## (8) 5CHMERSRL

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## 1. About this document

### 1.1 Function

This operating instructions manual provides all the information you need for the mounting, set-up and commissioning to ensure the safe operation and disassembly of the safety switchgear. The operating instructions must be available in a legible condition and a complete version in the vicinity of the device.

### 1.2 Target group: authorised qualified personnel

All operations described in this operating instructions manual must be carried out by trained specialist personnel, authorised by the plant operator only.

Please make sure that you have read and understood these operating instructions and that you know all applicable legislations regarding occupational safety and accident prevention prior to installation and putting the component into operation.

The machine builder must carefully select the harmonised standards to be complied with as well as other technical specifications for the selection, mounting and integration of the components.

### 1.3 Explanation of the symbols used

```
Information, hint, note:
This symbol is used for identifying useful additional information.
```

Caution:Failure to comply with this warning notice could lead to failures or malfunctions.
Warning:Failure to comply with this warning notice could lead to physical injury and/or damage to the machine.

### 1.4 Appropriate use

The products described in these operating instructions are developed to execute safety-related functions as part of an entire plant or machine. It is the responsibility of the manufacturer of a machine or plant to ensure the correct functionality of the entire machinery or plant.

The safety switchgear must be exclusively used in accordance with the versions listed below or for the applications authorised by the manufacturer. Detailed information regarding the range of applications can be found in the chapter "Product description".

### 1.5 General safety instructions

The user must observe the safety instructions in this operating instructions manual, labelled with the caution or warning symbol above, the country-specific installation standards as well as all prevailing safety regulations and accident prevention rules.

Further technical information can be found in the Schmersal catalogues or in the online catalogue on the Internet: www.schmersal.net.

The information contained in this operating instructions manual is provided without liability and is subject to technical modifications.

## 1 <br> The entire concept of the control system, in which the safety component is integrated, must be validated to EN ISO 13849-2.

There are no residual risks, provided that the safety instructions as well as the instructions regarding mounting, commissioning, operation and maintenance are observed.

### 1.6 Warning about misuse



In case of inadequate or improper use or manipulations of the safety switchgear, personal hazards or damage to machinery or plant components cannot be excluded. The relevant requirements of the standard EN 1088 must be observed.

### 1.7 Exclusion of liability

We shall accept no liability for damages and malfunctions resulting from defective mounting or failure to comply with this operating instructions manual. The manufacturer shall accept no liability for damages resulting from the use of unauthorised spare parts or accessories

For safety reasons, invasive work on the device as well as arbitrary repairs, conversions and modifications to the device are strictly forbidden; the manufacturer shall accept no liability for damages resulting from such invasive work, arbitrary repairs, conversions and/or modifications to the device.

## 2. Product description

### 2.1 Ordering code

This operating instructions manual applies to the following types:

| MZM $\mathbf{1 2 0}$ (1) ST2-(2)RE-A |  |  |
| :--- | :--- | :--- |
| No. | Option | Description |
| (1) | B | Actuator monitored <br> combined actuator detection and locking function |
| (2) | BM | 1P2PW2 |
| 1 p-type diagnostic output and 2 p-type safety |  |  |
| outputs, combined diagnostic signal: |  |  |
| safety guard is closed and can be locked |  |  |
| serial diagnostic output and 2 p-type safety outputs |  |  |

MZM 120-B1.1 actuator

Only if the information described in this operating instructions manual are realised correctly, the safety function and therefore the compliance with the Machinery Directive is maintained.

### 2.2 Special versions

For special versions, which are not listed in the order code below 2.1, these specifications apply accordingly, provided that they correspond to the standard version

### 2.3 Comprehensive quality insurance to 2006/42/EC

Schmersal is a certified company to appendix X of the Machinery Directive. As a result, Schmersal is entitled to autonomously conduct the conformity assessment procedure for the products listed in Appendix IV of the MD without involving a notified body. The EC prototype test certificates are available upon request or can be downloaded from the Internet at www.schmersal.com

### 2.4 Destination and use

The MZM 120 is designed for application in safety circuits and is used for monitoring the position of movable separating safety guards. A door detection sensor monitors the closed condition of the safety guard. The latching force is activated by the detection of the actuator when the safety guard is closed

The safety function consists of safely switching off the safety outputs when the safety guard is opened and maintaining the safe switched off condition of the safety outputs for as long as the safety guard is open. The opening of the safety guard is detected by the safety sensors. The magnetic force monitoring detects when the latching force drops below a defined latching force.

