

Model Number

ENA58IL-R***-SSI

Features

- Recessed hollow shaft
- SSI interface
- Up to 32 Bit multiturn
- Free of wear magnetic sampling
- High resolution and accuracy

Description

The ENA58IL series are high precision encoders with internal magnetic sampling. This multiturn absolute encoder transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface). The control module sends a start sequence to the absolute encoder to obtain the position data. The rotary encoder then sends the position data synchronous to the cycles of the control module. It is possible to select the counting direction with the function input. **Technical data** General specifications Detection type Device type Linearity error Functional safety related parameters $\mathsf{MTTF}_{\mathsf{d}}$ Mission Time (T_M) L_{10h} Diagnostic Coverage (DC) **Electrical specifications** Operating voltage UB No-load supply current I₀ Power consumption P₀ Output code Code course (counting direction) Interface Interface type Resolution Single turn Multiturn Overall resolution Transfer rate Cycle time Standard conformity Input 1 Input type Signal voltage High Low Input current Switch-on delay Input 2 Input type Signal voltage Hiah Low Input current Signal duration Connection Connector Cable Standard conformity Degree of protection Climatic testing Emitted interference Noise immunity Shock resistance Vibration resistance Ambient conditions Operating temperature Storage temperature Relative humidity Mechanical specifications Material Housing Flange Shaft Mass Rotational speed Moment of inertia Starting torque Shaft load Angle offset Axial offset Radial offset

magnetic sampling Absolute encoders ≤ ± 0.1 150 a 20 a 1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load 0 % 4.75 ... 30 V DC typ. 50 mA approx. 1.5 W Gray code, binary code adjustable SSI up to 16 Bit up to 16 Bit up to 32 Bit 0.1 ... 2 MBit/s < 100 μs RS 422 Selection of counting direction (cw/ccw) 4.75 V ... U_B (cw descending) 0 ... 2 V or unconnected (cw ascending) < 6 mA < 250 ms zero-set (PRESET 1) with falling edge 4.75 V ... U_B 0 ... 2 V < 6 mA ≥ 1.1 s M12 connector, 8-pin or M23 connector, 12-pin Ø7 mm, 6 x 2 x 0.14 mm², 1 m (cable length, see order code) DIN EN 60529, IP65 or IP67 DIN EN 60068-2-3, no moisture condensation EN 61000-6-4:2007 EN 61000-6-2:2005 DIN EN 60068-2-27, 200 g, 6 ms DIN EN 60068-2-6, 30 g, 10 ... 1000 Hz -40 ... 85 °C (-40 ... 185 °F) -40 ... 85 °C (-40 ... 185 °F) 98 % , no moisture condensation nickel-plated steel aluminum Stainless steel approx. 300 g , with cable max. 12000 min -1 50 gcm²

 \pm 0.9 ° static: \pm 0.3 mm, dynamic: \pm 0.1 mm static: \pm 0.5 mm, dynamic: \pm 0.2 mm

< 5 Ncm

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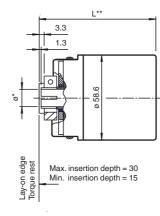
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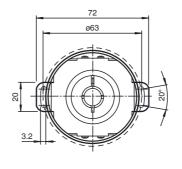
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Dimensions



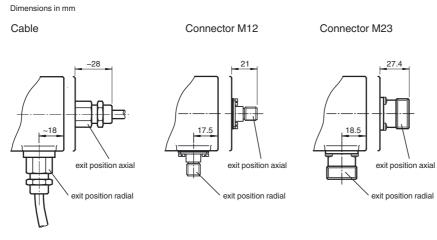




* See type code ** Singletum design with axial output: L = 60.6 All other designs: L = 76.6 mm



