# Leuze electronic

the sensor people



BCL 148 Bar Code Reader



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# 1 About this document

# 1.1 Used symbols and signal words

# Tab. 1.1: Warning symbols and signal words

	Symbol indicating dangers to persons
	Symbol indicating dangers from harmful laser radiation
	Symbol indicating possible property damage
NOTE	Signal word for property damage
	Indicates dangers that may result in property damage if the measures for dan- ger avoidance are not followed.
CAUTION	Signal word for minor injuries
	Indicates dangers that may result in minor injury if the measures for danger avoidance are not followed.
WARNING	Signal word for serious injury
	Indicates dangers that may result in severe or fatal injury if the measures for danger avoidance are not followed.

# Tab. 1.2: Other symbols

1	Symbol for tips Text passages with this symbol provide you with further information.
Ŕ	Symbols for action steps Text passages with this symbol instruct you to perform actions.
⇒	Symbol for action results Text passages with this symbol describe the result of the preceding action.

# Tab. 1.3: Terms and abbreviations

BCL	Bar code reader
DNC	This PIN must not be connected
(Do Not Connect)	
DTM	Software device manager
(Device Type Manager)	
EMC	Electromagnetic compatibility
EN	European standard
FDT	Software frame for management of device managers (DTM)
(Field Device Tool)	
FE	Functional earth
GUI	Graphical user interface

HID	Device class for input devices with which users directly interact
(Human Interface De- vice)	
NC	This pin is not contacted at the device
(Not Connected)	
SWI1	Switching input
PLC	Programmable Logic Control
	(corresponds to Programmable Logic Controller (PLC))

# 2 Safety

This bar code reader was developed, manufactured and tested in accordance with the applicable safety standards. It corresponds to the state of the art.

# 2.1 Intended use

The BCL 148 bar code reader is designed as a stationary compact scanner with integrated decoder for all common bar codes used for automatic object detection.

# Areas of application

The bar code reader of type BCL 148 is intended especially for the following areas of application:

- automatic analyzers
- automation technology

	CAUTION
	Observe intended use!
	The protection of personnel and the device cannot be guaranteed if the device is operated in a manner not complying with its intended use.
	$\clubsuit$ This device is not a safety sensor and is not intended as personnel protection.
	$\clubsuit$ The device may only be put into operation by competent persons.
	♦ Only operate the device in accordance with its intended use.
	Leuze electronic GmbH + Co. KG is not liable for damages caused by improper use.
	Read these original operating instructions before commissioning the device. Knowledge of the original operating instructions is an element of proper use.
	NOTICE
	Comply with conditions and regulations!

# Observe the locally applicable legal regulations and the rules of the employer's liability insurance association.

# 2.2 Foreseeable misuse

Any use other than that defined under "Intended use" or which goes beyond that use is considered improper use.

In particular, use of the device is not permitted in the following cases:

- · in rooms with explosive atmospheres
- · in circuits which are relevant to safety
- for medical purposes

NOTICE

# Do not modify or otherwise interfere with the device!

- bo not carry out modifications or otherwise interfere with the device. The device must not be tampered with and must not be changed in any way.
- ✤ The device must not be opened. There are no user-serviceable parts inside.
- ✤ Repairs must only be performed by Leuze electronic GmbH + Co. KG.

# **NOTICE**To increase the decoding reliability, it is recommended that

be en

To increase the decoding reliability, it is recommended that only the actually needed code types be enabled.

# 2.3 Competent persons

Connection, mounting, commissioning and adjustment of the device must only be carried out by competent persons.

Prerequisites for competent persons:

- They have a suitable technical education.
- They are familiar with the rules and regulations for occupational safety and safety at work.
- They are familiar with the original operating instructions of the device.
- They have been instructed by the responsible person on the mounting and operation of the device.

# **Certified electricians**

Electrical work must be carried out by a certified electrician.

Due to their technical training, knowledge and experience as well as their familiarity with relevant standards and regulations, certified electricians are able to perform work on electrical systems and independently detect possible dangers.

In Germany, certified electricians must fulfill the requirements of accident-prevention regulations BGV A3 (e.g. electrician foreman). In other countries, there are respective regulations that must be observed.

# 2.4 Disclaimer

Leuze electronic GmbH + Co. KG is not liable in the following cases:

- The device is not being used properly.
- Reasonably foreseeable misuse is not taken into account.
- Mounting and electrical connection are not properly performed.
- Changes (e.g., constructional) are made to the device.

# 2.5 Laser safety notices

LASER RADIATION – LASER CLASS 2 Never look directly into the beam!
The device satisfies the requirements of IEC 60825-1:2007 (EN 60825-1:2007) safety regula- tions for a product of <b>laser class 2</b> as well as the U.S. 21 CFR 1040.10 regulations with devia- tions corresponding to "Laser Notice No. 50" from June 24, 2007.
Conforms to the applicable requirements of 21 CFR Subchapter J
Never look directly into the laser beam or in the direction of reflected laser beams! If you look into the beam path over a longer time period, there is a risk of injury to the retina.
rightarrow Do not point the laser beam of the device at persons!
Interrupt the laser beam using a non-transparent, non-reflective object if the laser beam is accidentally directed towards a person.
When mounting and aligning the device, avoid reflections of the laser beam off reflective surfaces!
Scaution! The use of operating or adjusting devices other than those specified here or carrying out of differing procedures may lead to dangerous exposure to radiation.
Adhere to the applicable legal and local regulations regarding protection from laser beams in its latest version.
The device must not be tampered with and must not be changed in any way. There are no user-serviceable parts inside the device. Repairs must only be performed by Leuze electronic GmbH + Co. KG.
If the scanner motor fails during the emission of laser radiation, the limit value of laser class 2 in accordance with IEC 60825-1 Edition 2.0 (2007) could be exceeded. The device has safeguards to prevent this occurrence.
✤ If the emitted laser beam is at a standstill, immediately disconnect the faulty device from the voltage supply.
The device emits scanned optical radiation at a wavelength of 650 nm (red). Looking at the device's mirror and operating at the lowest scanning rate (500 scans/s) at a viewing distance of 100 mm results in pulses with a pulse duration of 110 µs on the retina of the eye. The total pulse peak power at the exit window is less than 1.3 mW. The average laser power is, thus, less than 1 mW, corresponding to laser class 2 in accordance with EN 60825-1, Edition 2.0 (2007) and IEC 60825-1, Edition 2.0 (2007).

# NOTICE



# Laser aperture!

The glass optics cover is the only aperture through which laser radiation may be observed on this product.

# Affix laser information and warning signs! Laser information and warning signs attached to the device. Also included with the device are self-adhesive laser warning and laser information signs (stick-on labels) in multiple languages. When using the device in the U.S.A., use the stick-on label with the "Complies with 21 CFR 1040.10" notice. When using the device in the US, use the stick-on label with the "Complies with 21 CFR 1040.10" note. Affix the laser information and warning signs near the device if no signs are attached to the device (e.g., because the device is too small) or if the attached laser information and warning signs are concealed due to the installation position. Affix the laser information and warning signs so that they are legible without exposing the reader to the laser radiation of the device or other optical radiation.



- 2 Laser aperture
- 3 Laser information sign with laser parameters





Fig. 2.2: Laser warning and notice signs – supplied stick-on labels

# 3 Device description

# 3.1 Device overview

# 3.1.1 The BCL 148 bar code reader

The bar code reader is a laser-based line scanner with integrated decoder and focus adjustment for all commonly used bar codes, e.g. 2/5 Interleaved, Code 39, Code 128, EAN etc.

- The many possible configurations of the device allow it to be adapted to a multitude of reading tasks.
- The focus adjustment enables reading of 1 15 rows of racks.
- Thanks to the high scanning rate of 750 scans per second, the bar code reader is ideally suited for instruments with manual insertion.
- Information on technical data and characteristics: see chapter 12 "Technical data".

