

# Absolute encoders - parallel

## Solid shaft with clamping or synchro flange

### Optical singleturn encoders 13 bit

#### GA240, GA241 - parallel



GA240 with clamping flange

#### Technical data - electrical ratings

|                             |   |
|-----------------------------|---|
| Voltage supply              | 10...30 VDC   |
| Reverse polarity protection | Yes   |
| Consumption w/o load        | ≤60 mA (24 VDC)   |
| Initializing time typ.      | 20 ms after power on  |
| Interface                   | 13 parallel outputs   |
| Function                    | Singleturn  |
| Steps per turn              | 8192 / 13 bit   |
| Absolute accuracy           | ±0.025 °  |
| Sensing method              | Optical   |
| Code                        | Gray or binary  |
| Code sequence               | CW/CCW coded by connection  |
| Inputs                      | Control signals UP/ <u>DOWN</u> and zero<br><u>STORE</u><br><u>ENABLE</u> |
| Output stages               | Push-pull short-circuit proof   |
| Interference immunity       | DIN EN 61000-6-2  |
| Emitted interference        | DIN EN 61000-6-4  |
| Diagnostic functions        | Self-diagnosis<br>Code continuity check                                   |
| Approval                    | UL approval / E63076  |

#### Features

- Encoder singleturn / parallel
- Optical sensing method
- Resolution: 13 bit
- Clamping or synchro flange
- Short-circuit proof push-pull outputs
- Output release by enable signal
- Permanent check of code continuity

#### Technical data - mechanical design

|                         |  |
|-------------------------|--|
| Size (flange)           | ø58 mm   |
| Protection DIN EN 60529 | IP 54 (without shaft seal),<br>IP 65 (with shaft seal)                                   |
| Operating speed         | ≤10000 rpm (mechanical)<br>≤6000 rpm (electric)  |
| Starting torque         | ≤0.015 Nm (+25 °C, IP 54)<br>≤0.03 Nm (+25 °C, IP 65)                                    |
| Rotor moment of inertia | 14.5 gcm <sup>2</sup>  |
| Admitted shaft load     | ≤20 N axial<br>≤40 N radial  |
| Materials               | Housing: aluminium<br>Flange: aluminium  |
| Operating temperature   | -25...+85 °C<br>-40...+85 °C (optional)  |
| Relative humidity       | 95 % non-condensing  |
| Resistance              | DIN EN 60068-2-6<br>Vibration 10 g, 16-2000 Hz<br>DIN EN 60068-2-27<br>Shock 200 g, 6 ms |
| Weight approx.          | 250 g  |
| Connection              | Connector M27, 21-pin<br>Cable 1 m   |

#### GA240

|            |                    |
|------------|--------------------|
| Shaft type | ø10 mm solid shaft |
| Flange     | Clamping flange    |

#### GA241

|            |                   |
|------------|-------------------|
| Shaft type | ø6 mm solid shaft |
| Flange     | Synchro flange    |

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#### Part number

#### Clamping flange

GA240.     02

#### Connection

- C0 Connector M27, 21-pin, axial
- C1 Connector M27, 21-pin, radial
- 51 Cable 21-core, 1 m, axial
- 61 Cable 21-core, 1 m, radial

#### Voltage supply / signals

- 10 10...30 VDC / gray code push-pull
- 12 10...30 VDC / binary code push-pull

#### Flange / Solid shaft

- 0 Clamping flange / ø10 mm, IP 54
- A Clamping flange / ø10 mm, IP 65

#### Synchro flange

GA241.     02

#### Connection

- C0 Connector M27, 21-pin, axial
- C1 Connector M27, 21-pin, radial
- 51 Cable 21-core, 1 m, axial
- 61 Cable 21-core, 1 m, radial