The MZM 120 distinguishes between a low holding force, which prevents the safety guard from inadvertedly bursting open and a latching force $F$, which prevent inadvertent interventions in the machine.

## Series-wiring

Series-wiring can be set up. The response and risk times are not altered by wiring in series. The number of components is only limited by the external cable protection according to the technical data and the line loss. Up to 31 components can be wired in series.

In devices with serial diagnostics function (ordering suffix -SD), the serial diagnostics connections are wired in series and connected to a SD-Gateway for evaluation purposes

Wiring examples for series-wiring, refer to appendix


The user must evaluate and design the safety chain in accordance with the relevant standards and the required safety level. If multiple safety switchgear are involved in the same safety function, the PFH values of the individual components must be added.

### 2.5 Technical data

Standards: IEC 60947-5-3, EN ISO 13849-1, IEC 61508

Material of the housings:
Plastic, glass-fibre reinforced thermoplastic, self-extinguishing
Working principle: inductive

Recommended actuator:
MZM 120-B1.
Switching distances to IEC 60947-5-3:

- assured switching distance $\mathrm{s}_{\mathrm{a}}$

0 mm

- assured switch-off distance $\mathrm{S}_{\mathrm{ar}}$ : 1 mm

Protection class: II 回
Switch-on time ED: 100 \%
Response time: $<150 \mathrm{~ms}$
Duration of risk: $<150 \mathrm{~ms}$

Time to readiness: $<4000 \mathrm{~ms}$
Series-wiring:
up to 31 devices
Length of the sensor chain: max. 200 m
Cable length and cable section alter the voltage drop depending on the output current

## Mechanical data:

| Execution of the electrical connection: | M12 connector plug, 8 poles |
| :---: | :---: |
| Mechanical life: | $\geq 1.000 .000$ operations |
| Notice - Mechanical life: | for safety guards $\leq 5 \mathrm{~kg}$; actuating speed $\leq 0.5 \mathrm{~m} / \mathrm{s}$ |
| Resistance to shock: | $30 \mathrm{~g} / 11 \mathrm{~ms}$ |
| Resistance to vibration: | $\begin{array}{r} 10 \ldots 150 \mathrm{~Hz}, \\ \text { amplitude } 0,35 \mathrm{~mm} / 5 \mathrm{~g} \end{array}$ |
| Electrically ajdustable latching force (RE): | $30 \mathrm{~N} . . .80 \mathrm{~N}$ |
| Holding force $\mathrm{F}_{\text {max }}$ : | 500 N |
| Holding force F guaranteed: | 300 N |
| Tightening torque for device fixing: | 8 N |
| Ambient conditions: |  |
| Ambient temperature: | $-25^{\circ} \mathrm{C} \ldots+55^{\circ} \mathrm{C}$ |
| Storage and transport temperature: | $-25^{\circ} \mathrm{C} \ldots+85^{\circ} \mathrm{C}$ |
| Relative humidity: | 30\% ... 95\% |
| - no condensation |  |
| - non-icing |  |
| Protection class: | IP67 / IP69K |
| - Rated impulse withstand voltage $\mathrm{U}_{\text {imp }}$ : | 0,8 kV |
| - Overvoltage category: |  |
| - Degree of pollution: |  |

## Electrical data:

Supply voltage $U_{B}$ (stabilised PELV units): $\quad 20,4 \mathrm{~V}$ DC... $26,4 \mathrm{~V}$ DC
Operating current: max. 0.6 A

- Note
plus current through the safety outputs
Switching frequency: 1 Hz
Rated operating voltage $U_{e}: \quad 24$ VDC
Rated insulation voltage $U_{i}: \quad 32$ VDC
Rated operating current $\mathrm{I}_{\mathrm{e}}$ : 1 A
No-load current $\mathrm{I}_{0}$ : max. 0.6 A
Required short-circuit current: 100 A
Device fuse rating:

Electrical data - Safety inputs:

| Safety inputs: | X1 and X 2 (PELV unit) |
| :--- | ---: |
| Voltage range: | $-3 \mathrm{~V} \ldots 5 \mathrm{~V}$ (Low) |
|  | $15 \mathrm{~V} \ldots 30 \mathrm{~V}$ (High), |
|  | typically 4 mA at 24 V |

