









## **Model number**

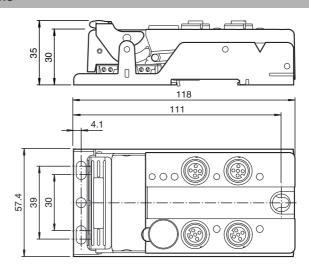
#### VBA-4E-G12-ZEJ

G12 flat module 4 inputs (PNP)

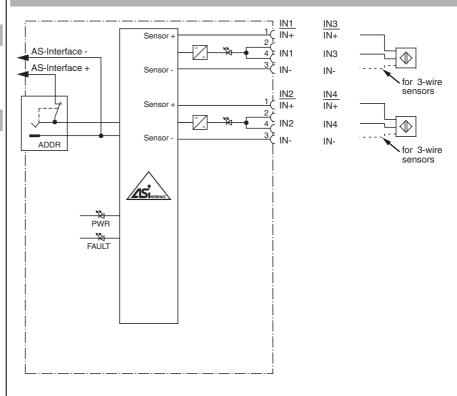
#### **Features**

- A/B slave with extended addressing possibility for up to 62 slaves
- One-piece housing with stainless steel base
- Installation without tools
- Metal threaded inserts with SPEED-CON technology
- Flat cable connection with cable piercing technique, variable flat cable guide
- · Communication monitoring
- Inputs for 2- and 3-wire sensors
- DIN rail mounting
- AS-Interface certificate

