



Motor feedback systems rotary incremental VFS60

VFS60A-BEPK01024



Model Name > [VFS60A-BEPK01024](#)
Part No. > [1036748](#)



Illustration may differ

At a glance

- TTL, HTL or sine 0.5 VSS interfaces
- Resolution of up to 65,536 lines per revolution
- Individual programming of the interface, line count and of the zero pulse
- Direct programming via RS485
- Excellent concentricity through large distance between the ball bearings
- Exceptional robustness and protection class IP 65
- Mechanical flexibility through blind hollow shaft and through hollow shafts with diameters of 8 to 15 mm, available with various torque supports
- Temperature range from -30 °C to +100 °C

Your benefits

- Programmable version for a reduced product variety
- Various programming tools designed to take into account your own programming requirements
- High performance and reliability even in rough ambient conditions
- Large ball bearing distances reduce uneven wear and minimize vibration on the motor feedback housing, which increases the motor feedback system's service life
- High vibration resistance and extended temperature range through nickel code disk



Performance

| | |
|---------------------------------|---|
| Number of lines per revolution: | 1,024 ¹⁾ |
| Reference signal, number: | 1 |
| Reference signal, position: | 90 ° electronically, gated with A and B |
| Error limits: | ± 0.03 ° |
| Measuring step deviation: | ± 0.01 ° |
| Maximum initialisation time: | 30 ms |

¹⁾ Factory programmed number of lines : 1024, level of output signal: TTL

Mechanical data

| | |
|------------------------------|--------------------|
| Shaft version: | Blind hollow shaft |
| Shaft diameter: | 12 mm |
| Shaft material: | Metal |
| Shaft plug-in length: | 15 mm ... 42 mm |
| Flange type/stator coupling: | Standard |

| | |
|--|---|
| Dimensions: | See dimensional drawing |
| Mass: | 0.2 kg |
| Moment of inertia of the rotor: | 40 gcm ² |
| Maximum operating speed: | 6,000 /min ¹⁾ |
| Maximum angular acceleration: | 500,000 rad/s ² |
| Operating torque: | 0.6 Ncm (20 °C) |
| Start up torque: | 0.8 Ncm (20 °C) |
| Permissible shaft movement, radial, dynamic: | ± 0.05 mm |
| Permissible shaft movement, axial, dynamic: | ± 0.01 mm |
| Life of ball bearings: | 3.0 x 10 ⁹ revolutions |
| Connection type: | Cable, 8-pin, radial, 1.5 m ²⁾ |

¹⁾ Self-warming 3.3 K/1,000 1/min, when applying note working temperature range ²⁾ The universal cable outlet is positioned in such a way, that it is possible to lay the cable in a radial or axial direction without kinking it

Electrical data

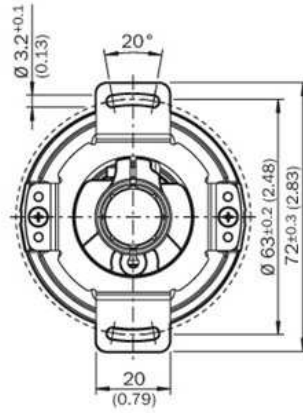
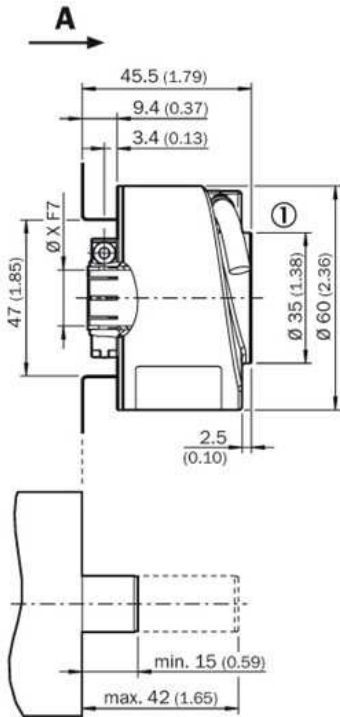
| | |
|---|----------------------|
| Electrical interface: | TTL/HTL programmable |
| Operating voltage range/supply Voltage: | 4.5 V ... 32 V |
| Maximum output frequency: | 820 kHz |
| Maximum load current: | 30 mA |
| Operating power consumption (no load): | 60 mA ¹⁾ |

¹⁾ Without load

Ambient data

| | |
|---------------------------------|---|
| Working temperature range: | -30 °C ... 100 °C |
| Storage temperature range: | -40 °C ... 100 °C, without package |
| Relative humidity/Condensation: | 90 %, condensation of the optical scanning not permitted |
| Resistance to shocks: | 70 g, 6 ms (according to EN 60068-2-27) |
| Resistance to vibration: | 30 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6) |
| EMC: | (according to EN 61000-6-2 and EN 61000-6-4) |
| Enclosure rating: | IP 65 (according to IEC 60529), shaft side, IP 67 (according to IEC 60529), housing side cable outlet |

Dimensional drawing



|1| Cable diameter = 5,6 mm
+/- 2 mm Bending radius = 30 mm

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