# 3.1.2 Stand-alone operation

The bar code reader is operated as a "stand-alone" single device. The electrical connection of the operating voltage and of the RS 232/RS 485 interfaces is established via a 0.9 m long cable that is equipped with a 15-pin SUB-D connector plug.

# 3.2 **Performance characteristics**

- · Compact scanner with lateral beam exit and integrated decoder
- · High-resolution optics
- Focus adjustment
- Resolution 127 µm

Reading of all common codes of module sizes 127 ... 300  $\mu$ m (5 ... 12 mil) at a reading field height of  $\geq$  60 mm, even with a reading distance of 30 mm

- Reading distance 30 ... 310 mm
- Scanning rate of 750 scans/s facilitates reliable reading, even while in motion
- · Compact design for simple integration, even in constrained spaces
- Robust diecast zinc housing with 0.9 m cable and 15-pin SUB-D connection
- Process interface: RS 232 or RS 485
- Service interface: RS 232

# 3.3 Device construction



- 1 Reading window with lateral beam exit
- 2 M4 mounting thread, two on each of the opposing sides, 4 mm deep
- 3 Connection cable with 15-pin SUB-D connector plug

Fig. 3.1: Device construction of the BCL 148

# 3.4 Connection technology

Connection cable with 15-pin SUB-D connector plug:

- 1 switching input
- 1 pin for addressing
- Process interface: RS 232 or RS 485
- Service interface: RS 232

# 4 Mounting

- ♦ Observe the mounting instructions (see chapter 4.1 "Selecting a mounting location").
- ✤ Fasten the bar code reader on the M4 mounting threads on one side of the device (see chapter 3.3 "Device construction").

# 4.1 Selecting a mounting location

The size of the bar code module influences the maximum reading distance and the w reading field.	dth of the
When selecting a mounting location and/or the bar code label, take into account the reading characteristics of the bar code reader with various bar code modules.	ne different
NOTICE	
NOTICE	
Observe when choosing the mounting location!	
🤟 🤟 🏷 Maintain the permissible environmental conditions (humidity, temperature).	
Avoid possible soiling of the reading window due to liquids, abrasion by boxes, or material residues.	packaging
Ensure that there is the lowest possible chance of damage to the bar code reader chanical collision or jammed parts.	by me-
Avoid possible ambient light influence (no direct sunlight).	

In order to select the right mounting location, several factors must be considered:

- size, orientation, and position tolerance of the bar codes on the objects to be scanned.
- The reading field of the bar code reader in relation to the bar code module width.
- The resulting minimum and maximum reading distance from the respective reading field with the respective module width (see chapter 12.2 "Reading fields").
- alignment of the bar code reader for avoiding reflections.
- distance between bar code reader and host system with respect to the interface.

The best read results are obtained if the following prerequisites are fulfilled:

- · The reading distance lies in the middle area of the reading field.
- · There is no direct sunlight and ambient light influences are avoided
- The bar code labels are of good print quality and have good contrast ratios.
- You are not using glossy labels.
- The bar code is moved past the reading window with a rotational angle of 10° to 15°.



# 5 Electrical connection

# Safety notices

CAUTION

- ✤ The bar code reader is completely sealed and must not be opened.
- b Do not try to open the device under any circumstances, as this voids both protection class IP 65 and the warranty.
- Before connecting the device, be sure that the supply voltage agrees with the value printed on the name plate.
- Sumple connection of the device and maintenance work while under voltage must only be carried out by a qualified electrician.
- The power supply unit for the generation of the supply voltage for the bar code reader and the corresponding connection units must have a secure electrical insulation according to IEC 60742 (PELV).
- If faults cannot be rectified, take the device out of operation and protect it from accidentally being started.

# NOTICE



# **UL applications!**

For UL applications, use is only permitted in Class 2 circuits in accordance with the NEC (National Electric Code).

# NOTICE

# Laying cables!

- Lay all connection cables and signal lines within the electrical installation space or permanently in cable ducts.
- Lay the cables and lines so that they are protected against external damages.
- ✤ For further information: see EN ISO 13849-2, Table D.4.

The electrical connection is established via the connection cable with 15-pin SUB-D connector plug (see chapter 5.3 "Pin assignment").

The bar code reader is equipped with the following ports and interfaces:

- 1 switching input
- 1 pin for addressing
- Process interface: RS 232 or RS 485
- Service interface: RS 232

You can configure the functions of the switching input and the addressing according to your requirements via the *Sensor Studio* configuration software (see chapter 6 "Configuration and diagnostics software - Sensor Studio").

# 5.1 Operating voltage

The bar code reader is designed for an operating voltage of 18 ... 30 V. The operating voltage is fed in via pin 8 and pin 15 of the 15-pin SUB-D connector plug (see chapter 5.3 "Pin assignment").

# 5.2 Housing ground

To avoid electromagnetic interference, a low-impedance connection is necessary from the housing to the machine ground.

# 5.3 Pin assignment



Fig. 5.1: Pin assignment

NOTICE

The functional earth (FE) is connected to the metal flange of the SUB-D connector plug.

L			
Pin	Signal	Description	
1	GND	0 V DC	for IN/OUT
		Reference ground bridged with pin 15	
2	SWI1	Switching input	IN
3	RS485A	A signal line of the RS 485 interface	IN/OUT
4	RS485B	B signal line of the RS 485 interface	IN/OUT
5	/MA0	Address for selecting the device in Host mode	IN
6	DNC	Do not connect - for internal use only	
7	DNC	Do not connect - for internal use only	
8	VIN	Operating voltage +18 30 V DC	IN
9	/PROT	Protocol changeover	IN
10	DNC	Do not connect - for internal use only	
11	RXD232	RxD signal line of the RS 232 interface	IN
12	TXD232	TxD signal line of the RS 232 interface	OUT
13	NC	Not connected	
14	NC	Not connected	
15	GNDIN	0 V DC	IN
		Reference ground	

# 5.4 Switching input/addressing/protocol changeover

The bar code reader is equipped with a switching input (**SWI1**), a pin for addressing (**/MA0**) (see chapter 5.3 "Pin assignment") and a pin for protocol changeover (**/PROT**) (see chapter 5.4.3 "Protocol changeover").

- The switching input can be used to trigger the reading.
- You can make the address setting via the pin for addressing if two bar code readers are operated on one interface.
  - /MA0 not active: device address=0
  - /MA0 active: device address=1

If pin **/MA0** is inactive on device startup, the device uses the device address from the parameter set (default device address=0).

· You can make a hardware-controlled switch to Service mode via the pin for protocol changeover.

You can configure the functions of the switching input according to your requirements via the *Sensor Studio* configuration software (see chapter 6 "Configuration and diagnostics software - Sensor Studio").

# 5.4.1 Switching input

Via switching input connection SWI1, you can trigger a read process in the standard setting (high = active).



- 1 Operating voltage UB 18 ... 30 V DC
- 2 SWI1
- 3 GND

Input resistance: approx. 6 kΩ

Fig. 5.2: Switching input (standard setting)

# 5.4.2 Addressing

The cable for addressing (pin /**MA0**) is only used during device startup. If multiple devices are operated on an RS 485 interface, the device address of the bar code reader is defined via pin /**MA0**. Bit flags 0 and 1 are set for the device address.

• /MA0 not active: device address=0

(Level on **/MA0** = high or not assigned)

- /MA0 active: device address=1
  - (Level on /**MA0** = low or GND)

If pin **/MA0** is inactive on device startup, the device uses the device address from the parameter set (de-fault device address=0).



3 GND



### 5.4.3 **Protocol changeover**

Via the input for protocol changeover (/PROT), it is alternatively possible to make a hardware-controlled switch to the Service mode protocol.

/PROT inactive: Host mode protocol

(Level on /PROT= high or not assigned)

 /PROT active: Service mode protocol (Level on /PROT= low or GND)



3 GND

Fig. 5.4: Circuit diagram example: protocol changeover

### 5.5 PC or terminal connection

Via the RS 232 service interface, you can configure the bar code reader by means of a PC or a terminal program. For this, you need an RS 232 connection that establishes the RxD, TxD and GND connections between PC and bar code reader (see chapter 5.3 "Pin assignment").