Electrical data - Safety outputs:
Safety outputs: Y1 and Y2, NO function,

| Fuse rating: | short-circuit proof, p-type |
| :--- | :--- |
| Voltage drop: |  |

Leakage current $\mathrm{I}_{\mathrm{r}}: \quad \leq 0.5 \mathrm{~mA}$
Operating current $\mathrm{I}_{\mathrm{e} 1}$ : max. 0.25 A
Minimum operating current $\mathrm{I}_{\mathrm{m}}$ : 0.5 mA
Utilisation category: DC-13

Electrical data - Diagnostic output:

| Fuse rating: | short-circuit proof, $p$-type |
| :--- | :--- |
| Voltage drop: | $<4 \mathrm{~V}$ |

Operating current $\mathrm{I}_{\mathrm{e} 2}$ : max. 0.05 A
Utilisation category:
Wiring capacitance for serial diagnostics: max. 50 nF

Electrical data - Magnet control IN:

| Voltage range: | $-3 \mathrm{~V} \ldots 5 \mathrm{~V}$ (Low) <br> $15 \mathrm{~V} \ldots 30 \mathrm{~V}$ (High); <br> typically 4 mA bei 24 V, <br> dynamic 20 mA |
| :--- | ---: |
| LED switching conditions display: |  |
| - Supply voltage $\mathrm{U}_{\mathrm{B}}:$ | green LED |
| - Operating condition: | Yellow LED |
| Error / functional defect: | red LED's |
| Dimensions: | $40 \times 179 \times 40 \mathrm{~mm}$ |

(UL) Us Use isolated power supply only. If the cable and connector assembly is not listed for Type 12 or higher, then the device shall be used in a Type 1 environment only.

### 2.6 Safety classification

Standards:
EN ISO 13849-1, IEC 61508,
IEC 60947-5-3
PL.
up to e
Control category: up to 4

PFH value:
$3 \times 10^{-9} / \mathrm{h}$
SIL: suitable for SIL 3 applications
Service life:
20 years
Classification:
PDF-M

## 3. Mounting

### 3.1 General mounting instructions

For fitting the MZM 120 safety switch and the actuator, two mounting holes for M6 screws with washers (washers included in delivery) are provided.

The safety switch must be used as end stop.

For a safe operation of the system, the angle between the safety switch and the actuator compulsory must be $\leq 2^{\circ}$. After fitting, the unused fixing holes must be covered by means of the provided blanking plugs. To remove these plugs, if required, exert pressure on the topmost extremity (when the connector is fitted downwards) or press on the righthand side of the plugs on the anchorage plate of the actuator. When fitting the actuator when the safety switch is used for the protection of man, refer to the "Safety instructions".

Safety sensor and actuator must be permanently fitted to the safety guards and protected against displacement by suitable measures (tamperproof screws, gluing, drilling, pinning).

At an ambient temperature of $\geq 50^{\circ} \mathrm{C}$, the MZM 120 must be fitted so that it is protected against unintentional contact with persons. Please observe the remarks of the standards EN ISO 12100, EN 953 and EN 1088

The safety component must be operated in the operating direction of the latching force (refer to image).

## Axial misalignment and operating direction of the latching force



### 3.2 Dimensions

All measurements in mm .

## Safety switch



## Actuator


4. Electrical connection

### 4.1 General information for electrical connection

## The electrical connection may only be carried out by

 authorised personnel in a de-energised condition.The voltage inputs $\mathrm{A} 1, \mathrm{X} 1, \mathrm{X} 2$ and IN must have a protection agains permanent overvoltage. Therefore, the use of PELV supply units according to IEC 60204-1 is recommended.
The safety outputs can be integrated in the safety circuit of the contro system. For applications of PL e / control category 4 to EN ISO 13849-1, the safety outputs of the safety switchgear or the chain of components must be connected to a safety-monitoring module of the same category. (see wiring examples)

## Requirements for the connected safety-monitoring module:

- Dual-channel safety input, suitable for 2 p-type semi-conductor outputs


## - Test function

The safety-monitoring module must tolerate internal functional tests of the sensors with cyclic switch-off of the sensor outputs for max. 2 ms (typically $<1 \mathrm{~ms}$ ). The switch-off stage of the test cycle is temporarily reduced by an active ohmic discharge of the cable. The safetymonitoring module does not need to have a cross-wire short monitoring function, if necessary, the cross-wire short monitoring function must be disabled.

