



Absolute encoders ARS60 SSI/Parallel

ARS60-F1A02048



Model Name > [ARS60-F1A02048](#)
Part No. > [1033822](#)



Illustration may differ

At a glance

- Absolute singleturn encoder
- Resolution: up to 15 bits (32,768 increments)
- Electrical interface: SSI with gray code type or gray capped
- Electrical interface: Parallel with gray, gray capped, binary, BCD code type
- Zero-set function
- Mechanical interfaces: face mount flange, servo flange, blind and through hollow shaft
- Enclosure rating: Up to IP66

Your benefits

- Optical and magnetic variants for the widest range of requirements
- Reduced maintenance costs thanks to magnetic, wearless scanning in single and multiturn design
- High level of productivity due to optical encoders with a high level of precision and fast calculation of positions
- Robust design for maximum system availability, even in extreme environmental conditions
- Absolutely compact - specially suited in cases where installation space is tight
- Flexible integration in all common networks



Performance

Max. number of steps per revolution:	2,048
Max. number of revolutions:	1
Resolution power:	2,048 x 1
Error limits:	0.035 ° (binary number of steps) 0.046 ° (non-binary number of steps)
Repeatability (Ta not constant):	0.005 °
Measuring step deviation:	0.005 °, 0.016 °
Measuring step:	360 ° /number of lines
Initialization time:	80 ms ¹⁾

¹⁾ Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Solid shaft, Servo flange
Shaft diameter:	6 mm
Mass:	0.3 kg

Start up torque:	0.25 Ncm
Operating torque:	0.2 Ncm
Permissible Load capacity of shaft:	10 N (axial), 20 N (radial)
Maximum operating speed:	10,000 /min (without shaft seal), 6,000 /min (with shaft seal) ¹⁾
Moment of inertia of the rotor:	48 gcm ²
Bearing lifetime:	3.6 x 10 ⁹ revolutions
Max. angular acceleration:	500,000 rad/s ²
Operation of zero-set:	≥ 100 ms ²⁾

¹⁾ If the shaft seal has been removed by the customer ²⁾ Only with shaft stationary (note initialisation time)

Electrical data

Operating voltage range:	10 V DC ... 32 V DC
Operating power consumption (no load):	90 mA
MTTFd: mean time to dangerous failure:	300 a (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

Interfaces

Electrical interface:	Connector M23, 21-pin, radial
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Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 65 (according to IEC 60529), with mating connector fitted
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	-20 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C
Resistance to shocks:	50 g (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

¹⁾

Set low only possible with a Ladder switch

Supply voltage to the encoder (before current conversion), rule must be taken if the type label of the encoder is

Supply voltage to the encoder, electrically isolated from the housing. The voltage referred to (DIN EN 60950-1, 11.1.1.1)

Power-on/Reverse: this input programs the counting direction of the encoder. If not connected this input is **high**. If the encoder starts, as viewed on the front side, rotates in the clockwise direction, it counts on an increasing sequence. It should count upwards when the shaft rotates in the anti-clockwise direction.

Encoder output: this input provides the output data of the encoder. If not connected this input is **high**.

Encoder stop: this input activates the data output data when a new level is signaled. If not connected this input is **low**. In the case of a high level, this input is **low**.

Stop: this input allows the encoder data in Gray code when a new level is applied. This assigns a read error if the natural data is requested in binary code. If this input is **low**, the data is the encoder output data in absolute, irrespective of whether the input is high or low. If not connected this input is **high**.

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Encoder output: this input provides the output data of the encoder. If not connected this input is **high**.

Encoder stop: this input activates the data output data when a new level is signaled. If not connected this input is **low**. In the case of a high level, this input is **low**.

Stop: this input allows to set the zero electrically, if the SET line is active for more than 100 ms, the mechanical position corresponds to the value 0.



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