









# **Model Number**

# **AHM58-H**

# **Features**

- **Industrial standard** housing Ø58 mm
- 30 Bit multiturn
- Hardware encoder
- Data transfer up to 2 MBaud
- Optically isolated RS 422 interface
- **Hollow shaft**

# Description

This multiturn absolute encoder with modern fast technology transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface). The maximum resolution of the AHM58-H is maximum 65536 steps per revolution at 16384 revolutions. In contrast to the AHM58 series the encoder does not have a microcontroller. Thus, it is a pure hardware encoder

The control module sends a clock bundle to the absolute encoder to obtain position data. The rotary encoder then sends the position data synchronous to the cycles of the control module. It is possible to select the counting direction with the function input. The absolute encoder is mounted directly onto the application shaft, without any coupling. Rotation of the absolute encoder is prevented by a torque rest

The electrical connection is made by a 12-pin round plug connector. A version with a 1 m cable connector is also available.

# **Technical data**

#### General specifications

Detection type photoelectric sampling Device type Multiturn absolute encoder

#### **Electrical specifications**

Operating voltage U<sub>B</sub> 4.5 ... 30 V DC No-load supply current I<sub>0</sub> max. 180 mA

± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit Linearity

Output code Gray code, binary code

Code course (counting direction) cw descending (clockwise rotation, code course descending)

Interface type SSI Monoflop time  $20~\pm10~\mu s$ 

Resolution

Single turn up to 16 Bit Multiturn 14 Bit Overall resolution up to 30 Bit 0.1 ... 2 MBit/s Transfer rate U<sub>B</sub> - 2.5 V Voltage drop Standard conformity RS 422

Input 1

Input type Selection of counting direction (cw/ccw)

Signal voltage

High 4.5 ... 30 V Low 0 ... 2 V Input current < 6 mA Switch-on delay < 10 ms

Connection

Connector type 9416 (M23), 12-pin, type 9416L (M23), 12-pin

Cable Ø7 mm, 6 x 2 x 0.14 mm<sup>2</sup>, 1 m

Standard conformity

DIN EN 60529, IP65 Degree of protection DIN EN 60068-2-3, no moisture condensation Climatic testing

Emitted interference EN 61000-6-4:2007

EN 61000-6-2:2005 Noise immunity

Shock resistance DIN EN 60068-2-27, 100 g, 6 ms DIN EN 60068-2-6, 20 g, 10 ... 2000 Hz Vibration resistance

Ambient conditions

Operating temperature -40 ... 85 °C (-40 ... 185 °F) -40 ... 85 °C (-40 ... 185 °F) Storage temperature

Mechanical specifications

Material

Housing: aluminum Flange: aluminum Shaft: stainless steel Combination 1

approx. 300 g (combination 1) Mass

Rotational speed max. 3000 min -1 Moment of inertia 30 gcm<sup>2</sup> Starting torque < 3 Ncm

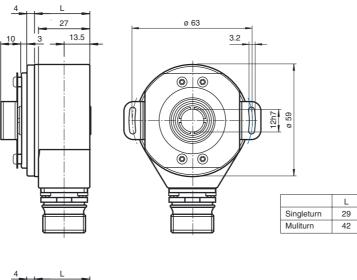
Shaft load

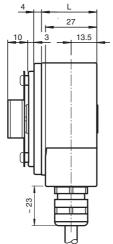
Angle offset ± 0.9 °

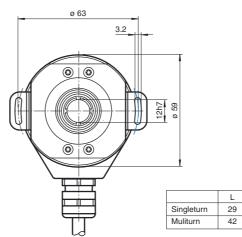
Axial offset static: ± 0.3 mm, dynamic: ± 0.1 mm Radial offset static: ± 0.5 mm, dynamic: ± 0.2 mm

# Approvals and certificates

**UL** approval cULus Listed, General Purpose, Class 2 Power Source







# **Electrical connection**

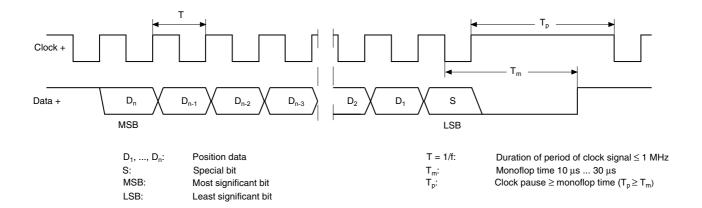
Signal	Cable Ø7 mm, 12-core	Connector 9416, 12-pin	Connector 9416L, 12-pin	Explanation
GND (encoder)	White	1	1	Power supply
U <sub>b</sub> (encoder)	Brown	2	8	Power supply
Clock (+)	Green	3	3	Positive cycle line
Clock (-)	Yellow	4	11	Negative cycle line
Data (+)	Grey	5	2	Positive transmission data
Data (-)	Pink	6	10	Negative transmission data
Reserved	Blue	7	12	Not wired, reserved
V/R	Red	8	5	Input for selection of counting direction
Reserved	Black	9	9	Not wired, reserved
Reserved	Violet	10	4	Not wired, reserved
Reserved	Grey/Pink	11	6	Not wired, reserved
Reserved	Red/Blue	12	7	Not wired, reserved
		9 8 10 7 12 6	9 1 12 2 10 3	

# **Description**

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

# SSI signal course Standard



# SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data  $(D_n)$  and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time  $T_m$  has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T<sub>D</sub> has expired.
- After the clock sequence is complete, the monoflop time T<sub>m</sub> is triggered with the last falling pulse edge.
- The monoflop time  $T_{\text{m}}$  determines the lowest transmission frequency.

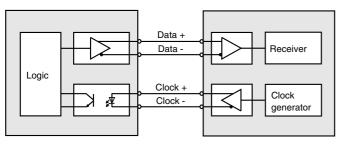
# SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, 25 bits are transferred per data word in standard format.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first transmission, the 26<sup>th</sup> pulse controls data repetition. If the 26<sup>th</sup> pulse follows after an amount of time greater than the monoflop time T<sub>m</sub>, a new current data word will be transmitted with the following pulses.



If the pulse line is exchanged, the data word is generated offset. Ring slide operation is possible up to max. 13 bits.

# **Block diagram**



Rotary encoder Interface electronics

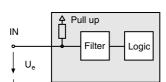
# Line length

Line length in m	Baudrate in kHz
< 50	< 400
< 100	< 300
< 200	< 200
< 400	< 100

# Input

The selection of the counting direction input (V/R) is activated with 0-level.

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# **Accessories**

Accessories	Name/defining feature	Order code
Connectors	Cable socket	9416
Connectors	Cable socket	9416L

For additional information on the accessories, please see the "Accessories" section.

#### Order code 5 8 0 R Ν Number of bits singleturn 12 4096 (standard) 13 8192 16 65536 Number of bits multiturn 00 for singleturn-encoders 12 4096 (standard) 14 16384 **Output code** В Binary G Gray Option Н Hardware encoder Zero set function **Exit position** R Radial Connection type K1 Cable Ø7 mm, 6 x 2 x 0.14 mm<sup>2</sup>, 1 m AA Plug connector type 9416, 12-pin ΑB Plug connector type 9416L, 12-pin Shaft dimension/flange version Hollow shaft with Ø10 mm OBA Hollow shaft with Ø12 mm **Housing material** Ν Aluminium Principle of operation Singleturn s Multiturn Wellenausführung н Hollow shaft

**Data format** 

A SSI (Synchronous Serial Interface)