









Model Number

AVM58-0

Features

- **Industrial standard** housing Ø58 mm
- 30 Bit multiturn
- Data transfer up to 2 MBaud
- Optically isolated RS 422 interface
- Servo or clamping flange
- **Zero-set function**

Description

This multiturn absolute encoder with modern fast technology transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface). The maximum resolution of the AVM58 is maximum 65536 steps per revolution at 16384 revolutions.

The devices of the AVM58 series are equipped with a microcontroller.

The control module sends a clock bundle to the absolute encoder to obtain the position data. The rotary encoder then sends the position data synchronous to the cycles of the control module. It is possible to select the following items with function inputs

- the counting direction and
- the zero-set function (preset value)

This multiturn absolute encoder is available in a clamping flange design with a shaft diameter of 10 mm x 20 mm, or in a servo flange design with a shaft diameter of 6 mm x 10 mm. The electrical connection is made by a 12-pin round plug connector. It is also possible to obtain a version with a 1 m cable connector.

Technical data

General specifications

Detection type photoelectric sampling Device type Multiturn absolute encoder

Functional safety related parameters

MTTF_d 150 a Mission Time (T_M) 20 a

1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load L_{10h} Diagnostic Coverage (DC)

Electrical specifications

Operating voltage U_R 4.5 ... 30 V DC No-load supply current I₀ max. 180 mA

± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit Linearity Output code

Gray code, binary code

cw descending (clockwise rotation, code course Code course (counting direction)

descending)

SSI

Interface type Monoflop time

Interface

 $20 \pm 10 \,\mu s$ Resolution Single turn up to 16 Bit Multiturn 14 Bit Overall resolution up to 30 Bit

Transfer rate 0.1 ... 2 MBit/s Voltage drop U_B - 2.5 V Standard conformity RS 422

Input 1 Selection of counting direction (cw/ccw) Input type

Signal voltage High

4.5 ... 30 V 0 ... 2 V Input current < 6 mA Switch-on delay < 10 ms

Input 2

Input type zero-set (PRESET 1)

Signal voltage Hiah 4.5 ... 30 V 0 ... 2 V Iow Input current < 6 mA

Signal duration ≥ 100 ms Switch-on delay < 10 ms

Connection

type 9416 (M23), 12-pin, type 9416L (M23), 12-pin Connector

Cable Ø7 mm, 6 x 2 x 0.14 mm², 1 m

Standard conformity Degree of protection

DIN EN 60529, IP65 Climatic testing DIN EN 60068-2-3, no moisture condensation

DIN FN 61000-6-4 Emitted interference Noise immunity DIN EN 61000-6-2 Shock resistance DIN EN 60068-2-27, 100 g, 6 ms Vibration resistance DIN EN 60068-2-6, 20 g, 10 ... 2000 Hz

Ambient conditions -40 ... 85 °C (-40 ... 185 °F) Operating temperature

Storage temperature -40 ... 85 °C (-40 ... 185 °F)

Mechanical specifications

Combination 1 housing: powder coated aluminum flange: aluminum

shaft: stainless steel Combination 2 (Inox) housing: stainless steel flange: stainless steel

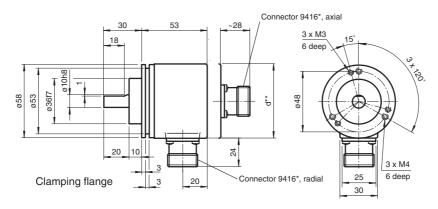
shaft: stainless steel Mass approx. 460 g (combination 1) approx. 800 g (combination 2)

max. 12000 min ⁻¹ Rotational speed Moment of inertia 50 gcm² Starting torque < 5 Ncm

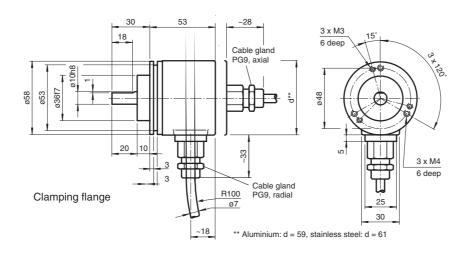
Shaft load Axial 40 N Radial 110 N

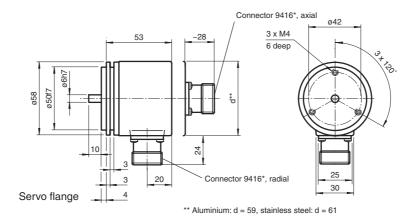
Approvals and certificates

UL approval cULus Listed, General Purpose, Class 2 Power Source

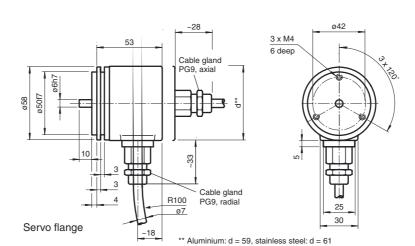


** Aluminium: d = 59, stainless steel: d = 61





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Electrical connection

Signal	Cable Ø7 mm, 12-core	Connector 9416, 12-pin	Connector 9416L, 12-pin	Explanation
GND (encoder)	White	1	1	Power supply
U _b (encoder)	Brown	2	8	Power supply
Clock (+)	Green	3	3	Positive cycle line
Clock (-)	Yellow	4	11	Negative cycle line
Data (+)	Grey	5	2	Positive transmission data
Data (-)	Pink	6	10	Negative transmission data
Reserved	Black	7	12	Not wired, reserved
V/R	Red	8	5	Input for selection of counting direction
PRESET 1	Blue	9	9	zero-setting input
Reserved	Violet	10	4	Not wired, reserved
Reserved	Grey/Pink	11	6	Not wired, reserved
Reserved	Red/Blue	12	7	Not wired, reserved
		9 8 10 7 12 6	9 1 12 2 10 3	