# 6 Configuration and diagnostics software - Sensor Studio

The *Sensor Studio* configuration software provides a graphical user interface for the operation, configuration and diagnosis of the device via the RS 232 service interface.

A device that is not connected to the PC can be configured offline.

Configurations can be saved and reopened as projects for transferring back to the device at a later time.

# NOTICE



The Sensor Studio configuration software is designed according to the FDT/DTM concept:

- You make the individual configuration settings for the bar code reader in the Device Type Manager (DTM).
- The individual DTM configurations of a project can be called up via the frame application of the Field Device Tool (FDT).
- Communication DTM for bar code readers: LeCommInterface
- · Device DTM for the BCL 148 bar code reader

Procedure for the installation of the software and hardware:

- ✤ Install the Sensor Studio configuration software on the PC.
- Install the communication and device DTM. Communication and device DTM are included in the Le-AnalysisCollectionSetup installation package.
- ♦ Create device DTM for BCL 148 in the project tree of the Sensor Studio FDT frame.
- ♦ Connect bar code reader to PC (see chapter 5.5 "PC or terminal connection").
- ♦ Activate service interface on bar code reader (see chapter 7.3.1 "Service mode").

# 6.1 System requirements

To use the Sensor Studio configuration software, you need a PC or laptop with the following specifications:

Operating system	Windows XP or higher (32 bit, 64 bit)
	Windows Vista
	Windows 7
	Windows 8
Computer	Processor type: 1 GHz or higher
	Serial COM interface
	CD-ROM drive
	Main memory (RAM): at least 64 MB
	Keyboard and mouse or touchpad
Graphics card	At least 1024 x 768 pixels
Required hard disk capacity for Sensor Studio and communication DTM	35 MB

Tab. 6.1: System requirements for Sensor Studio installation



Administrator privileges on the PC are necessary for installing Sensor Studio.

# 6.2 Installing Sensor Studio configuration software

# NOTICE

The installation files of the *Sensor Studio* configuration software must be downloaded from the Internet at **www.leuze.com**. For subsequent updates, you can find the most recent version of the *Sensor Studio* installation software on the Internet at **www.leuze.com**.

# 6.2.1 Downloading configuration software

- S Call up the Leuze home page: www.leuze.com
- ♥ Enter the type designation or part number of the device as the search term.
- ⇔ The configuration software can be found on the product page for the device under the *Downloads* tab.

# 6.2.2 Installing the Sensor Studio FDT frame

# NOTICE

# First install the software!

- Do not yet connect the device to the PC.
- ♥ First install the software.

	NOTICE
1	If FDT frame software is already installed on your PC, you do not need the <i>Sensor Studio</i> instal- lation. You can install the communication DTM and the device DTM in the existing FDT frame. Com- munication DTM and device DTM are included in the <i>LeAnalysisCollectionSetup</i> installation package.

- Start the PC.
- Download the configuration software from the Internet to the PC (see chapter 6.2.1 "Downloading configuration software"). Unpack the installation package.
- ♦ Start the SensorStudioSetup.exe file.
- Follow the instructions on the screen.

# 6.2.3 Install the communication DTM and device DTM

# Prerequisites:

- ✓ An FDT frame is installed on the PC.
- Start the *LeAnalysisCollection.exe* file from the installation package and follow the instructions on the screen.

# 6.2.4 Connecting device to PC

The device is connected to the PC via the RS 232 interface.

You need an RS 232 connection that establishes the RxD, TxD and GND connections between PC and device (see chapter 5.5 "PC or terminal connection").

# 6.3 Starting the Sensor Studio configuration software

Prerequisites:

- ✓ The device has been mounted (see chapter 4 "Mounting") and connected (see chapter 5 "Electrical connection") correctly.
- ✓ The device is connected to the PC via the RS 232 interface (see chapter 6.2.4 "Connecting device to PC").
- ✓ The Sensor Studio configuration software is installed on the PC (see chapter 6.2 "Installing Sensor Studio configuration software").
- 以 Start the Sensor Studio configuration software by double-clicking the [Sensor Studio] icon.
- ⇒ The **mode selection** of the Project Wizard is displayed.
- Select the Device selection without communication connection (offline) configuration mode and click on [Next].
- ⇒ The Project Wizard displays the device selection list of the configurable devices.

Sensor 1	Studio			_ = X
2	Sensor Studio			△ Leuze electronic
	Device selection			the service people
Select a c	evice from the list.	Device	Vening	Handadara
-		CR100	1.0.1.0	Leuze electronic
	67	DCR 80	1.0.1.0	Leuze electronic
	<b>1</b> .	BCL148	1.0.1.0	Leuze electronic
		CR50	1.0.1.0	Leuze electronic
		CR55	1.0.1.0	Leuze electronic
				< Back Next > Cancel
-				

Fig. 6.1: Device selection for the BCL 148

- ♦ Select BCL 148 in the device selection and click on [Next].
- ⇒ The device manager (DTM) of the connected BCL 148 starts with the offline view for the Sensor Studio configuration project.
- ♦ Establish the online connection to the connected BCL 148.
  - ⇒ In the Sensor Studio FDT frame, click on the [Establish connection with device] button.
  - ⇒ In the Sensor Studio FDT frame, click on the [Upload parameters to device] button.
- ⇒ The current configuration data is displayed in the device manager (DTM).



Fig. 6.2: Configuration project: device manager for BCL 148

- The menus of the Sensor Studio device manager (DTM) can be used to change or read out the configuration of the connected device.
  - ⇒ The user interface of the Sensor Studio device manager (DTM) is largely self-explanatory.
  - ⇒ The online help system provides information on the menu items and adjustment parameters. Select the Help menu item in the menu [?].
- ✤ Transfer the modified configuration parameters to the device.
  - ⇒ If a connection exists, click on the [Download parameters to device] button on the task bar.

# 6.4 Exiting Sensor Studio

After completing the configuration settings, close the Sensor Studio configuration software.

- ♦ Exit the program via File > Exit.
- ♦ Save the configuration settings as a configuration project on the PC.

# 6.5 Configuration parameters

In this chapter, you will find information and explanations on the configuration parameters of the device manager (DTM) for the BCL 148 bar code reader.

# NOTICE

This chapter does not include a complete description of the *Sensor Studio* configuration software. Complete information on the FDT frame menu and on the functions in the device manager (DTM) can be found in the online help system.

The device manager (DTM) for BCL 148 bar code readers of the *Sensor Studio* configuration software offers the following configuration functions:

- Decode (see chapter 6.5.1 "Decode tab")
- Output (see chapter 6.5.2 "Output tab")
- Control (see chapter 6.5.3 "Control tab")
- Host Interface (see chapter 6.5.4 "Host interface tab")
- Switching input (sensor) (see chapter 6.5.5 "Sensor tab")
- System/scanner character (system properties) (see chapter 6.5.6 "System/scanner character tab")

# NOTICE

The online help system displays information on the menu items and configuration parameters for each function. Select the **Help** menu item in the menu [?]

The Sensor Studio configuration software offers the following buttons in the CONFIGURATION menu:

- Export Parameter Command File ...] Saves the currently set parameter data as text file in a selectable directory.
- Solution [Reset all parameters in the GUI to their factory default settings] Resets all parameters in the graphical user interface to the factory settings.

