(Mar	Technical data		
	General specifications		
	Sensing range Unusable area	80 1000 mm 0 80 mm	
	Standard target plate	100 mm x 100 mm	
	Transducer frequency	approx. 255 kHz	
	Response delay	approx. 150 ms	
	Indicators/operating means	Power on	
	LED green LED red	flashing: error(br>permanent: no object detected	
	Electrical specifications		
•	Operating voltage U _B	10 30 V DC , ripple 10 % _{SS}	
	No-load supply current I ₀	≤ 50 mA	
	Input/Output Synchronization	1 synchronous connection, bi-directional	
	Synchronization	0-level: -U _B +1 V	
		1-level: +4 V+U _B	
		input impedance: > 12 k Ω	
C US		synchronization pulse: \geq 100 µs, synchronization interpulse period: \geq 2 ms	
	Synchronization frequency		
	Common mode operation	≤ 30 Hz	
Model Number	Multiplex operation	\leq 30/n Hz, n = number of sensors	
UB1000-18GM75-PWM-V15	Input Input type	1 Parameterization input	
		Input impedance: > 4.7 k Ω	
Single head system	Output		
Factures	Output type	1 PWM output, push/pull, programmable	
Features	Resolution Deviation of the characteristic curve	1 mm ± 1 % of full-scale value	
PWM output	Repeat accuracy	± 0.5 % of full-scale value	
• 3 different output options can be	Load impedance	> 1000 Ohm < 100 nF	
programmed	Temperature influence	± 1.5 % of full-scale value	
Paramaterization input	Ambient conditions Ambient temperature	-25 70 °C (-13 158 °F)	
-	Storage temperature	-40 85 °C (-40 185 °F)	
 Synchronization options 	Mechanical specifications		
Deactivation option	Connection type	Connector M12 x 1 , 5-pin	
-	Degree of protection	IP67	
Temperature compensation	Material Housing	brass, nickel-plated	
Diagrams	Transducer	epoxy resin/hollow glass sphere mixture; foam	
Diagrams		polyurethane, cover PBT	
Characteristic response ourse	Mass Compliance with standards and	60 g	
Characteristic response curve	directives		
Distance Y [mm]	Standard conformity		
	Standards	EN 60947-5-2:2007	
250 flat ourfood 100 mm x 100 mm		IEC 60947-5-2:2007	
250 flat surface 100 mm x 100 mm		EN 60947-5-7 [.] 2003	
200 flat surface 100 mm x 100 mm		EN 60947-5-7:2003 IEC 60947-5-7:2003	
Image: 200 Image: File stress of the stress of			
200 flat surface 100 mm x 100 mm	Approvals and certificates		
100 flat surface 100 mm x 100 mm	Approvals and certificates UL approval		
100 mm x 100 mm 150 5 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		IEC 60947-5-7:2003	
200 flat surface 100 mm x 100 mm 150 100 5 0 0 0 0 0 0 0 0	UL approval	IEC 60947-5-7:2003 cULus Listed, General Purpose cCSAus Listed, General Purpose CCC approval / marking not required for products rated	
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 Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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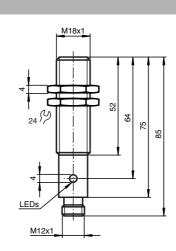
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UB1000-18GM75-PWM-V15

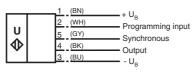
Dimensions





Electrical Connection

Standard symbol/Connections:



Core colours in accordance with EN 60947-5-2.

Pinout



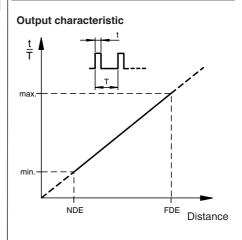
Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)
5	GY	(gray)

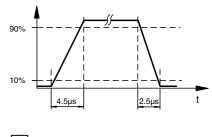
Accessories

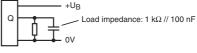
MHW 11 Mounting brackets for sensors M18K-VE UB1000-18GM75-PWM-V15

Additional Information



Rise-/fall time of output signal





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Parameter assignment of the signal output

The ultrasonic sensor is equipped with a signal output that represents the distance determined to the object in the form of a pulse-duty factor proportional to the distance of the object. The current path characteristic of this output signal follows a zero-point straight line, i.e. the extrapolated pulse-duty factor for the object distance 0 (not usable in practice) also corresponds to 0. As the distance to the object increases, the pulse-duty factor also increases. It is 50 % when the nominal sensing range is reached. The object distance can be calculated according to:

Object distance [mm] = 2 * sensing range [mm] * pulse length [s] * frequency [Hz]

If the object distance reaches or exceeds twice the nominal detection range, or if no object is detected, a level 1 is permanently present on the output.

The frequency of the output channel is adjusted by the wiring arrangement of the parameterisation input.

Wiring arrangement of the parameteri- sation input	Output frequency
-U _B	30 Hz
Not used	245 Hz
+U _B	1900 Hz

The sensor checks the parameterisation input when the operating voltage is switched on. A change in the wiring of the parameterisation input during ongoing operation has no effect on the signal output.

LED display

The sensor is equipped with 2 LEDs. Their meaning is as follows:

LED green: Operating voltage applied

LED red: No object detected

Synchronisation

The sensor features a synchronisation input for the suppression of mutual interference. If this input is not used, the sensor will operate using an internally generated clock rate. The synchronisation of multiple sensors can be implemented as follows:

External synchronisation

The sensor can be synchronised by the external application of a square wave voltage. A synchronisation pulse at the synchronisation input starts a measuring cycle. The pulse must have a duration greater than 100 μ s. The measuring cycle starts with the falling edge of a synchronisation pulse. A low level > 1 s or an open synchronisation input results in normal operation of the sensor. A high level at the synchronisation input disables the sensor.

Two operating modes are available

1) Multiple sensors can be controlled by the same synchronisation signal. The sensors work on the same clock rate.

2) The synchronisation pulses are sent cyclically to only one sensor at a time. The sensors operate in multiplex mode.

Internal synchronisation

The synchronisation connections of up to 5 sensors capable of internal synchronisation are connected to one another. When power is applied, these sensors operate in multiplex mode. The response delay increases according to the number of sensors to be synchronised. **Note**

If the option for synchronisation is not used, the synchronisation input should be connected with ground (0 V) or the sensor should be operated with a V1 cable connector (4-pin).

Installation conditions

If the sensor is installed at places, where the environment temperature can fall below 0 °C, for the sensors fixation, one of the mounting flanges BF18, BF18-F or BF 5-30 must be used.

In case of direct mounting of the sensor in a through hole using the steel nuts, it has to be fixed at the middle of the housing thread. If a fixation at the front end of the threaded housing is required, plastic nuts with centering ring (accessories) must be used.

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