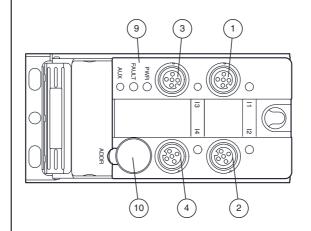
### **Dimensions**



### **Electrical connection**



## **Indicating / Operating means**







9 Status indication

(10) Addressing socket

Technical data			
General specifications			
Slave type		A/B slave	
AS-Interface specification		V3.0	
Required master specification		≥ V2.1	
UL File Number		E87056	
Functional safety related paramet	ers		
MTTF <sub>d</sub>		410 a	
Mission Time (T <sub>M</sub> )		20 a	
Diagnostic Coverage (DC)		0 %	
Indicators/operating means			
LED FAULT		error display; LED red red: communication error or address i red flashing: overload of sensor suppl	
		AS-Interface voltage; green LED green: voltage OK flashing green: address 0	
LED IN		switching state (input); 4 LED yellow	
Electrical specifications			
Rated operating voltage	U <sub>e</sub>	26.5 31.6 V from AS-Interface	
Rated operating current	l <sub>e</sub>	$\leq$ 40 mA (without sensors) / max. 240	mA
Protection class		III	
Input			
Number/Type		4 inputs for 2- or 3-wire sensors (PNP	), DC
Supply		from AS-Interface	
Voltage		21 31 V	
Current loading capacity		≤ 200 mA, overload and short-circuit protected	
Input current		≤ 8 mA (limited internally)	
Switching point		according to DIN EN 61131-2 (Type 2	)
0 (unattenuated)		≤2 mA	
1 (attenuated)		≥ 6 mA	
Signal delay		< 1 ms (input/AS-Interface)	
Programming instructions		0.04.0	
Profile		S-0.A.0	
IO code ID code		0	
ID1 code		A 7	
ID2 code		0	
		•	
Data hits (function via AS-Interface	۱,	innut	output
Data bits (function via AS-Interface	<del>)</del>	input IN1	output -
Data bits (function via AS-Interface D0 D1	e)	input IN1 IN2	output - -
D0	<del>)</del> )	IN1	output - - -
D0 D1	e)	IN1 IN2	output
D0 D1 D2		IN1 IN2 IN3 IN4	output
D0 D1 D2 D3		IN1 IN2 IN3 IN4	output
D0 D1 D2 D3 Parameter bits (programmable via		IN1 IN2 IN3 IN4 function	-
D0 D1 D2 D3 Parameter bits (programmable via		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression	- - - - on ≤ 2 ms
D0 D1 D2 D3 Parameter bits (programmable via P0 P1		IN1 IN2 IN3 IN4 function not used Input filter P1 = 0 input filter on, pulse suppressic P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on	- - - - on ≤ 2 ms
D0 D1 D2 D3 Parameter bits (programmable via P0 P1		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppressic P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode off (basic setting)	- - - - on ≤ 2 ms
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppressic P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode off (basic setting)	- - - - on ≤ 2 ms
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppressic P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting)	- - - - on ≤ 2 ms
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) To such the such that	- - - - on ≤ 2 ms etting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) structure of the synchronous mode off (basic setting)  -25 70 °C (-13 158 °F) -25 85 °C (-13 185 °F) 30 g, 11 ms in 6 spatial directions 3 structure of the synchronous mode off (basic setting)	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) To such the such that	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) To such the such that	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) To such the such that	- - - - - on ≤ 2 ms setting)
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D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection Connection Material		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) sont used  -25 70 °C (-13 158 °F) -25 85 °C (-13 185 °F) 30 g, 11 ms in 6 spatial directions 3 st 10 g, 16 ms in 6 spatial directions 100 0.75 mm 10 57 Hz , 5 g 57 150 H  IP67 cable piercing method flat cable yellow inputs: M12 round connector	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection Connection  Material Housing		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) sont used  -25 70 °C (-13 158 °F) -25 85 °C (-13 185 °F) 30 g, 11 ms in 6 spatial directions 3 st 10 g, 16 ms in 6 spatial directions 100 0.75 mm 10 57 Hz , 5 g 57 150 H  IP67 cable piercing method flat cable yellow inputs: M12 round connector	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection Connection  Material Housing Mass		IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) P3 = 1 synchronous mode off (basic setting) Synchronous mode off (basic setting) P3 = 1 synchronous mode off (basic setting) P4 = 1 synchronous mode off (basic setting) P5 = 25 85 °C (-13 158 °F) P5 = 30 g, 11 ms in 6 spatial directions 3 st P6 = 30 g, 16 ms in 6 spatial directions 100 P6 = 30 g, 16 ms in 6 spatial directions 100 P6 = 30 g, 16 ms in 6 spatial directions 100 P6 = 30 g, 16 ms in 6 spatial directions 100 P6 = 30 g, 16 ms in 6 spatial directions 100 P7 = 30 g, 16 ms in 6 spatial direc	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Wechanical specifications Degree of protection Connection  Material Housing Mass Mounting Compliance with standards and design of the compliance with standards and d	AS-i)	IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) sont used  -25 70 °C (-13 158 °F) -25 85 °C (-13 185 °F) 30 g, 11 ms in 6 spatial directions 3 st 10 g, 16 ms in 6 spatial directions 100 0.75 mm 10 57 Hz , 5 g 57 150 H  IP67 cable piercing method flat cable yellow inputs: M12 round connector  PBT 200 g Mounting base	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection Connection  Material Housing Mass Mounting Compliance with standards and dives	AS-i)	IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) sont used  -25 70 °C (-13 158 °F) -25 85 °C (-13 185 °F) 30 g, 11 ms in 6 spatial directions 3 st 10 g, 16 ms in 6 spatial directions 100 0.75 mm 10 57 Hz , 5 g 57 150 H  IP67 cable piercing method flat cable yellow inputs: M12 round connector  PBT 200 g Mounting base	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection Connection  Material Housing Mass Mounting Compliance with standards and dives Directive conformity	AS-i)	IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppressic P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) P2 = 1 synchronous mode off (basic setting) Synchronous mode off (basic setting) P3 = 1	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection Connection  Material Housing Mass Mounting Compliance with standards and dives Directive conformity EMC Directive 2004/108/EC	AS-i)	IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppression P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) sont used  -25 70 °C (-13 158 °F) -25 85 °C (-13 185 °F) 30 g, 11 ms in 6 spatial directions 3 st 10 g, 16 ms in 6 spatial directions 100 0.75 mm 10 57 Hz , 5 g 57 150 H  IP67 cable piercing method flat cable yellow inputs: M12 round connector  PBT 200 g Mounting base	- - - - - on ≤ 2 ms setting)
D0 D1 D2 D3 Parameter bits (programmable via P0 P1 P2 P3 Ambient conditions Ambient temperature Storage temperature Shock and impact resistance Vibration resistance Mechanical specifications Degree of protection Connection  Material Housing Mass Mounting Compliance with standards and dives Directive conformity EMC Directive 2004/108/EC Standard conformity	AS-i)	IN1 IN2 IN3 IN4  function not used Input filter P1 = 0 input filter on, pulse suppressic P1 = 1 input filter off (basic setting) Synchronous mode P2 = 0 synchronous mode on P2 = 1 synchronous mode off (basic setting) P2 = 1 synchronous mode off (basic setting) Synchronous mode off (basic setting) P3 = 1 synchronous mode off (basic setting) Synchronous mode off (basic setting) Synchronous mode off (basic setting) P3 = 1 synchronous mode off (basic setting) Synchronous mode off (basic sett	- - - - - on ≤ 2 ms setting)
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### **Function**

The VBA-4E-G12-Z\*J is an AS-Interface trigger module with 4 inputs. 2- and 3-wire sensors as well as mechanical contacts can be connected to the plus switching electronic inputs.

The solid housing permits fast mounting without tools as well as easy removal without tools. The stainless steel shell and the cast housing ensure durability and a high protection category.

The connection to the AS-Interface cable is achieved via penetration technology in the integrated flat cable. The insert for the flat cables can be turned in two orientations.

All connections to inputs are implemented via metal inserts for high stability. The connection to the sensors is achieved via a M12 x 1 circular connector with SPEEDCON quick locking option.

The inputs and the connected sensors are supplied via the internal power supply of the module (from AS-Interface).

To indicate the current switching state there is an LED for each channel fitted to the top of the module.

An LED to indicate the AS-Interface voltage and that the module has an address of 0 is available, another indicates errors in the AS-Interface communication as well as periphery faults.

This module can be mounted in any position using three screws or can be snapped onto the DIN rail using the stainless steel holder.

#### **Accessories**

### VBP-HH1-V3.0-KIT

AS-Interface Handheld with accessory

#### VAZ-V1-B3

Blind plug for M12 sockets

#### **VBP-HH1-V3.0**

AS-Interface Handheld

# VAZ-PK-1,5M-V1-G

Adapter cable module/hand-held programming device

## VAZ-CLIP-G12

lock for G12 module

Date of issue: 2015-02-05

**PEPPERL+FUCHS** 

Notes

Do not connect inputs and outputs, which are supplied via the module from AS-interface or via auxiliary power, with power supply and signal circuits with external potentials.

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