# 6.5.1 Decode tab

				IDENTIFICATION CONFI		the sensor peop
Decode	DECODE					△ Leuze electronic
Output	CODE TAB	LE				the sensor peop
Control Host Interface	Code 1	Code type Code 2/5 Interleaved	Interval mode	Element number	Decode	
Sensor System	Code 2	None		0 💠 , 0 💠 , 0 💠	Code table	
	Code 3	None		0 0 0 0 0	Specifies the code code types which a	which are to be decoded. We recommend enabling only the are actually to be read with the corresponding element numbers.
	Code 4	None	•	0 🔹 , 0 🔹 , 0 🔹	Codes which are no Element number	it enabled are not decoded!
	Code 5	None		0 0 0 0 0	Up to 3 element nu	mbers may be specified for each code.
:	Code 6	None			If Interval mode is is shown by a dash	enabled the first two element numbers represent a range. This
	Code 7	None		0,0,0,0	Number of barcod	••
	Code 8	None		0 ‡, 0 ‡, 0 ‡	Here, the number o is set.	f barcodes to be decoded within a read cycle (one reading gat
	COMPLET	ENESS		- Marci,	Reading security (	equal scans)
	Number of	f bar codes	1		Specifies how ofter	a code must be decoded before the result is valid and output.
	Reading s	ecurity (equal scans)	2	•	security.	by be increased for test purposes or for codes with low

Fig. 6.3: Decode tab

Code table	Here, the codes which are to be decoded are set.
(CODE TABLE)	We recommend enabling only the code types which are to actually be read with the corre- sponding element numbers.
	Codes which are not enabled are not decoded!
Number of digits (Element number)	In the field Element number, up to 3 element entries may be entered.
	A range of permissible elements is indicated by a dash:
	e.g., 4-40 elements.
	To select a range, set the check mark beneath In- terval mode. Up to 3 fixed element numbers with comma: e.g.: 8,13 digits
	Both are also possible, but the range must be specified first (select Interval mode):
	e.g.: 4-10,20 elements

Number of bar codes	Here, the number of the bar codes to be decoded
Reading security (equal scans)	within a read cycle (one reading gate) is set.
(COMPLETENESS)	Under reading reliability (Equal Scans), it is possible
(	to select how often a code must be decoded before
	the result is valid and output.

# 6.5.2 Output tab

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File Edit View Device Tools Window ?	
E CL145 - Main operation	X ···
BCL148 Code Render	4 Leuze electronic
Analysis Automation	the sensor people
IDENTIFICATION CONFIGURATION DIAGNOSIS	
	<b>0</b> -
CONFIGURATION OUTPUT	▲ Leuze electronic <sup>▲</sup>
Control OUTPUT FORMAT	the sensor people
Control Output header	
	Output
Sensor	The parameters of the output formater enable to configure the format of the result
Label Header	string the scanner will sent after decoding.
	Output header
	The output header is sent in a separate message before the read results.
Label foster	Label header
	The label header is sent directly before the code data.
	Label footer
Message mode Each label in a different message   Properties	The label footer is appended directly to the code data.
No reed string	Message mode
MESSAGE FORMAT	Selects whether the barcodes read are sent in concatenation or separately as individual strings
	No read string
	This string is set for each unrecognized barcode. A string of up to 20 characters is
	possible.
	Properties
	The Properties button navigates to a screen where advanced output properties can be set.
	*
4 Disconnected & Administrator	1.27123

# Fig. 6.4: Output tab

Output header	Select from the options listed below. The output header is sent in a separate message before the read result.
Label header	The label header is set directly before the code data.
Label footer	The label footer is appended directly to the code data.
Message mode (Message mode)	Selects whether the bar codes read are sent in con- catenation or separately as individual strings.

# NOTICE

•

The structure of this message string is depicted symbolically in the preview window.

Text in the case of misreading (No read string)	This character is set for each unrecognized bar code. Multiple characters (=string) may be entered here. Up to 20 characters are possible.
Properties	Set the desired formatting modes and formatting
(Output Properties)	characters as necessary.

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BCL148 - Main operation			• ×
BCL148			4 Leuze electronic
Code Reader	lion		the sensor people
rulay sa rulas indi		IDENTIFICATION CONFIGURATION DIAGNOSIS	
			0.
CONFIGURATION	DECODE - COMMON PROPERTIES		A Leuze electronic
Decode	FORMATTER MODES		the serior people
Properties	Message mode	Each label in a different message	
Control	Separator output mode	None output	Output - Properties
Framing Protocol	Address align mode	No alignment	Advanced output properties like special formatting modes and formatting characters
System	Output length mode	No length formating	raine ar inte ar resear.
	FORMAT CHARACTER		Foramtter Modes
	Output header 1	Label header 1	Message mode
	Separator 17	Good read character     NULL	Selects whether the barcodes read are sent in concatenation or separately as individual strings.
			Separator output mode
			Defines the output mode of a separator character.
			Address align mode
			Enables to align the label output to a word address. The information will be prefixed by separator characters.
			Output length mode
			This parameter enables to format the output length of a label. If a formatting mode is selected the information of shorter labels will be expanded by separator characters. Longer labels will be truncated.
			Format Character
			Output / Label header
			These characters can be used in the output formatter to specify the message format.
적DDisconnected (2)	Administrator		
			Out in the second se

Fig. 6.5: Standard settings for the Properties window – Output tab

# 6.5.3 Control tab

🚄 Sensor Studio - New Project	<ul> <li><ul> <li><ul> <li><ul></ul></li></ul></li></ul></li></ul>	
File Edit View Device 1	ools Window ?	
	0. DHIRSOPPICCNIERSIND,	
BCL148 - Main operation BCL148 Code Reader Analysis Automati	an	▲ Leuze electronic the sensor people
	IDENTIFICATION CONFIGURATION DIAGNOSIS	
9		0.
CONFIGURATION	CONTROL ACTIVATION Decode delay time DEACTIVATION Command character Time Scores without into Scores without into	
석p Disconnected t	Administrator	Scans without Info Following a successful read, the scanser waits for this number of scans (sequential scans with no read read?) before it automatically dearbivates itself.

Fig. 6.6: Control tab

# Activation

Switching input 1	See menu switching input
Function	
Sensor function (Sensor Function)	The function of the switching input as trigger input is activated or deactivated.
Command character (Command character)	The standard online character for the trigger start is the '+' character. The character cannot be changed.

Delay until scanner reads	Time delay after the trigger signal by the switching
(Decode delay time)	input until the actual code reading is triggered.

# Deactivation

Switching input 1	See menu switching input
Function	
Command character	The standard online character for the trigger end is
(Command character)	the '-' character.
	The character cannot be changed.
Time	If the code reader is activated, the reading gate is
(Time)	automatically closed by the code reader after this preset time has elapsed (e.g. for test purposes).
Scans without info	Following a successful read, the code reader waits
(Scans without info)	for this number of scans (sequential scans with no read result) before it automatically deactivates itself.

# 6.5.4 Host interface tab

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File Edit View Device	Tools Window ?				
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BCL148 - Main operation					• ×
A Code Reader					4 Leuze electronic
Analysis Automat	ion				the sensor people
			IDENTIFICATION CONFIGURATION	DIAGNOSIS	
• • • • •					0 -
CONFIGURATION	HOST INTERFACE				▲ Leuze electronic <sup>▲</sup>
Decode Output	RS232 SETTINGS				the sensor people
Control	Baud rate	9 600 💌 Baud			Host Interface
Host Interface	Data mode	8 data bits, none parity, 1 start/stop	•		The host interface parameters enable to specify the settings of the serial COM
System	Handshake	No handshake	•		interface.
	Protocol	Framing protocol with acknowledge	-		Serial COM Settings
		Framing Protocol			Build rate
					Specifies the number of transferred symbols per second
					Data mode
					This combined parameter specifes the nubmer of data bits in each character, the perity mode and the number of stop bits at the end of each character.
					Handshake
					Specifies the handshake mode for hardware flow control.
					Protocol
					Specifies the protocol mode, If famming protocol with achionikedgment is selected such massage has to be the analysis of the second second second second second second second the opticity protocol for communication is used when the communication follows defined rules.
					-
ØD Disconnected €2	Administra	ator			- tesis
					Gurren

Fig. 6.7: Host interface tab

Select the desired baud rate, the stop bits, the data bits, the parity and various transmission modes here. The parameters are not active until these settings have been transferred to the code reader (standard procedure).

The desired acknowledgment settings are also to be set in this selection window.