Information for the selection of suitable safety-monitoring modules can be found in the Schmersal catalogues or in the online catalogue on the Internet: www.schmersal.net.

If the safety component is wired to relays or to non-safety relevant control components, a new risk analysis must be carried out

When wiring SD devices, please observe the voltage drop on the cables and the current carrying capacity of the individual components

## 5. Operating principles and latching force adjustment

### 5.1 Mode of operation of the safety outputs

## MZM 120 B

Due to the permanent monitoring of the closed magnetic circuit, the safety outputs $\mathrm{Y} 1 / \mathrm{Y} 2$ are only enabled during the latching, when the magnetic circuit is properly closed and the latching force $F$ can also be obtained when activated. If the metal surfaces are soiled or damaged, the enabling signal is not transmitted.

The unlocking of the MZM 120 safety switch with interlocking function does not lead to a switch-off.

## MZM 120 BM

The safety outputs are enabled when the actuator is present on the safety switch and the magnet control is activated. The unlocking of the safety switch causes the safety outputs to be disabled within the duration of risk. As long as the actuator is inserted into the safety switch, the unlocked safety switch with interlocking function can be relocked. In this case, the safety outputs are re-enabled

The latching force $F$ is permanently measured and checked. In this way, soiling of the solenoid interlock can be detected. If the latching force drops below 300 N , the release signal for the safety outputs Y 1 and Y 2 is not given.

## Description of the MZM 120 latching force adjustment

The latching force of the MZM 120 can be set in 8 steps each within a range of approx. 30 N to approx. 80 N . To this end, the adjustment target MZM 100 TARGET is used directly on the fitted MZM 120.

## Adjustment of the latching force

1.) Open the safety guard and isolate the MZM 120 from the voltage supply. Either switch off the voltage supply or pull out the connector.
2.) Put the adjustment target with the active side on the identification plate of the MZM 120.
3.) Switch the voltage supply of the MZM 120 back on and wait at least 10 seconds before removing the adjustment target. The component searches for the adjustment target. When the adjustment mode is active, the safety outputs remain disabled
4.) Remove the adjustment target again from the component. The yellow LED of the MZM 120 will repeatedly flash briefly to show the currently set latching force level (e.g. 4 flashes $=4^{\text {th }}$ latching force level approx. 51 N )
5.) Put the adjustment target approx. 1 second back on the solenoid interlock with the safety guard open to gradually increase the latching force by each time one step. The number of flashes will increase accordingly.

The modified latching force can be checked directly on the safety guard. If necessary, the latching force can be increased by another step. When latching force level 8 is reached, level 1 will be activated when the adjustment target is placed back on the component.
6.) Switch off the voltage supply of the MZM 120 once more to permanently save the chosen latching force.

When the component is switched off, the adjustment mode is quit. After the voltage supply is switched back on, the MZM 120 is ready for operation.

## Latching force indication

If the voltage supply of the MZM 120 is switched on when the safety guard is open, the yellow LED will show the set latching force for 10 seconds by means of repeated brief flashes (e.g. 4 flashes $=$ $4^{\text {th }}$ latching force level approx. 50 N ).

Description of the latching force adjustment for the MZM 120-...SD with serial diagnostic function
The latching force can be set through the latching force bits 1-3 of the request bytes in 8 steps within a range of approx. 30-80 N.

## 

| 0 | 0 | 0 | 30 N |
| :--- | :--- | :--- | :--- |
| 0 | 0 | 1 | 37 N |
| 0 | 1 | 0 | 44 N |
| 0 | 1 | 1 | 51 N |
| 1 | 0 | 0 | 58 N |
| 1 | 0 | 1 | 65 N |
| 1 | 1 | 0 | 72 N |
| 1 | 1 | 1 | 80 N |

## 6. Diagnostic functions

### 6.1 Diagnostic LED's

The safety switch signals the operational state as well as errors through three coloured LED's installed at the front side of the device.

| green | Supply voltage on |
| :--- | :--- |
| red | Fault (s. Table: flash codes of the red diagnostic LED |
| yellow | Operating condition |

### 6.2 Safety switch with conventional diagnostic output

The short-circuit proof diagnostic output OUT can be used for central visualisation or control functions, e.g. in a PLC. This is not a safetyrelevant output!

