\frown	Technical data	
	General specifications	
	Measurement range	400 6000 mm
	Sensing range	350 6000 mm
	Unusable area	0 350 mm
	Standard target plate	100 mm x 100 mm
IN CAL	Transducer frequency	approx. 65 kHz
The second second	Response delay	approx. 650 ms
	Indicators/operating means LED green	Power on
along a	LED green	object in evaluation range
	LED yellow	error
	Electrical specifications	
	Operating voltage U _B	10 30 V DC , ripple 10 % _{SS}
	No-load supply current I ₀	≤ 60 mA
	Input/Output	
	Synchronization	bi-directional
		0 level -U _B +1 V
		1 level: +4 V+U _B
		input impedance: > 12 KOhm synchronization pulse: ≥ 100 μs, synchronization interpuls period: ≥ 2 ms
lodel Number	Synchronization frequency	
	Common mode operation	≤ 7 Hz
B6000-F42-I-V1-Y220443	Multiplex operation	\leq 7/n Hz, n = number of sensors
ingle head system	Output	
Single nead system	Output type	1 analog output 4 20 mA
eatures	Resolution Deviation of the characteristic curve	0.7 mm ± 1 % of full-scale value
	Repeat accuracy	± 0.1 % of full-scale value
Analog output 4 mA 20 mA	Load impedance	0 300 Ohm
Extremly small unusable area	Temperature influence	± 1 % of full-scale value
-	Ambient conditions	
Temperature compensation	Ambient temperature	-25 70 °C (-13 158 °F)
Synchronization options	Storage temperature	-40 85 °C (-40 185 °F)
	Mechanical specifications	
iagrams	Connection type	Connector M12 x 1 , 4-pin IP67
lagramo	Protection degree Connection	
	Material	connector M12 x 1, 4-pin
haracteristic response curve	Housing	ABS
tance Y [m]	Transducer	epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT
	Mass	330 g
- Flat surface 100 mm x 100 mm	Factory settings	
	Output	evaluation limit A1: 400 mm evaluation limit A2: 6000 mm rising slope
	Beam width	wide sound lobe
┝ ┍╞╕╡┊╻┍┍╕╡ ╪╪╪┼┥		
	Approvals and certificates	
	UL approval	cULus Listed, General Purpose
Round bar, Ø 25 mm	CSA approval	cCSAus Listed, General Purpose
0 1 2 3 4 5 6 7 8 9	CCC approval	CCC approval / marking not required for products rated
Distance X [m]		≤36 V
ŧΥ		·
X		

 Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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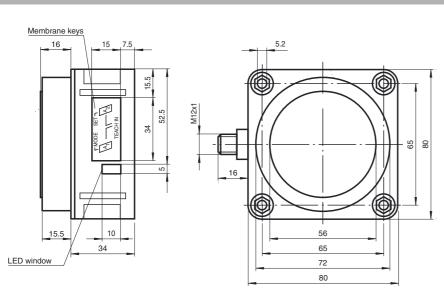
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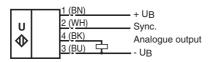


Dimensions



Electrical Connection

Standard symbol/Connections:



Core colours in accordance with EN 60947-5-2.

Pinout

Connector V1



Accessories

MH 04-3505 Mounting aid for FP and F42 sensors

MHW 11 Mounting brackets for sensors

DA5-IU-2K-V Process control and indication equipment

V1-G-2M-PVC Female cordset, M12, 4-pin, PVC cable V1-W-2M-PUR

Female cordset, M12, 4-pin, PUR cable

Description of Sensor Functions

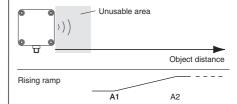
Synchronization

2

This sensor features a synchronization input for suppressing ultrasonic mutual interference ("cross talk"). If this input is not connected, the sensor will operate using internally generated clock pulses. It can be synchronized by applying an external square wave. The pulse duration must be $\geq 100 \ \mu$ s. Each falling edge of the synchronization pulse triggers transmission of a single ultrasonic pulse. If the synchronization signal remains low for ≥ 1 second,

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Analogue output programmation



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the sensor will revert to normal operating mode. Normal operating mode can also be activated by opening the signal connection to the synchronization input. (See note below) If the synchronization input goes to a high level for > 1 second, the sensor will switch to standby mode, indicated by the green LED. In this mode, the outputs will remain in the last valid output state.

Note:

If the option for synchronization is not used, the synchronization input has to be connected to ground (0 V).

The following synchronization modes are possible:

- 1. Several sensors (max. number see technical data) can be synchronized together by interconnecting their respective synchronization inputs. In this case, each sensor alternately transmits ultrasonic pulses in a self multiplexing mode. No two sensors will transmit pulses at the same time. (See note below)
- 2. Multiple sensors can be controlled by the same external synchronization signal. In this mode the sensors are triggered in parallel and are synchronized by a common external synchronization pulse.
- 3. A separate synchronization pulse can be sent to each individual sensor. In this mode the sensors operate in external multiplex mode. (See note below)
- 4. A high level (+U_B) on the synchronization input switches the sensor to standby mode.

Note:

Sensor response times will increase proportionally to the number of sensors that are in the synchronization string. This is a result of the multiplexing of the ultrasonic transmit and receive signal and the resulting increase in the measurement cycle time.