Properties window (Framing Protocol) – Host interface tab

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BCL 148	△ Leuze electronic
Code Reader	the sensor people
IDENTIFICATION CONFIGURATION DIAGNOSIS	
	0.
CONFIGURATION FRAMING PROTOCOL	▲ Leuze electronic ▲
Decode     MESSAGE FRAME	the sensor people
Control     Transmit     STX     V     DATA BCC ETX     Control     Transmit     STX     V     DATA BCC ETX	Framing Protocol
Franing Protocol	The framing protocol is a character based protocol for the transmission of 7-bit
Sensor RECEIVE / TRANSMT	ASCII characters. It groups the characters to be transmitted into a data block and
Prefix 1 Prefix 2 Postfix 1 Postfix 2 BCC Mode	manies the block with control characters.
STX V NULL V ETX V NULL V BCC Mode 2 V	Various block checking methods are optionally available for protecting the integrity of the data
ADDRESS SETTINGS	
Address format Address	Receive / Transmit
ASCII address (2 character) 🗾 0 💠	
	Prefix and Postfix
	For both transmission directions up to 2 prefix and postfix characters can be set as
	BCC Mode
	The Block Check Character (BCC) mode specifies a computation algorithm of a check character for error recognition.
	Address settings
	Address format
	When the device is part of a network this value specifies the address format of the serial interface.
	Address
	The address identifies a single device within a network.
۹۶ Disconnected کا Administrator	

Fig. 6.8: Standard settings for the Properties window (Framing Protocol) – Host interface tab

Here, you can change the address settings and the protocol for sending and receiving.

To be able to continue to communicate with a device following a parameter transfer, it may be necessary to make appropriate adjustments to the communication properties of the device in the *Sensor Studio* configuration software.

# 6.5.5 Sensor tab

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CONFIGURATION	SENSOR	▲ Leuze electronic <sup>▲</sup>
Output	SWITCHING INPUT	the sensor people
Control Control Framing Protocol Sensor	Invert     Debounce time       Image: trput mode     Image: trput mode       Image: trput mode     Image: trpu	<section-header><text><section-header><text><text><text><text><text><text><text><text></text></text></text></text></text></text></text></text></section-header></text></section-header>
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		admin

# Fig. 6.9: Sensor tab

Inverted	Here, the input level can be inverted
Debounce time	This time period must lapse until the trigger signal is
(Debounce time)	regarded as valid.
Switch-off delay	After the end of the trigger signal, the pulse is ex-
(Delay off time)	tended internally by this time period.
Function	Event that is started when the switching input is ac-
(Control)	tivated.

# 6.5.6 System/scanner character tab

With the system parameters, you can define the general behavior of the code reader.

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File Edit View Device	Tools Window ?		
	■ <b>○</b> • ■ 12 3 ○   P- P-  C- C-	< (2) (2, 2) · ● ;	
BCL148 - Main operation			A Louis shakarin
Code Reader			4 Leuze electronic
Analysis Automa	tion		the sensor people
		IDENTIFICATION CONFIGURATION D	IAGNOSIS
CONFIGURATION	SYSTEM		△ Leuze electronic <sup>▲</sup>
Decode Output	SYSTEM PROPERTIES		the sensor people
Control	Start character	\$°	System
Framing Protocol	Warning character	NULL	The system parameters enable to specify the common behavior of the scanner.
System	Error character	NULL	Start character
			This character is sent by the scanner after restart when the system is ready, i.e. when the initialization has been successfully completed.
			After sending this character the decoding system is ready for processing external commands or signals.
	:		<ul> <li>Please Note!</li> <li>If the parameter is set to the value NULL no start character will be sent by the scanner.</li> </ul>
			Warning character
			This character will be sent in case of a warning by the scanner via its serial host interface.
			Please Note! The warning character won't be sent if its value is NULL.
			Error character
			This character will be sent in case of an error by the scanner via its serial host interface.
			Please Note! The error character won't be sent if its value is NULL.
م Disconnected ک	Administrator		
			admin.

Eig 6 10.	SVSTEM DDODEDTIES / scanner character
FIG. 0. IU.	STSTEW FROFERIES / Scallier character

Start character	Start character
	The code reader sends the start character if the system is ready; i.e., once initialization has been successfully completed. Default start character: 'S'
	After the code reader has sent the start character, the decoder system can process external commands or signals.
	<b>Note</b> : If this parameter is set to value <i>zero</i> , the code reader does not send a start character.
Warning character	Warning character
	To output a warning, the code reader sends the warning character via the serial host interface.
	<b>Note</b> : If this parameter is set to the value <i>zero</i> , the start character does not send a warning character.
Error character	Error character
	In the event of an error, the code reader sends the error character via the serial host interface.
	<b>Note</b> : If this parameter is set to the value <i>zero</i> , the code reader does not send an error character.

	NOTICE
6	After the code reader is configured via the <i>Sensor Studio</i> configuration software, you can gener- ate and save a file with the parameter data, e.g., to configure further code readers (see chapter 8.5 "Online commands for the parameter set operations").

# 7 Starting up the device - Configuration

# 7.1 Measures to be performed prior to the initial commissioning

NOTICE
Observe the notices for device arrangement (see chapter 4.1 "Selecting a mounting loca- tion").
If possible, always trigger the bar code reader with the aid of commands or an external transducer (photoelectric sensor).
Only then can you be certain whether a code has been read. If read, the code contents are transmitted; if not, the NoRead character is transmitted at the end of the reading gate).
Before commissioning, familiarize yourself with the operation and configuration of the de- vice.
Before connecting the supply voltage, recheck all connections and ensure that they have been properly made.

# 7.2 Starting the device

# 7.2.1 Power-on test

After connecting the operating voltage, the bar code reader performs an automatic "Power On" function test.

After the switch-on phase, the bar code reader responds with the start message via the interface.

- The start message is preset to 'S'.
- If the start message has been transferred, the bar code reader is ready.

# 7.2.2 Interface

Proper function of the interface can most easily be tested in service operation using the RS 232 interface with the *Sensor Studio* configuration software.

# 7.2.3 Online commands

Using the online commands, important device functions can be checked, e.g. reading activation (see chapter 8 "Online commands").

You can use online commands to directly send control and configuration commands to the device.

You can send online commands with a terminal program or with the *Sensor Studio* configuration software see chapter 6 "Configuration and diagnostics software - Sensor Studio").

# 7.2.4 Problems

For information on how to proceed in the event of problems during commissioning of the devices, see chapter 10 "Diagnostics and troubleshooting".

If a problem occurs that cannot be rectified even after checking all electrical connections and settings on the devices and on the host, contact your responsible Leuze electronic subsidiary or Leuze electronic customer service (see chapter 11 "Service and support").

# 7.3 Setting the configuration parameters

You commissioned the device. Usually, you will have to configure it before you can use it. With the configuration possibilities offered by the *Sensor Studio* configuration software or the device DTM, you can individually adapt the device to your specific application. For instructions regarding the various setting options, refer to the online help or to the see chapter 6.5 "Configuration parameters".

- To operate the bar code reader, it is normally sufficient to set code type and code length in accordance with the bar codes that are to be read.
- Depending on the application, you can configure the switching input according to your requirements.

# Configuration settings

The configuration settings are stored in the memory of the bar code reader in parameter sets. The various parameter sets are explained to understand what is happening during configuration parameter setting (see chapter 7.3.2 "Parameter sets").

- The setting of code type and code length is usually accomplished by using the *Sensor Studio* configuration software (see chapter 6 "Configuration and diagnostics software Sensor Studio").
- · You can set other configuration parameters as follows:
  - Via the Sensor Studio configuration software with the buttons located under CONFIGURATION.
  - Via the internal setup of the bar code reader (start with the online command **CS**; see chapter 7.3.2 "Parameter sets")
  - Via online commands (see chapter 8.5 "Online commands for the parameter set operations").

# 7.3.1 Service mode

You can connect a PC or a terminal to the device via the RS 232 interface and configure the device through this connection (see chapter 5.5 "PC or terminal connection").

