	350 m at 100 kHz
Temperature	-40 .. +100 °C	-40 .. +100 °C	-40 .. +85 °C

## Sine waves

Sine waves are an alternative form of output signal. The analogue signal produces a unique amplitude for each position on the wave, allowing interpolation and very high resolutions. The interface I Vpp is often used in safety-critical applications where detection are required of extremely small movements.



For further information regarding our encoders and functional safety, please contact your nearest distributor or call Leine & Linde at +46-(0)152-265 00. The wide range of encoder variation is always available at [www.leinelinde.com](http://www.leinelinde.com).

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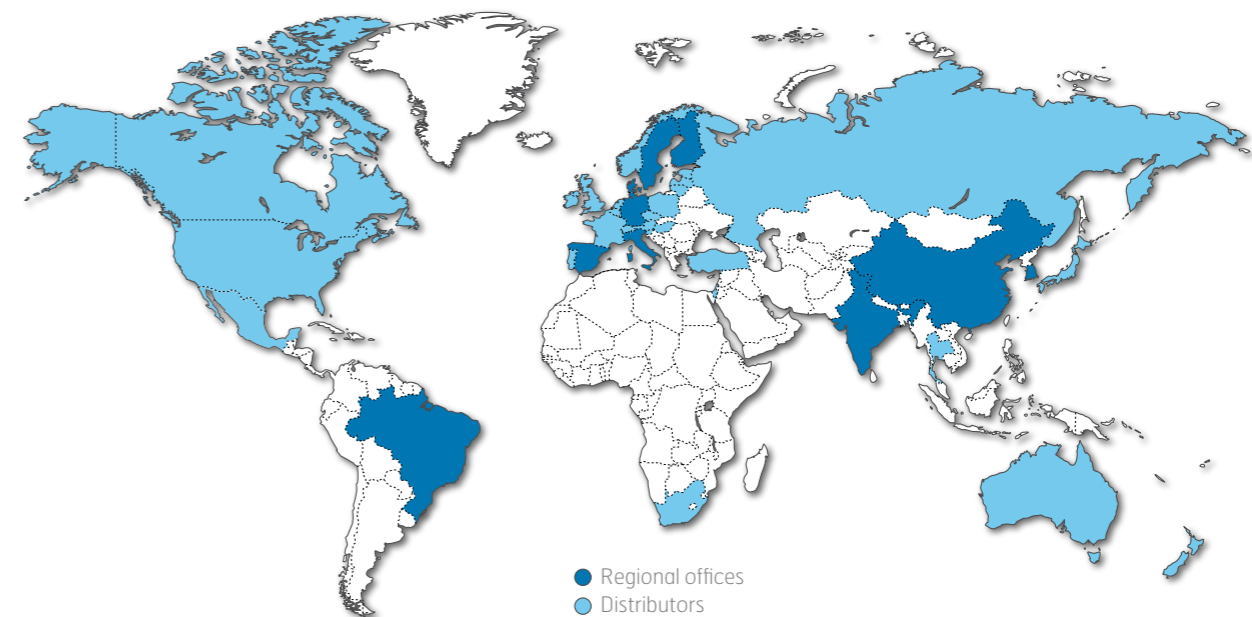
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Leine & Linde's worldwide presence. Read more at [www.leinelinde.com](http://www.leinelinde.com)







Through local presence we support our customers, wherever they are, with a high level of availability and service.

Call us at +46-(0)152-265 00.





The best encoders are those you never have to think about. Those that simply do their job – year after year. Leine & Linde develops and manufactures customised encoder solutions for demanding environments, advanced measuring systems for accurate feedback of speed and position.

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