# **Temposonics**®

Magnetostrictive Position Sensors



L-Series Start-Stop Interface

**Temposonics-LH**Measuring length 50 - 3000 mm



# High Pressure Stainless Steel Sensor with 100°C Electronics

Linear, Absolute Measurement
Contactless Sensing with Highest Durability
Rugged Industrial Sensor, EMC shielded and CE certified
Linearity Tolerance better 0,02 %
Repeatability 0,001 %
Start/Stop Pulse Transmission
Operating Temperature up to 100° C

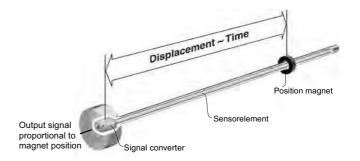




# Magnetostriction

The absolute Temposonics® linear position sensors are based on the MTS developed magnetostrictive measurement principle. That combines various magneto-mechanical effects and uses the physical hight precise speed-measurement of an ultrasonic wave (torsion pulse in its sensor element) for position detecting.

Sensor integrated signal processing transforms the measure-ments directly into market standard outputs. The contactless priciple - an external movable magnet marks the position - eliminates the wear, noise and erroneous signal problems and guarantees the best durability without any recalibration.



Operating principle: Magnetostrictive ultrasonic speed measurement = Position sensing

#### **Technical Data**

Input

Measured variable Displacement 50 - 3000 mm Measuring range

Output

Start-Stop pulse RS 422 differential signal

Accuracy - Resolution

0,1 mm / 0,01 mm / 0,005 mm (controller dependent) - Linearity

< ± 0,02 % F.S. (Minimum ± 50 µm)

- Repeatability < ± 0,001 % F.S - Update frequency Controller dependent

**Operating conditions** 

Magnet speed Operating pressure

Operating temperature

Any
350 bar (530 bar peak pressure)
-40 °C ... +100 °C
90% rel. humidity, no condensation Dew point, humidity IP67 if mating connector is correctly fitted 100 g single hit, IEC-Standard 68-2-27 Sealing Shock test 10 g / 10 - 2000 Hz, IEC-Standard 68-2-6 Vibration test Norms, EMC test Electromagnetic emission EN 50081-1 Electromagnetic immunity EN 50082-2 EN 61000, Criteria A, CE-qualified

Form factor, material

Sensor head Aluminum

Stainless steel 1.4301 / AISI 304 Rod with flange

Ring- or U-Magnet Position transmitter

Installation

Mounting position

Threaded flange M18 x 1,5 or 3/4" -16 UNF-3A, hex nut M18 Rod

Magnet Mounting plate and screws: amagnetic

**Electrical connection** 

Connection type 6 pin connector M16 or 2 m cable outlet

24 VDC (-15 / +20 %) 100 mA typical Input voltage Current consumption Ripple

< 1 % peak-peak 500 V (DC ground to machine ground) Electric strength



### **Formfactor**

The extremely robust sensor, ideal for continuous operation under harshest industrial conditions is completely modular in mechanics and electronics design.

- A rod-shaped sensor housing protects the sensing element in which gives rise to the measurement signal.
- The sensor head accommodates the complete modular electronics interface with active signal conditioning. Double encapsulation ensures high operating safety and optimum EMC protection.
- The position transmitter, a permanent magnet fixed at the mobile machine part - drives contactlessly over the sensor's stroke and starts measuring through the housing wall.

# Temposonics-LH ... high pressure rod design

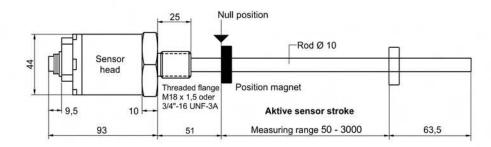
### Measuring length 50 - 3000 mm

Temposonics-LH with pressure-resistant stainless steel flange and sensing rod is suitable for use in hydraulic cylinders and <u>externally</u> in all applications where space is a problem. Position measurement is via ring or U-magnets travelling along the sensing rod without any mechanical contact.

#### Advantage...

the completely operable sensor cartridge can be replaced for servicing easily without opening the fluid circuit.







hex 46

All dimensions in mm

# Connection types

## Connector outlet D600 6 pin male connector M16



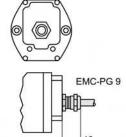


# Cable outlet R002

Max. operating temperature: 70° C 6 wires PVC cable, 3 x 2 x 0,14 mm<sup>2</sup> shield, cable-Ø 6 mm, bending radius 50 mm at fixed installation

# Cable outlet T002

Max. operating temperature: 150° C 8 wires Teflon cable, 4 x 2 x 0,25 mm<sup>2</sup> shield, cable-Ø 7,5 mm, bending radius 75 mm at fixed installation



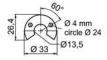
# Available position magnets (pls. order separately)



Ring magnet OD33 (standard) Part No. 201 542-2 Height: 8 mm Composite PA-ferrite-GF20 weight ca. 14 g, operating temperature -40...+100° C



Ring magnet OD25,4 Part No. 400 533 Height: 8 mm Composite PA-Ferrite, weight ca. 10 g, operating temperatur -40...+100° C



U-magnet OD33
Part No. 251 416-2
Height: 8 mm
Composite PA-ferrite-GF20
weight ca. 11 g, operating
temperature -40...+100° C



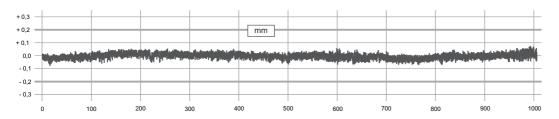
# Start/Stop output

Digital Temposonics-LH is equipped with a start/stop output. The sensor requires a start signal from an external indicator in the control system and returns a signal corresponding to the magnet position. The time elapsed between the two signals is proportional to the magnet position, i.e. to the displacement.