# NOTICE



✤ To enter Service mode, you must connect pin 9 (/PROT) on the connector plug to GND.

 $\Rightarrow$  You can then access the device under permanently defined interface settings.

Setting the required parameters is carried out easiest in the 'Service' operating mode.

The Service mode provides the following defined operating parameters on the RS 232 interface, no matter how the device is configured for process mode:

- transmission rate: 9600 baud
- no parity
- 8 data bits
- 1 stop bit
- prefix: STX
- · postfix: CR, LF

# NOTICE

The bar code reader has various command sets!

The command set of the bar code reader in Service mode differs in some respects from the bar code reader in Host mode.

# 7.3.2 Parameter sets

The configuration settings are stored in the memory of the bar code reader in parameter sets.

- Factory default parameter set
- · Current parameter set

# Factory default parameter set

This parameter set contains the factory-set default settings for all parameters of the bar code reader. It is permanently stored in the FLASH ROM of the bar code reader.

The parameter set with the default settings is loaded into the memory of the bar code reader:

- · Prior to delivery
- With the *Sensor Studio* configuration software via the [Factory Default] button in the **DIAGNOSIS** menu.
- After the online command PC20 (see chapter 8.5 "Online commands for the parameter set operations")

# Current parameter set

In this parameter set, the current settings for all device parameters are stored. When the bar code reader is in operation, the parameter set is stored in the EEPROM of the bar code reader.

# 8 Online commands

You can use online commands to directly send control and configuration commands to the device. To do this, connect the bar code reader to a computer (host) (see chapter 5.5 "PC or terminal connection").

# NOTICE

You can send online commands with a terminal program or with the *Sensor Studio* configuration software see chapter 6 "Configuration and diagnostics software - Sensor Studio").

Information about the transmission protocol: see chapter 6.5.4 "Host interface tab".

Using the online commands you can:

- control/decode the reading gate.
- read/write/copy parameters.
- · call up status information.
- · carry out a software reset in order to reinitialize the device.

# NOTICE

For diagnosis, you can send online commands to the device via the *Sensor Studio* configuration software (**DIAGNOSIS > Terminal**).

# 8.1 Overview of commands and parameters

# NOTICE



The following chapters describe the input of online commands via a terminal program. To input online commands via the *Sensor Studio* configuration software see chapter 6 "Configuration and diagnostics software - Sensor Studio"

# Syntax

Online commands consist of one or two ASCII characters followed by command parameters.

No separation characters may be entered between the command and the command parameter(s). Both small and capitalized letters can be used.

Example:

Command:	<esc> 'f+' '<aaa>'</aaa></esc>
<esc>:</esc>	ESC character; hex 0x1B
f+:	Command, start focusing/decoding
<aaa>:</aaa>	Parameter, focus position in mm

# Notation

Commands, parameters and returned data are enclosed between single quotation marks ' ' in the text of this manual.

Most online commands are acknowledged by the device and any requested data returned.

# 8.2 General online commands

# Software version number

Command	'V'
Description	Requests device version information
Parameter	None
Acknowledgment	Example: 'BCL 148 V 60.18 17.11.2014'
	The first line contains the device type of the bar code reader, followed by the device version number and version date. The data which is actually displayed may vary from the values given here.
Operating mode	Service mode, Host mode

# NOTICE

You can use this command to check whether the communication between PC and bar code reader is functional. If you do not receive an acknowledgment, please check the interface connections or the protocol.

# Software reset

Command	'H'		
Description	Carries out a software reset. The device is restarted and reinitialized, leaving it in the same state as when the supply voltage is switched on.		
Parameter	None		
Acknowledgment	'S' (start signal)		
Operating mode	Service mode, Host mode		

# **Device status**

Command	'Z'
Description	Queries the device status.

Answer	<\$\$<\$\$<\$\$<\$\$<\$			
	<a></a>	General status		
		'0'	No error	
		'1'	Read result exists	
		'2'	Output buffer not available	
		'3'	Focus command has wrong length	
		'4'	Impermissible reading distance	
		'5'	Invalid data format for the reading distance	
		'6'	Device temperature too high	
		'7'	Motor speed too high	
	<b></b>	Device status		
		'0'	Scanner OFF	
		'1'	Scanner ON	
		'2'	Scan active	
	<c></c>	Motor status		
		'0'	Motor OFF	
		'1'	Motor is switched on and accelerating, but not yet ready	
		'2'	Motor maintaining nominal rotational speed	
	<d></d>	Laser status		
		'0'	Laser OFF	
		'1'	Laser ON (laser starting up)	
		'2'	Laser ON (laser at rated power)	
	<e></e>	Status of focusing		
		'0'	Lens at reference position	
		'1'	Lens moves from the reference position to the desired position	
		'2'	Lens at the desired position	
Operating mode	Serv	ervice mode, Host mode		

# Start setup program

Command	'E'
Description	The command starts the internal setup program of the device. In the menu for the internal setup program, you can change certain defined configuration parameters of the current parameter set.
Operating mode	Service mode, Host mode

# Navigate in the setup program

- [E] button: start setup program
- [ESC] button: back one menu item
- [X] button: exit menu
  - Dialog: with or without saving
- [Enter] button: if you have entered a parameter, you must conclude the entry by depending on the terminal program – pressing the [Enter] button once or twice.

# 8.3 Online commands for controlling decoding

# Start focusing/decoding

Command	<esc>'f+' '<aaa>'</aaa></esc>		
Description	The command starts decoding. The laser switches on, the motor runs at the correct speed, etc.		
	<esc></esc>	ESC (cancel) character; hex 0x1B	
	' <aaa>'</aaa>	aa>' Focus position in mm	
Answer	'>' on successful start, otherwise none		
Operating mode	Service mode		

# Stop focusing/decoding

Command	<esc>'f-'</esc>		
Description	The command stops decoding. The laser switches off and the lens return the reference position.		
	<esc></esc>	ESC (cancel) character; hex 0x1B	
Answer	None		
Operating mode	Service mode		

# 8.4 Online commands for controlling the code reader

# Start code reader

Command	'M'
Answer	None
Operating mode	Host mode

To activate the scanner in Host mode, you must enter the online commands in a certain sequence – and with a certain device status – as shown in the following image.



Scanner Code reader

Fig. 8.1: Flow chart: software command status



0	
	NOTICE
6	The processing status of the 'M', 'F', '+' and '-' commands can be monitored with the 'Z' command (status query).

# Stop code reader

Command	'N'
Answer	None
Operating mode	Host mode



♥ Refer to the flow chart for the correct sequence of command input.

# Start sensor (start reading)

Command	'+'
Parameter	None
Answer	None
Operating mode	Host mode

# NOTICE

✤ Refer to the flow chart for the correct sequence of command input.

♦ To start a reading, the switching input must be set after the '+' command.

# Stop sensor (end reading)

Command	·_·
Parameter	None
Answer	None
Operating mode	Host mode



 ${\ensuremath{\,{\mathbb S}}}$  Before the '-' command, the switching input must be reset.