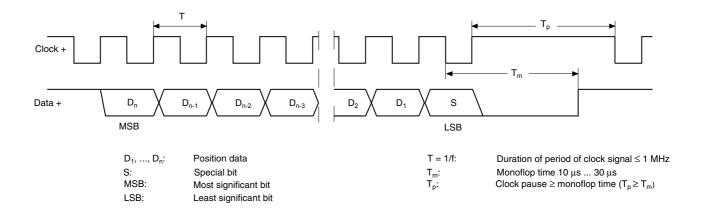
FPEPPERL+FUCHS

Description

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

SSI signal course Standard



SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D_n) and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T_m has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T_n has expired.
- After the clock sequence is complete, the monoflop time T_m is triggered with the last falling pulse edge.
- The monoflop time T_m determines the lowest transmission frequency.

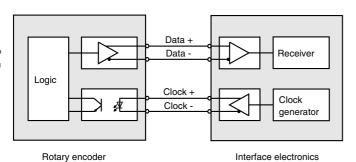
SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, 25 bits are transferred per data word in standard format.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first transmission, the 26th pulse controls data repetition. If the 26th pulse follows after an amount of time greater than the monoflop time
 T_m, a new current data word will be transmitted with the following pulses.



If the pulse line is exchanged, the data word is generated offset. Ring slide operation is possible up to max. 13 bits.

Block diagram



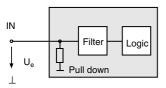
Line length

Line length in m	Baudrate in kHz	
< 50	< 400	
< 100	< 300	
< 200	< 200	
< 400	< 100	

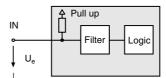
Inputs

The selection of the counting direction input (V/R) is activated with 0-level. The zero-set input (PRESET 1) is activated with 1-level.

zero-set input (PRESET 1)



Input for selection of counting direction (V/R)



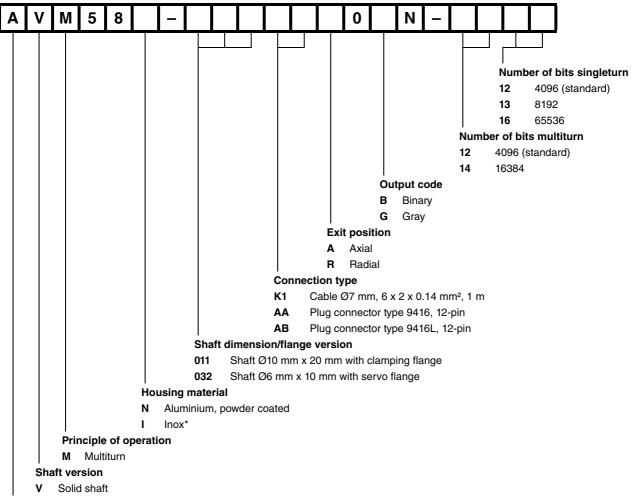
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Accessories

For type	Accessories	Name/defining feature	Order code
		D1: Ø10 mm, D2: Ø10 mm	9401
	O a servicio a servici	D1: Ø10 mm, D2: Ø10 mm	9404
	Couplings	D1: Ø10 mm, D2: Ø10 mm	9409
		D1: Ø10 mm, D2: Ø10 mm	KW
		Plastic	9101, 10
	Measurement wheels with cir- cumference of 500 mm	Pimpled rubber	9102, 10
AVM58*-011		Knurled aluminium	9103, 10
AVIVIOO -UTI		Knurled plastic	9112, 10
	Measurement wheels with cir-	Plastic	9108, 10
		Pimpled rubber	9109, 10
	cumference of 200 mm	Knurled aluminium	9110, 10
		Knurled plastic	9113, 10
	Mounting aids	Mounting bracket	9203
	Mounting aids	Mounting bracket	9213
		D1: Ø6 mm, D2: Ø6 mm	9401
		D1: Ø6 mm, D2: Ø6 mm	9402
	Couplings	D1: Ø6 mm, D2: Ø6 mm	9404
AVM58*-032		D1: Ø6 mm, D2: Ø6 mm	9409
		D1: Ø6 mm, D2: Ø6 mm	KW
	Mounting side	Mounting bracket and set	9300 and 9311-3
	Mounting aids	Eccentric clamping elements	9310-3
ΔII	Connectors	Cable socket	9416
All	Connectors	Cable socket	9416L

For additional information on the accessories, please see the "Accessories" section.

Order code



Data format

SSI (Synchronous Serial Interface)

*Housing material I only available with axial exit position.