

AHS58-0

Features

- **Industrial standard** housing Ø58 mm
- 16 Bit singleturn
- Data transfer up to 2 MBaud
- Optically isolated RS 422 interface
- **Zero-set function**
- Hollow shaft

Description

This singleturn absolute encoder with modern fast technology transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface).

The resolution of the AHS58 is maximum 65536 steps per revolution.

The devices of the AHS58 series are equipped with a microcontroller.

The control module sends a clock bundle to the absolute encoder to obtain the position data. The rotary encoder then sends the position data synchronous to the cycles of the control module. It is possible to select the following items with function inputs

- the counting direction and
- the zero-set function (preset value)

The absolute encoder is mounted directly onto the application shaft, without any coupling. Rotation of the absolute encoder is prevented by a torque rest. The electrical connection is made by a 12-pin round plug connector. It is also possible to obtain a version with a 1 m cable connector.

Technical data

General specifications

Detection type photoelectric sampling Device type Singleturn absolute encoder

Electrical specifications

Operating voltage U_B 4.5 ... 30 V DC No-load supply current I₀ max. 180 mA

± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit Linearity

descending)

Selection of counting direction (cw/ccw)

Output code Gray code, binary code Code course (counting direction) cw descending (clockwise rotation, code course

Interface type SSI Monoflop time $20~\pm10~\mu s$

Resolution

Single turn up to 16 Bit Overall resolution up to 16 Bit Transfer rate 0.1 ... 2 MBit/s U_B - 2.5 V Voltage drop RS 422 Standard conformity

Input 1

Input type

Signal voltage 4.5 ... 30 V High

Low 0 ... 2 V Input current < 6 mA Switch-on delay < 10 ms

Input 2 Input type

zero-set (PRESET 1) Signal voltage

4.5 ... 30 V High 0 ... 2 V Low Input current < 6 mA > 100 ms

Signal duration Switch-on delay < 10 ms Connection

Connector type 9416 (M23), 12-pin, type 9416L (M23), 12-pin Cable

Ø7 mm, 6 x 2 x 0.14 mm², 1 m

Standard conformity

DIN EN 60529, IP65 Degree of protection DIN EN 60068-2-3, no moisture condensation Climatic testing

Emitted interference EN 61000-6-4:2007 FN 61000-6-2:2005 Noise immunity

Shock resistance DIN EN 60068-2-27, 100 g, 6 ms Vibration resistance DIN EN 60068-2-6, 20 g, 10 ... 2000 Hz

Ambient conditions

-40 ... 85 °C (-40 ... 185 °F) Operating temperature Storage temperature -40 ... 85 °C (-40 ... 185 °F)

Mechanical specifications

Material

Combination 1 Housing: aluminum Flange: aluminum Shaft: stainless steel

approx. 300 g (combination 1) Mass

max. 3000 min Rotational speed Moment of inertia 30 gcm² Starting torque < 3 Ncm

Shaft load

Anale offset ± 0.9 °

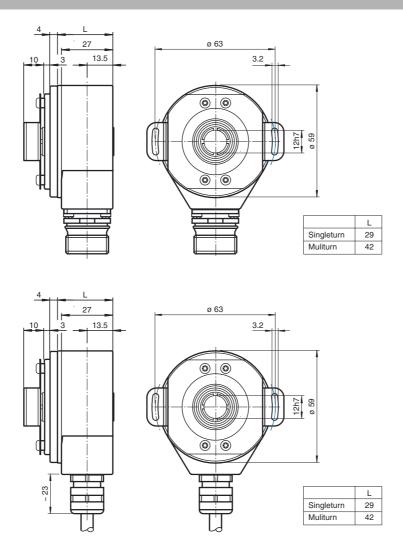
Axial offset static: ± 0.3 mm, dynamic: ± 0.1 mm Radial offset static: ± 0.5 mm, dynamic: ± 0.2 mm

Approvals and certificates

UL approval

cULus Listed, General Purpose, Class 2 Power Source

Dimensions



Electrical connection

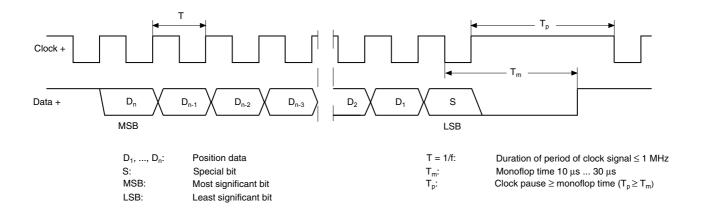
Signal	Cable Ø7 mm, 12-core	Connector 9416, 12-pin	Connector 9416L, 12-pin	Explanation
GND (encoder)	White	1	1	Power supply
U _b (encoder)	Brown	2	8	Power supply
Clock (+)	Green	3	3	Positive cycle line
Clock (-)	Yellow	4	11	Negative cycle line
Data (+)	Grey	5	2	Positive transmission data
Data (-)	Pink	6	10	Negative transmission data
Reserved	Black	7	12	Not wired, reserved
V/R	Red	8	5	Input for selection of counting direction
PRESET 1	Blue	9	9	zero-setting input
Reserved	Violet	10	4	Not wired, reserved
Reserved	Grey/Pink	11	6	Not wired, reserved
Reserved	Red/Blue	12	7	Not wired, reserved
		9 8 10 7 12 6	9 1 12 2 10 3	

Description

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

SSI signal course Standard



SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D_n) and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T_m has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T_D has expired.
- After the clock sequence is complete, the monoflop time T_m is triggered with the last falling pulse edge.
- The monoflop time T_{m} determines the lowest transmission frequency.

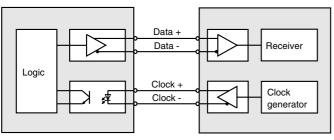
SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, 25 bits are transferred per data word in standard format.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first transmission, the 26th pulse controls data repetition. If the 26th pulse follows after an amount of time greater than the monoflop time T_m, a new current data word will be transmitted with the following pulses.



If the pulse line is exchanged, the data word is generated offset. Ring slide operation is possible up to max. 13 bits.

Block diagram



Line length

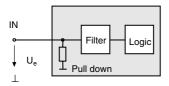
Line length in m	Baudrate in kHz
< 50	< 400
< 100	< 300
< 200	< 200
< 400	< 100

Rotary encoder

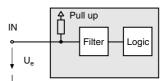
Interface electronics

Inputs

The selection of the counting direction input (V/R) is activated with 0-level. The zero-set input (PRESET 1) is activated with 1-level.



Input for selection of counting direction (V/R)



Accessories

Accessories	Name/defining feature	Order code
Connectors	Cable socket	9416
Connectors	Cable socket	9416L

For additional information on the accessories, please see the "Accessories" section.

Order code 5 8 R Ν 0 Number of bits singleturn 12 4096 (standard) 13 8192 16 65536 Number of bits multiturn 00 for singleturn-encoders 12 4096 (standard) 14 16384 **Output code** В Binary G Gray Option Н Hardware encoder Zero set function **Exit position** R Radial Connection type K1 Cable Ø7 mm, 6 x 2 x 0.14 mm², 1 m AA Plug connector type 9416, 12-pin ΑB Plug connector type 9416L, 12-pin Shaft dimension/flange version Hollow shaft with Ø10 mm OBA Hollow shaft with Ø12 mm **Housing material** Ν Aluminium Principle of operation Singleturn s Multiturn Wellenausführung н Hollow shaft

Data format

SSI (Synchronous Serial Interface)