## Error

Errors, which no longer guarantee the function of the safety switch with interlocking function (internal errors) cause the safety outputs to be disabled within the risk time. Any error that does not immediately affect the safe functionality of the safety switch with interlocking function (e.g. the ambient temperature too high, interference potential at a safety output, cross-wire short) will lead to a delayed shut-down (refer to table 2).

## Behaviour of the diagnostic outputs of the W variant

## Input signal magnet control

IN


Normal sequence, door was locked


Door could not be locked or fault
OUT


Legend


After fault rectification, the sensor can be reset by opening the relevant guard door.

If more than one fault is detected at the safety outputs, the component will be electronically locked and a normal fault reset will no longer be possible.
To reset this type of interlocking, the component must be isolated from the power supply after elimination of the error causes.

## Error warning

A fault has occured, which causes the safety outputs to be disabled after 30 minutes. The safety outputs initially remain enabled. This enables the shutdown of the process in a controlled manner. An error warning is deleted when the error cause is eliminated.

## Evaluation of the diagnostic outputs



Table 1: the diagnostic function of the MZM 120 safety switch with additional interlocking function
The diagnostic output OUT signals faults before the safety outputs are disabled, thus enabling a controlled shutdown.

| System condition | Solenoid control N | LED green | LED red | LED yellow | Safety outputs Y1, Y2 | Diagnostic output OUT |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Safety guard open | 0 V | On | Off | Off | 0 V | 0 V |
| Safety guard closed, actuator in, safety guard can be locked | 0 V | On | Off | Flashes | 24 V | 24 V |
| Safety guard closed and locked | 24 V | On | Off | On | 24 V | 24 V |
| Solenoid interlock cannot be locked, safety guard not correctly closed or solenoid soiled | 24 V | On | Off | Off | 0 V | 0 V |
| Error warning ${ }^{1}$, actuator in | $0 \mathrm{~V} / 24 \mathrm{~V}$ | On | flashes ${ }^{2)}$ | flashes/on | 24 V | 0 V |
| Error | $0 \mathrm{~V} / 24 \mathrm{~V}$ | On | flashes ${ }^{2)}$ | Off | 0 V | 0 V |

[^0]Table 2: flash codes red LED

| Flash codes (red) | Designation | Autonomous switch-off after | Error cause |
| :---: | :---: | :---: | :---: |
| 1 flash pulse | Error (warning) at output Y1 | 30 min | Fault in output test or voltage at output Y1, although the output is disabled. |
| 2 flash pulses | Error (warning) at output Y2 | 30 min | Fault in output test or voltage at output Y 2 , although the output is disabled. |
| 3 flash pulses | Error (warning) cross-wire short | 30 min | Cross-wire short between the output cables or fault at both outputs. After 30 minutes, voltage switch-off/on required |
| 5 flash pulses | Actuator fault | 0 min | incorrect or defective actuator |
| 6 flash pulses | Latching force fault | 0 min | Latching force has dropped below 300 N (e.g. actuator misalignment) |
| 10 flash pulses | Magnet temperature too high | 0 min | The magnet is too hot: $\mathrm{T}>70^{\circ} \mathrm{C}$. |
| continuous red signal | internal error | 0 min |  |
| 6.3 Safety switch with serial diagnostic function Safety switches with serial diagnostic cable have a serial input and output cable instead of the conventional diagnostic output. |  |  | If more than one fault is detected at the safety outputs, the component will be electronically locked and a normal fault reset will no longer be possible. <br> To reset this type of interlocking, the component must be isolated from the power supply after elimination of the error causes. | Gateway SD-I-DP-V0-2 or the Universal-Gateway SD-I-U-... are used. This SD-Gateway is integrated as slave in an existing field bus system. In this way, the diagnostic signals can be evaluated by means of a PLC. The necessary integration for the integration of the SD-Gateway is available for download at www.schmersal.net.

The response data and the diagnostic data are automatically and permanently written in an input byte of the PLC for each safety switch in the series-wired chain. The request data for each safety switch are transmitted to the component through an output byte of the PLC.

In case of a communication error between the field bus gateway and the safety switch, the switching condition of the interlocking device is maintained.