# **Request read result**

Command	'L'				
Description	The command reque	he command requests the output of the read result.			
	<esc></esc>	ESC (cancel) character; hex 0x1B			
	' <aaa>'</aaa>	Focus position in mm			
Answer	String (without carria	age retu	ırn):		
	' <n_index><status></status></n_index>	<cr><l< td=""><td>_F&gt;'</td></l<></cr>	_F>'		
	'01 <timer_i1><timer< td=""><td>_h1&gt;<n< td=""><td>code_1&gt;<cl11><barcode 11=""><mr11> <cl12><cr> <lf>'</lf></cr></cl12></mr11></barcode></cl11></td></n<></td></timer<></timer_i1>	_h1> <n< td=""><td>code_1&gt;<cl11><barcode 11=""><mr11> <cl12><cr> <lf>'</lf></cr></cl12></mr11></barcode></cl11></td></n<>	code_1> <cl11><barcode 11=""><mr11> <cl12><cr> <lf>'</lf></cr></cl12></mr11></barcode></cl11>		
	'02 <timer_i1><timer <lf>…'</lf></timer </timer_i1>	_h1> <n< td=""><td>code_1&gt;<cl11><barcode 11=""><mr11><cl12> <cr></cr></cl12></mr11></barcode></cl11></td></n<>	code_1> <cl11><barcode 11=""><mr11><cl12> <cr></cr></cl12></mr11></barcode></cl11>		
	' <n_index><timer_lr <lf>'</lf></timer_lr </n_index>	i> <time< td=""><td>r_hn&gt;<ncode_n><cln1><barcode n1=""><mrn1><cln2> <cr></cr></cln2></mrn1></barcode></cln1></ncode_n></td></time<>	r_hn> <ncode_n><cln1><barcode n1=""><mrn1><cln2> <cr></cr></cln2></mrn1></barcode></cln1></ncode_n>		
	If multiple codes are same line.	detecte	ed in a reading gate, the decoded content is displayed in the		
	<n_index>'</n_index>	Numbe	er of reading gates (00 … 99)		
	' <status>'</status>	Status	code		
		'0'	Read results exist		
		'1'	No read results exist		
		'2'	Scan active		
		'3'	Overflow of the communication buffer		
		'4'	Overflow of the decoder buffer		
	' <timer_li>'</timer_li>	Time frame before the read impulse (duration of the index marking (0000 9999)			
	' <timer_hi>'</timer_hi>	Time frame of the read impulse (0000 9999)			
	' <ncode_i>'</ncode_i>	Number of codes per read impulse (0 9)			
		1: Without error			
	' <clix>'</clix>	Length of the xth code in the ith read impulse (00 99)			
	' <barcode ix="">'</barcode>	Content of the bar code (ASCII character)			
	' <mrix>'</mrix>	Number of identical readings of the code (00 99)			
	' <cr>'</cr>	ASCII code for carriage return; hex 0x0D			
	' <lf>'</lf>	ASCII	code for line feed; hex 0x0A		
Operating mode	Host mode				

	NOTICE
	The result string contains <cr> and <lf> characters</lf></cr>
U	♦ <cr> and <lf> characters may <b>not</b> be used in the framing protocol. Use, e.g., <stx><i>mes-sage</i><etx>.</etx></stx></lf></cr>
	If you work in Host mode, set your terminal program so that, if necessary, <cr> and <lf> characters are <b>not</b> used.</lf></cr>

# 8.5 Online commands for the parameter set operations

# Transferring parameters to parameter set

Command	'PT <a><b><c><ddd><ee_0><ee_n><f>'</f></ee_n></ee_0></ddd></c></b></a>			
Description	The command transmits parameter data beginning with the start address.			
Parameter	' <a>'</a>	BCC mode for sending the data to the code reader		
		'0'	No BCC	
		'3'	BCC mode	
	,,	Memo	ry location for the parameter set	
		'0'	Save parameter set in EEPROM	
		'3'	Save parameter set in RAM	
	, <c>,</c>	Additic	onal messages	
		'0'	No additional messages – write immediately	
		'3'	Additional messages follow	
	' <ddd>'</ddd>	Offset for the start of transfer; decimal number Value range: 000 510		
	' <ee_n>'</ee_n>	The nth byte (in hex format) that is written in the parameter set, counting from the start of the transfer ( <ddd>)</ddd>		
	' <f>'</f>	Block	check test (ASCII), optional.	
Answer	'PS <aa>'</aa>			
	' <aa>'</aa>	Status		
		'00'	Transfer successful	
		'01'	Invalid message	
		'02'	Invalid message length	
		'03'	Invalid BCC type	
		'04'	Invalid BCC	
		'05'	Invalid data length	
		'06'	Invalid message data	
		'07'	Invalid start address	
		'08'	Invalid parameter set	
		'09'	Invalid parameter type	
Operating mode	Service mode, Host mode			

# Requesting parameter data from parameter set

Command	'PR <a><b><ccc>ddd&gt;'</ccc></b></a>		
Description	The command requests parameter data from a parameter set.		
Parameter	' <a>'</a>	BCC mode for sending the data to the host	
		'0'	No BCC
		'3'	BCC mode

Parameter	, <p>,</p>	Parameter set for reading			
		'0'	Parameter set in EEPROM		
		'3'	Parameter set in RAM		
	' <ccc>'</ccc>	Offset	Offset for the start of reading; decimal number		
		Value range: 000 510			
	<ddd></ddd>	Numbe	Number of answer bytes		
Answer	'PT <a><b>0<ccc><dd_0><dd_1><dd_n><e>'</e></dd_n></dd_1></dd_0></ccc></b></a>				
	' <dd_n>'</dd_n>	The nth byte (in hex format) of the parameter set, counting from the <start address="">.</start>			
	' <e>'</e>	Block check test (ASCII) for <bcc type=""> '3'</bcc>			
	'PS <aa>'</aa>				
	' <aa>'</aa>	Status			
		'01'	Invalid message		
		'02'	Invalid message length		
		'03'	Invalid BCC type		
		'05'	Invalid data length		
		'07'	Invalid start address		
		'08'	Invalid parameter set		
		'09'	Invalid parameter type		
	None, if no intermediate buffer is available for the parameter set.				
Operating mode	Service mode, Host mode				

# Copying parameter set

Command	'PC' ' <a>' 'b&gt;'</a>			
Description	The command copies complete parameter sets.			
	Note: Only command 'PC20' is valid. This command copies the parameter set with the factory settings to the current parameter set.			
Parameter	' <a>'</a>	' Output parameter set		
	,,	Target	parameter set	
Answer	None, if the command was successfully executed (code reader restarts).			
	'PS' ' <aa>'</aa>			
	' <aa>'</aa>	Status		
		'02'	Invalid message length	
		'08'	Invalid parameter set	
		'09'	Invalid parameter type	
Operating mode	Service mode, Host mode			

# Analyzing parameter set

Command	'PA' ' <a>&gt;'</a>
Description	The command analyzes the check sum calculation for the selected parameter set.

Parameter	' <a>'</a>	Parameter set for analyzing the check sum calculation		
		0	Parameter set that is stored in the EEPROM	
		1	Customer-specific parameter set	
		2	Parameter set with factory settings	
		3	Parameter set currently stored in RAM	
Answer	'PS' ' <aa>'</aa>			
	' <aa>'</aa>	Status		
		'00	Transfer successful	
		'02'	Invalid message length	
		'08'	Invalid parameter set (checksum)	
		'09'	Invalid parameter type	
Operating mode	Service mode, Host mode			

# NOTICE

The Sensor Studio configuration software offers an [Export Parameter Command File...] button in the **CONFIGURATION** menu ( ) via which the currently set parameter data is written to a text file in such a way that it can again be directly copied from the text file back into the code reader.

Application example: Within the scope of series production, copy a parameter set to many code readers.



# NOTICE

On request, Leuze electronic will be happy to provide you with additional information on the topic of online commands. Please contact Leuze electronic customer service (see chapter 11 "Service and support").

# **Application example**

Within the scope of series production, copy a parameter set to other code readers.

After the code reader is configured via the Sensor Studio configuration software, you can use the [ ] button to generate a file with the parameter data and save it in the desired directory.

Example configuration:

- File name: BCL148\_ParameterCMD.txt
- File type: txt files (\*.txt)

# File BCL148\_ParameterCMD.txt contains the following data string:

Η

To load this configuration data string for use in multiple code readers (e.g., series production), this data must be loaded in the code readers as individual PT sequences (PT = **P**arameter **T**ransmit).

· Command from the control to the code reader:

### Answer from the code reader:

PS0

# · Command from the control to the code reader:

### Answer from the code reader:

PS0

# • Command from the control to the code reader:

# Answer from the code reader:

PS0

# · Command from the control to the code reader:

### Answer from the code reader:

PS0

# • Command from the control to the code reader:

# Answer from the code reader:

PS0

# · Command from the control to the code reader:

Answer from the code reader:

ps0

· Command from the control to the code reader:

**`**H**`** 

Answer from the code reader:

**`**S **`** 

The parameter set is thereby loaded in the code reader and ready.