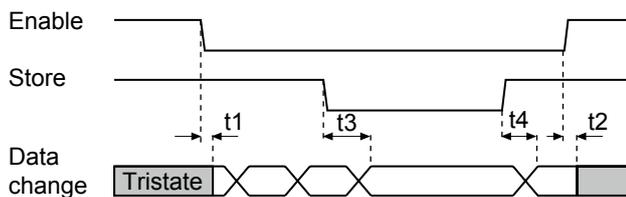
#### Voltage supply / signals

- 10 10...30 VDC / gray code push-pull
- 12 10...30 VDC / binary code push-pull

#### Flange / Solid shaft

- 1 Synchro flange / ø6 mm, IP 54
- B Synchro flange / ø6 mm, IP 65

#### Data transfer



| Signal form | Typ. pul time | Time  |
|-------------|---------------|-------|
| Enable      | t1/t2         | 60 µs |
| Store       | t3/t4         | 60 µs |

#### Accessories

##### Connectors and cables

|           |   |
|-----------|---|
| Z 132.001 | Female connector M27, 21-pin, without cable |
| Z 132.003 | Female connector M27, 21-pin, 2 m cable     |
| Z 132.005 | Female connector M27, 21-pin, 5 m cable     |
| Z 132.007 | Female connector M27, 21-pin, 10 m cable    |

##### Mounting accessories for GA240

|           |   |
|-----------|---|
| Z 119.006 | Eccentric fixing, single  |
| Z 119.013 | Adaptor plate for clamping flange for modification into synchro flange              |
| Z 119.017 | Mounting adaptor for clamping flange (M3)   |
| Z 119.025 | Adaptor plate for clamping flange, mounting by eccentric fixings (order separately) |

##### Mounting accessories for GA241

|           |   |
|-----------|---|
| Z 119.006 | Eccentric fixing, single                        |
| Z 119.015 | Mounting adaptor for synchro flange             |
| Z 119.035 | Bearing flange for encoders with synchro flange |

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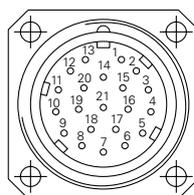
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| Terminal significance         |  |
|-------------------------------|--|
| UB                            | Encoder voltage supply.  |
| GND                           | Encoder ground connection relating to UB.  |
| Outputs D0-D12                | 13 parallel output signals.  |
| $\overline{\text{DATAVALID}}$ | Diagnostic output.<br>An error warning is given at level Low.<br>Important: Interferences must be filtered by the downstream electronics.  |
| Zero setting                  | Input for setting a zero point anywhere within the programmed encoder resolution. The zero setting operation is triggered by a High impulse and has to be in line with the selected direction of rotation ( $\overline{\text{UP/DOWN}}$ ). Connect to GND after setting operation for maximum interference immunity. Impulse duration $\geq 100$ ms. |
| $\overline{\text{UP/DOWN}}$   | $\overline{\text{UP/DOWN}}$ counting direction input.<br>This input is standard on High. $\overline{\text{UP/DOWN}}$ means ascending output data with clockwise shaft rotation when looking at flange. $\overline{\text{UP/DOWN}}$ -Low means ascending values with counterclockwise shaft rotation when looking at flange.                          |
| ENABLE                        | Input for activating the output drivers that are triggered by input level Low. Upon being on High (or less potential) the output drivers switch to high-impedance (Tristate).  |
| STORE                         | Input for output data storage. Upon a Low input level the encoder data are stored in the intermediate memory. Upon being on High (or less potential) the current encoder position data are switched to the output drivers. This line must be applied for reliable data readout in binary code.   |

| Terminal assignment |              |                               |
|---------------------|--------------|-------------------------------|
| Connector           | Core colour  | Assignment                    |
| Pin 1               | violet       | Output D0                     |
| Pin 2               | white/brown  | Output D1                     |
| Pin 3               | white/green  | Output D2                     |
| Pin 4               | white/yellow | Output D3                     |
| Pin 5               | white/grey   | Output D4                     |
| Pin 6               | white/pink   | Output D5                     |
| Pin 7               | white/blue   | Output D6                     |
| Pin 8               | white/red    | Output D7                     |
| Pin 9               | white/black  | Output D8                     |
| Pin 10              | brown/green  | Output D9                     |
| Pin 11              | brown/yellow | Output D10                    |
| Pin 12              | brown/grey   | Output D11                    |
| Pin 13              | brown/pink   | Output D12                    |
| Pin 14              | green/grey   | -                             |
| Pin 15              | blue         | GND                           |
| Pin 16              | blue/yellow  | $\overline{\text{DATAVALID}}$ |
| Pin 17              | brown        | $\overline{\text{UP/DOWN}}$   |
| Pin 18              | pink         | $\overline{\text{STORE}}$     |
| Pin 19              | red          | UB                            |
| Pin 20              | red/yellow   | Zero setting                  |
| Pin 21              | yellow       | $\overline{\text{ENABLE}}$    |