## Error

A fault has occured, which causes the safety outputs to be disabled. The fault is reset, when the cause is eliminated and bit 7 of the request byte changes from 1 to 0 or the safety guard is opened. Faults at the safety outputs are only deleted upon the next release, as the fault rectification cannot be detected sooner.

## Error warning

A fault has occured, which causes the safety outputs to be disabled after 30 minutes. The safety outputs initially remain enabled.

## Diagnostic error (warning)

If an error (warning) is signalled in the response byte, detailed fault information can be read out.

> Detailed information about the use of the serial diagnostics can be found in the operating instructions of the PROFIBUSGateway SD-I-DP-V0-2 and the Universal-Gateway SD-I-U-....

## Accessories for the series-wiring

To provide for a comfortable wiring and series-wiring of SD components, the connectors and the SD-2V-F-SK SD junction boxes (variant for the field in closed enclosure) and SD-2V-S-SK (variant for DIN rail mounting in the control cabinet) are available as accessory.

Table 3: I/O data and diagnostic data

| Bit $n^{\circ}$ | Request byte | Response byte | Diagnostic error warning | Diagnostic error |
| :--- | :--- | :--- | :--- | :--- |
| Bit 0: | Magnet in, <br> error reset | Safety output activated | Error output Y1 | Error output Y1 |
| Bit 1: | Latching force bit | Actuator detected | Error output Y2 | Error output Y2 |
| Bit 2: | Latching force bit | Solenoid interlock locked | Cross-wire short | Cross-wire short |
| Bit 3: | Latching force bit | --- | Magnet temperature too high | Magnet temperature too high |
| Bit 4: | --- | Input condition X1 and X2 | Locking blocked or F < 300 N | incorrect or defective actuator |
| Bit 5: | --- | Internal device error | Internal device error |  |
| Bit 6: | --- | Communication error between the field bus <br> Gateway and the solenoid interlock | --- |  |
| Bit 7: | Error reset | Error (enabling path switched off) | Operating voltage too low | Operating voltage too low |

The described condition is reached, when Bit $=1$

Table 4: Function of the visual diagnostic LED`s, the serial status signals and the safety outputs by means of an example

| System condition | LED |  |  | Safety outputs Y1, Y2 | Response byte bit $\mathrm{n}^{\circ}$ : |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | green | red | yellow |  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Safety guard open | On | Off | Off | 0 V | 0 | 0 | 0 | X | 0 | 0 | 0 | 0 |
| Safety guard closed, actuator in, safety guard can be locked | On | Off | Flashes | 24 V | 0 | 0 | 0 | 1 | 0 | 0 | 1 | 0 |
| Safety guard closed and locked | On | Off | On | 24 V | 0 | 0 | 0 | 1 | 0 | 1 | 1 | 1 |
| Solenoid interlock cannot be locked, safety guard not correctly closed or solenoid soiled | On | Off | Flashes | 0 V | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 |
| Error warning ${ }^{1}$, actuator in | On | flashes $^{2}$ | On | 24 V | 0 | 1 | 0 | 1 | 0 | X | 1 | 1 |
| Error | On | flashes ${ }^{2}$ | Off | 0 V | 1 | 0 | 0 | X | 0 | X | X | 0 |

${ }^{1)}$ after $30 \mathrm{~min}->$ fault
${ }^{2)}$ refer to flash code

## 7. Set-up and maintenance

### 7.1 Functional testing

The safety function of the safety components must be tested. The following conditions must be previously checked and met:

1. Check max. axial misalignment of actuator and safety switch
2. Check max. angular misalignment (see "Mounting" part)
3. Check the integrity of the cable entry and connections
4. Check the switch enclosure for damage
5. Remove particles of dust and soiling

### 7.2 Maintenance

In the case of correct installation and adequate use, the safety component features maintenance-free functionality. We recommend a regular visual inspection and functional test, including the following steps:

- Check the fixing of the safety switch and the actuator
- Check max. axial misalignment of actuator and safety switch
- Check max. angular misalignment (see "Mounting" part)
- Check the integrity of the cable entry and connections
- Check the switch enclosure for damages
- Remove soiling

Damaged or defective components must be replaced.

## 8. Disassembly and disposal

### 8.1 Disassembly

The safety switchgear must be disassembled in a de-energised condition only.