# 9 Care, maintenance and disposal

# Cleaning

Clean the glass window of the bar code reader with a soft cloth before mounting if necessary.

# NOTICE



# Do not use aggressive cleaning agents!

b Do not use aggressive cleaning agents such as thinner or acetone for cleaning the device.

# Maintenance

Usually, the bar code reader does not require any maintenance by the operator.

Repairs to the device must only be carried out by the manufacturer.

Solution in the second seco

# Disposing

♥ For disposal observe the applicable national regulations regarding electronic components.

# 10 Diagnostics and troubleshooting

Status messages from the device can be transferred via the interface.

# Troubleshooting

Please contact your responsible Leuze electronic subsidiary or Leuze electronic customer service if you cannot rectify faults and errors with the configuration software (see chapter 11 "Service and support").

Tab. 10.1: Errors, causes of errors and measures

Error	Possible error cause	Measures
No communi- cation possi- ble	Incorrect wiring.	Check wiring.
	Wrong interface selected.	Select the correct interface via the <i>Sensor Studio</i> con- figuration software.
	Different protocol settings.	Check protocol settings in the device and in the Sensor Studio configuration software or switch device to the Service operating mode.
No code reading pos- sible	Code reading not possible (qual- ity).	Improve code quality! Entire code in laser line?
	Code is not enabled.	Check entries in the code table (type and length).
	Excessive reflections.	Increase skew of the laser beam to > $10^{\circ}$ with respect to vertical.

# 11 Service and support

# 24-hour on-call service at:

+49 (0) 7021 573-0

# Service hotline:

+49 (0) 7021 573-123 Monday to Friday 8.00 a.m. to 5.00 p.m. (UTC+1)

# E-mail:

service.identify@leuze.de

# Repair service and returns:

Procedure and Internet form can be found at

www.leuze.com/repair Return address for repairs:

# Service center

Leuze electronic GmbH + Co. KG

In der Braike 1

D-73277 Owen / Germany

# 11.1 What to do should servicing be required?

# NOTICE



Please use this chapter as a master copy should servicing be required!

Enter the contact information and fax this form together with your service order to the fax number given below.

# Customer data (please complete)

Device type:	
Serial number:	
Firmware:	
Error description:	
Company:	
Contact person/department:	
Phone (direct dial):	
Fax:	
Street/No:	
ZIP code/City:	
Country:	

# Leuze Service fax number:

+49 (0) 7021 573-199

# 12 Technical data

# 12.1 General specifications

Tab. 12.1: Optics

Light source	Laser diode
Wavelength	650 nm (visible red light)
Beam exit	Lateral
Impulse duration	110 µs
Max. output power (peak)	1.3 mW
Laser class	2 acc. to IEC 60825-1:2007
Scanning rate	750 scans/s
Focus setting time	<250 ms
Reading distance / reading field width	see chapter 12.2 "Reading fields"
Reading area	30 mm $\dots$ 290 mm for module width up to 200 $\mu m$
	30 mm $\dots$ 310 mm for module width from 200 $\mu$ m
	70 mm $\dots$ 110 mm for module width of 127 $\mu$ m
Reading field height	Min. 60 mm at reading distance from 30 mm
	Min. 80 mm at reading distance from 50 mm
Software features	Selectable output format, multiple read, real time decoding, con- trol of the switching input

# Tab. 12.2: Code specifications

Code types	2/5 Interleaved, Code 39 (number of digits 2 63), 2/5 IATA, 2/5 Industrial, UPC (A/E) Code 128, EAN 128 (number of digits 2 63), Pharmacode, Add-On (EAN), Codabar
Module width	5 mil, 6.5 20 mil
(distance dependent)	127 μm, 167 … 500 μm
Print quality	ANSI X3, 123
	DIN EN 1635 class A, B
Skew	> 10°

# Tab. 12.3: Interfaces

Process interface	RS 232 or RS 485
Baud rate	110 57600 baud
Data formats	Data bits: 7, 8, 9
	Parity: none, even, odd
	Stop bit: 1, 2
Service interface	RS 232 with fixed data format
	8 data bits, no parity, 1 stop bit
	<stx> <data> <cr><lf></lf></cr></data></stx>
Protocols	application specific

Ports	1 switching input (SWI1)	
	1 addressing input (/MA0)	
	1 changeover input for Service mode protocol / Host mode proto- col (/PROT)	

# Tab. 12.4: Electrical equipment

Operating voltage	+18 30 V DC, Safety Class III - PELV (Protective Extra Low Voltage)	
	Note:	
	For UL applications: use is permitted exclusively in Class 2 cir- cuits according to NEC	
Power consumption	Max. 9 W	
Switching input	+18 30 V DC depending on operating voltage,	
	I <sub>max</sub> .= 8 mA	

# Tab. 12.5: Mechanical data

Degree of protection	IP 65	
Connection type	Connection cable, 0.9 m long with 15-pin SUB-D connector plug	
Weight	615 g	
Dimensions (H x W x D)	119 x 71 x 38 mm	
Fastening	M4 mounting bracket, 4 mm deep	
Housing	Diecast zinc	
Optics cover	Glass	

# Tab. 12.6: Environmental data

Ambient temperature (operation)	+5 °C +40 °C	
Air humidity	10 % 85 % rel. humidity, non-condensing	
Electromagnetic compatibility	EN 61326-1:2013-01	
	FCC15 - CFR 47 Part 15 (July 18, 2014)	
Certifications	UL 60950-1 For UL applications: use is permitted exclusively in Class 2 circuits according to NEC	
	CSA C22.2 No. 60950-1-07	
Conformity	CE, FCC	

# 12.2 Reading fields



Please note that the actual reading fields are also influenced by factors such as labeling material, printing quality, scanning angle, printing contrast etc., and may thus deviate from the reading fields specified here. The origin of the read distance always refers to the front edge of the housing of the beam exit.



2 Reading field width [mm]

Fig. 12.1: Reading curve for module m=127 µm

Reading curve for module m=167 ... 200 µm



Fig. 12.2: Reading curve for module m=167 ... 300 µm



Fig. 12.3: Reading curve for module m=200  $\dots$  300  $\mu$ m

# 12.3 Dimensioned drawings

# **Dimensioned drawing BCL 148**



all dimensions in mm

- A Optical axis
- B M4 mounting bracket, 4 mm deep (4x)
- C Laser beam
- D Rastering max. 3 mm at a distance of 200 mm
- E Optical beam path (for received light), approx. 15 mm wide
- L Cable length approx. 0.9 m
- Fig. 12.4: Dimensioned drawing BCL 148

# 13 Order guide and accessories

# 13.1 Type overview

Tab. 13.1: Part numbers

Part no.	Part designation	Description
50131538	BCL 148 V 340 B	Single line scanner, RS 232 or RS 485 interface, 310 mm reading distance

# 13.2 Accessories

Tab. 13.2: Accessories

Sensor Studio configuration software Download at www.leuze.com (see chapter 6.2.1 "Downloading configuration software")	Sensor Studio designed according to the FDT/DTM concept. Contains: communication DTM and device DTM
NOTICE	
On request, Leuze electronic can make available the <i>BCL Configuration Tool</i> editor program.	

# 14 EC Declaration of Conformity

The bar code readers of the BCL 148 series have been developed and manufactured in accordance with the applicable European standards and directives.



# 15 Appendix

15.1 Bar code samples



Module 0.3

Fig. 15.1: Code type 01: Interleaved 2 of 5



135AC

Module 0.3

Fig. 15.2: Code type 02: Code 39



a121314a

Module 0.3

Fig. 15.3: Code type 11: Codabar



abcde

Module 0.3

Fig. 15.4: Code 128



uze

Module 0.3

Fig. 15.5: Code type 08: EAN 128



SC 2

Fig. 15.6: Code type 06: UPC-A



SC 3

Fig. 15.7: Code type 07: EAN 8