| Trigger level     |                         |
|-------------------|-------------------------|
| Control inputs    | Input circuit           |
| Input level High  | >0.7 UB                 |
| Input level Low   | <0.3 UB                 |
| Input resistance  | 10 k $\Omega$           |
| Parallel outputs  | Output circuit          |
|                   | Push-pull circuit-proof |
| Output level High | >UB -3.5 V (I = -20 mA) |
| Output level Low  | <0.5 V (I = 20 mA)      |
| Load High         | <-30 mA                 |
| Load Low          | <30 mA                  |
| Tristate          | <10 $\mu$ A             |

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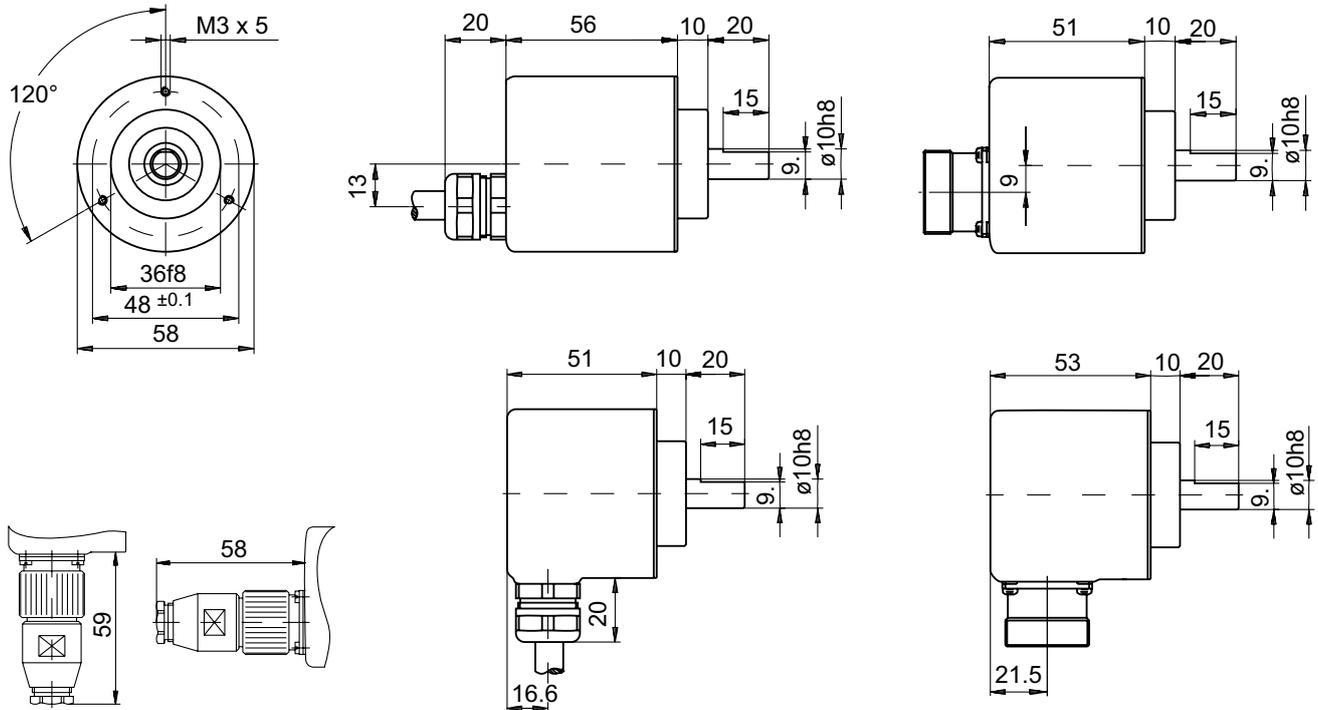
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#### Dimensions

##### GA240 - parallel, clamping flange



##### GA241 - parallel, synchro flange