### 8.2 Disposal

The safety switchgear must be disposed of in an appropriate manner in accordance with the national prescriptions and legislations.

## 9. Appendix

### 9.1 Wiring examples

The application examples shown are suggestions. They however do not release the user from carefully checking whether the switchgear and its set-up are suitable for the individual application

Wiring example 1: Series-wiring of the MZM 120 safety switch with diagnostic output
The voltage is supplied at both safety inputs of the terminal safety component of the chain (considered from the safety-monitoring module).
The safety outputs of the first safety component are wired to the safety-monitoring module.

$\begin{array}{lllllll}5 & 2 & 1 & 748 \\ 4\end{array}$



| 5 | 2 | 6 | 1 | 3 | 7 | 4 | 8 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 4 |  |  |  |  |  |  |  |




## Wiring example 2: Series-wiring of the MZM 120 safety switch with serial diagnostic function

The safety outputs of the first safety component are wired to the safety-monitoring module. The serial Diagnostic Gateway is connected to the serial diagnostic input of the first safety component.


### 9.2 Wiring configuration and connector accessories

Function safety switchgear

|  | with conventional <br> diagnostic output | with serial diag- <br> nostic function |  |
| :---: | :---: | :---: | :---: |
| A1 | $\mathrm{U}_{\mathrm{e}}$ |  | 1 |
| X1 | Safety input 1 |  | 2 |
| A2 | GND |  | 3 |
| Y1 | Safety output 1 |  | 4 |
| OUT | Diagnostic output | SD output | 5 |
| X2 | Safety input 2 |  | 6 |
| Y2 | Safety output 2 |  | 7 |
| IN | Solenoid control | SD input | 8 |

## Connector plug

 ST2 M12, 8-pole

Connecting cables with female connector IP67, M12, 8-pole - $8 \times 0.23 \mathrm{~mm}^{2}$

| Cable length | Part number |
| :--- | :--- |
| 2.5 m | 101209963 |
| 5.0 m | 101209964 |
| 10.0 m | 101209960 |

Connecting cables with female connector
IP69K, M12, 8-pole - $8 \times 0.21 \mathrm{~mm}^{2}$

| Cable length | Part number |
| :--- | :--- |
| 5.0 m | 101210560 |
| 5.0 m | 101210561 (angled) |

9.3 EC Declaration of conformity

|  | EC Declaration of conf | S 5CHmERS <br> y |
| :---: | :---: | :---: |
|  | Translation of the original declaration of conformity | K.A. Schmersal GmbH Industrielle Sicherheitsschaltsysteme Möddinghofe 30, 42279 Wuppertal Germany Internet: www.schmersal.com |
|  | We hereby certify that the hereafter describ construction conform to the applicable Eu | ty components both in its basic design and Directives. |
|  | Name of the safety component: | MZM 120 |
|  | Type: | Refer to ordering code |
|  | Description of the safety component: | Safety switch with interlocking function |
|  | Harmonised EC-Directives: | 2006/42/EC - EC-Machinery Directive 2004/108/EC - EMC-Directive |
|  | Person authorized for the compilation of the technical documentation: | Ulrich Loss Möddinghofe 30 42279 Wuppertal |
|  | Notified body, which approved the full quality assurance system, referred to in Appendix X, 2006/42/EC: | TÜV Rheinland Industrie Service GmbH Alboinstr. 56 12103 Berlin ID n ${ }^{\circ}: 0035$ |
| $\begin{aligned} & \underset{U}{N} \\ & \stackrel{N}{N} \\ & N \\ & \sum_{N}^{N} \end{aligned}$ | Place and date of issue: | Wuppertal, November 29, 2011 |
|  |  | Authorised signature <br> Philip Schmersal <br> Managing Director |
| 1 | The currently valid declaration of conformity can be downloaded from the internet at www.schmersal.net. |  |

## K. A. Schmersal GmbH

Industrielle Sicherheitsschaltsysteme
Möddinghofe 30, D-42279 Wuppertal
Postfach 2402 63, D-42232 Wuppertal
Phone: $\quad+49-(0) 2$ 02-6474-0
Telefax +49-(0)202-64 74-100
E-Mail: info@schmersal.com
Internet: http://www.schmersal.com


[^0]:    ${ }^{1)}$ after $30 \mathrm{~min}->$ fault
    ${ }^{2)}$ refer to flash code