Connections



Electrical connection

Signal	Cable, 12-core	Connector M12, 8-pin	Connector M23, 12-pin, cw	Connector M23, 12-pin, ccw	Explanation
GND (encod- er)	White	1	1	1	Power supply
U _b (encoder)	Brown	2	2	8	Power supply
Clock (+)	Green	3	3	3	Positive cycle line
Clock (-)	Yellow	4	4	11	Negative cycle line
Data (+)	Grey	5	5	2	Positive transmission data
Data (-)	Pink	6	6	10	Negative transmission data
Reserved	Black		7	12	Not wired, reserved
V/R	Red	8	8	5	Input for selection of counting di- rection
PRESET 1	Blue	7	9	9	zero-setting input
Reserved	Violet		10	4	Not wired, reserved
Reserved	Grey/Pink		11	6	Not wired, reserved
Reserved	Red/Blue		12	7	Not wired, reserved
			$\begin{array}{c} 8 \\ 12 \\ 7 \\ 6 \\ 5 \\ 11 \\ 4 \end{array}$	$\begin{array}{c} 9 \\ 10 \\ 2 \\ 3 \\ 4 \\ 11 \\ 5 \end{array}$	

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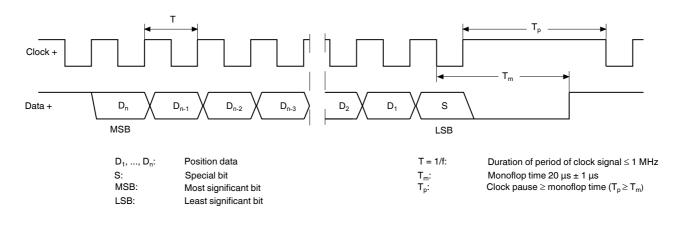


Description

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

SSI signal course Standard



SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D_n) and special bit (S)) is stored in the encoder is introduced.±
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T_m has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T_n has expired.
- After the clock sequence is complete, the monoflop time T_m is triggered with the last falling pulse edge.
- The monoflop time T_m determines the lowest transmission frequency.

SSI output format ring slide operation (multiple transmission)

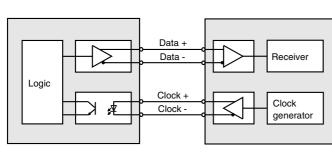
- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, n bits are transferred per data word in standard format. The value n equals the total resolution of the encoder. As an example: a multiturn encoder with a resolution of 8192 steps/revolution (13 bit) and a max. number of 4096 revolutions (12 bit) has a total resolution of n = 25 bit.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first position transmission, the n+1 pulse controls data repetition. If the n+1 pulse follows after an amount of time greater than the monoflop time T_m, a new current data word will be transmitted with the following pulses.



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If the pulse line is exchanged, the data word is generated offset.

Block diagram



Rotary encoder

Interface electronics

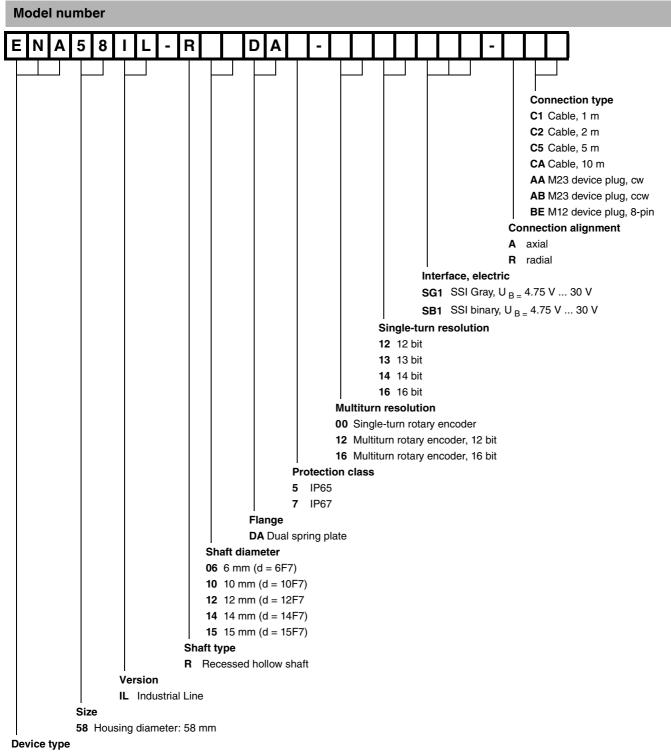
Line length

ſ	Line length in m	Baudrate in kHz
	< 50	< 400
	< 100	< 300
	< 200	< 200
Ī	< 400	< 100

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ENA Absolute rotary encoder

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