Time measurement is by the controller and used for calculating the position value.

# Start/Stop Displacement ~ Time Start/Stop Displacement ~ Time Time interval Position Start Start

# Linearity protocol



Sensor Temposonics-LH, stroke length 1000 mm

Tolerance allowed: ± 0,2 mm

Tolerance measured: ± 0,09 mm uncorrected



# Variable mounting in any position

#### Rod

Mount the sensor directly via flange or by means of the nut packed with the sensor. If possible, <u>non-magnetizable material</u> should be used for the sensor mounting component. Taking the mounting dimensions shown right into account is indispensable.

#### Position magnet

To have a neat magnetic field for measurement, <u>antimagnetic</u> <u>material</u> must be used for the position magnet mounting component (screws, spacers, etc.).

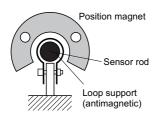
### Horizontal installation

With horizontal mounting, sensors with a measuring length from 1 meter must be provided with mechanical support at the rod end, and with supports distributed regularly over the length if the measuring rod is very long. In this case, open ring magnets must be used as position transmitter.

### Hydraulic sealing

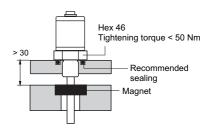
Recommended is sealing of the flange facing with an O-Ring (e.g. 22,4 x 2,65) in a cylinder cover nut.

## Sample: Sensor support

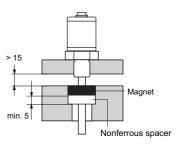


# Minimum assembly distance

### 1. Non-magnetizable material



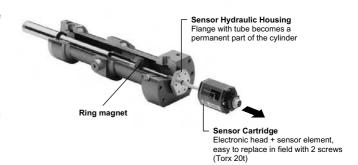
# 2. Magnetizable material



# Cylinder installation

Due to form factor, a rod sensor is excellently suited for <u>direct</u> stroke measurement in fluid cylinders. The magnet, mounted on the piston bottom, drives contactlessly along the stroke and marks exactly the position through the rod wall - <u>independent of the used hydraulic fluid</u> - that guarantees a longlife and trouble-free operation.

The sensor cartridge can be removed from the flange and rod housing while still installed in the cylinder. This procedure allows quick and easy sensor cartridge replacement, without the loss of hydraulic pressure.

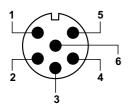


### Notes

- Magnet must not slide along the sensor tube
- Bore in the piston rod and type of sealing depends on pressure and piston velocity (13 mm min.)
- Do not exceed peak pressure
- Protect sensor rod from wear



# Wiring



Front face of sensor plug rear of mating connector

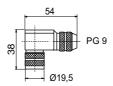
Pin	Cable color	Function
1	gray	Stop (-)
2	pink	Stop (+)
3	yellow	Start (+)
4	green	Start (-)
5	brown	+ 24 Vdc (±10 %)
6	white	DC Ground (0 V)

# Mating connectors (recommended, not on delivery)



6 pin female connector M16, PG 7 Part No. STC0 9131 D

6 pin female connector M16, PG 9 Part No. STC0 9131 D06 PG9

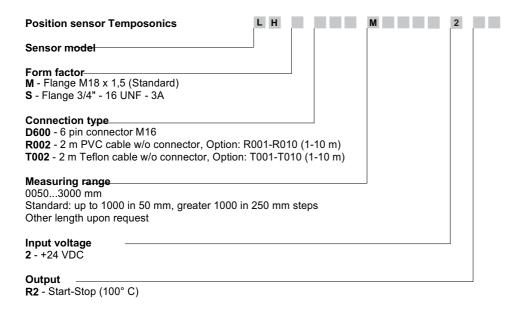


6 pin 90° female connector M16 Insert adjustable in 45° positions
Part No. STC0 9131-6

Housing: Zinc, nickel plated Termination: Solder Contact insert: Silver plated Cable clamp: PG 7 / 9



# **Ordering Code**



On delivery: Sensor, hex nut, pls. order magnet (see below) separately.

Accessories	Part-Nr.
Ring magnet OD33, Standard	201 542-2
Ring magnet OD25,4	400 533
U-Magnet OD33	251 416-2
6 pin mating connector M16, PG7	ST C0 9131D
6 pin matingconnector M16, PG9	ST C0 9131D06 PG9
6 pin 90° female mating connector M16	ST C0 9131-6
PVC cable 3 x 2 x 0,14 mm <sup>2</sup>	K27
Teflon cable, temperature resistance 100° C, 4 x 2 x 0.25 mm <sup>2</sup>	K34

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