

Model Number

DSS58

Features

- Industrial standard housing Ø58 mm
- 16 Bit singleturn
- Galvanically isolated DeviceNet interface
- · Recessed hollow shaft

Description

In addition to the CANopen, PROFIBUS and AS-Interface rotary encoders, we have broadened our product line of bus-capable absolute encoders with the DSS58 for DeviceNet.

Absolute encoders deliver an absolute step value for each angle setting. All these values are represented by code samples of one or more code disks. The code disks are screened by an infrared LED and the bit obtained sample is detected by means of an optical array. Its signals are electronically amplified and are forwarded on to the interface for processing.

The absolute encoder has a maximum basic resolution of 65536 steps per revolution (16 Bits).

The integrated CAN bus interface of the absolute encoder supports all DeviceNet functions. The following operating modes can be programmed, and can selectively be turned on or off:

- Polled mode
- Cyclic mode
- Change of state mode

The absolute encoder is mounted directly onto the application shaft, without any coupling. Rotation of the absolute encoder is prevented by a torque rest.

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General specifications Detection type Device type Functional safety related parameters MTTF_d Mission Time (T_M)

L_{10h} Diagnostic Coverage (DC) Electrical specifications

Operating voltage U_B No-load supply current I₀

Linearity Output code Code course (counting direction)

Interface

Interface type Resolution Single turn Overall resolution Transfer rate

Connection Terminal compartment

Standard conformity Degree of protection

Climatic testing Emitted interference Noise immunity Shock resistance

Vibration resistance Ambient conditions Operating temperature

Storage temperature Mechanical specifications Material Combination 1

Combination 2 (Inox)

Mass

Rotational speed Moment of inertia Starting torque Tightening torque, fastening screws Shaft load Angle offset Axial offset Radial offset photoelectric sampling Singleturn absolute encoder

80 a 20 a

1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load 0 %

10 ... 30 V DC max. 230 mA at 10 V DC max. 100 mA at 24 V DC ± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit binary code cw ascending (clockwise rotation, code course ascending) cw descending (clockwise rotation, code course descending)

DeviceNet

up to 16 Bit up to 16 Bit max. 0.5 MBit/s

in removable housing cover

DIN EN 60529, IP65 IP66 (with shaft seal) DIN EN 60068-2-30 , no moisture condensation DIN EN 61000-6-4 DIN EN 61000-6-2 DIN EN 60068-2-27, 100 g, 6 ms DIN EN 60068-2-6, 20 g, 10 ... 2000 Hz

-40 ... 85 °C (-40 ... 185 °F) -40 ... 85 °C (-40 ... 185 °F)

housing: powder coated aluminum flange: aluminum shaft: stainless steel housing: stainless steel flange: stainless steel shaft: stainless steel approx. 550 g (combination 1) approx. 1100 g (combination 2) max. 12000 min $^{-1}$ 30 gcm² \leq 3 Ncm (version without shaft seal) max. 1.8 Nm

± 0.9 ° static: ± 0.3 mm, dynamic: ± 0.1 mm static: ± 0.5 mm, dynamic: ± 0.2 mm

Approvals and certificates

UL approval

cULus Listed, General Purpose, Class 2 Power Source

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end

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Dimensions



Electrical connection

Terminal	Cable	M12 x 1 Connector	Explanation
\perp	-	-	Ground connection for power supply
(+)	Red	2	Power supply
(-)	Black	3	Power supply
CG	-	1	CAN ground
CL	Blue	5	CAN low
СН	White	4	CAN high
CG	-	-	CAN ground
CL	Blue	-	CAN low
СН	White	-	CAN high





Indicating and operating elements



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Adjusting the participant address

The participant address can be adjusted with the rotary switches. The address can be defined between 1 and 63, and may only be assigned once.

Adjusting the termination resistor

The terminating resistor R_T (121 Ω) can be connected to the circuit by means of the switch:

ON participant X



x10

Baud rate adjustment

Baud rate [kBit/s]	Switch position
125	0
250	1
500	2
125	3
reserved	4 9

LED-indicators

LED red	LED green	Meaning
off	off	No voltage supply
off	on	Encoder ready, boot-up message not transmitted, yet. Possible reasons:
		- no further participant present
		- wrong baud rate
		- encoder in prepared status
flashing	on	Boot-up message transmitted, Device configuration possible.
on	on	Normal operation mode, encoder in operational status.



3

Mode	Explanation
Polled mode	The connected host requests the current actual position value via a telegram. The absolute encoder reads in the current position, calculates all parameters that may have been set and then sends back the actual process value.
Cyclic mode	The absolute encoder sends the current process value depending on a programmable timer. This can cause the bus load to be reduced since the member on the network only sends a message after a specific amount of time without a prompt from the master.
Change of state mode	The absolute encoder monitors the current process value and transfers the current value by itself if there is any change in the value. This can cause the bus load to be reduced, since the member on the network only sends a message if there has been a change.

Programmable rotary encoder parameters

Parameter	Explanation	
Operating parameter	The direction of rotation (complement) can be specified by parameter as the operating parameter. This para- meter determines the direction of rotation in which the output code will be rising or descending.	
Resolution per revolution	The "Resolution" parameter is used to program the rotary encoder so that a desired number of steps can be implemented in reference to a revolution.	
Preset value	The preset value is the desired position value that must be achieved for a specific physical setting of the axis. The preset value parameter is used to set the actual position value to the desired actual process value.	

Order code



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