

SRS50-HAV0-K22







Motor feedback systems rotary HIPERFACE® SRS/SRM50

Model Name > SRS50-HAV0-K22

Part No. > 1037062





Illustration may differ

At a glance

- · Motor feedback systems for the top performance range
- 1,024 sine/ cosine periods per revolution
- Absolute position with a resolution of 32,768 increments per revolution and 4,096 revolutions with the multiturn system
- HIPERFACE® interface: Programming of the position value and electronic type label
- · Insert shaft or tapered shaft with various torque supports
- · Integrated version, mounted version or stand-alone design
- Certified according to SIL2/PL d (only valid for SRS50S/SRM50S...)
- · Conforms to RoHs

Your benefits

- · Motor feedback system with HIPERFACE® interface
- · High shock/vibration resistance thanks to built-in metal code disk
- Consistent motor design due to identical size of single and multiturn design
- To use of a motor feedback system certified to SIL2/PL d makes it easier to have your system certified.
- · Very smooth running thanks to maximum ball bearing distance



Performance

Number of sine/cosine periods per revolution: 1,024

Number of the absolute ascertainable revolutions: 1 (Singleturn)
Total number of steps: 32,768

Measuring step: 0.3 angular seconds at interpolation of the sine/cosine signals with e.g. 12

Bit

Differential non-linearity: ± 7 angular seconds (Non-linearity within a sine/cosine period)

Operating speed: 6,000 /min, up to which the absolute position can be reliably produced

Available memory area: 1,792 Byte, 1,792 Byte (E2PROM 2048)

Integral non-linearity typ.: ± 45 angular seconds (Error limits for evaluating sine/cosine period)

without mechanical tension of the stator coupling

Mechanical data

Shaft diameter: 7 mm

Flange type/stator coupling: Rubber support

Dimensions: See dimensional drawing

Moment of inertia of the rotor: 10 gcm²
Maximum operating speed: 12,000 /min

200,000 rad/s² Maximum angular acceleration: Operating torque: 0.2 Ncm Start up torque: 0.4 Ncm Permissible shaft movement, radial, static: ± 0.5 mm Permissible shaft movement, radial, dynamic: ± 0.1 mm Permissible shaft movement, axial, static: ± 0.75 mm

Permissible shaft movement, axial, dynamic: ± 0.2 mm Life of ball bearings: 3.6 x 10⁹ revolutions Connection type: Cable, 8-pin, radial, 200 mm

Shaft version: Plug-in shaft ± 0.005 mm/mm

Angular motion perpendicular to the rotational axis, static:

Angular motion perpendicular to the rotational axis,

dynamic:

± 0.002 mm/mm

GEWICHT01: 0.2 kg

Electrical data

Electrical interface: **HIPERFACE** Operating voltage range/supply Voltage: 7 V DC ... 12 V DC

Recommended supply voltage: 8 V DC

Output frequency for sine/cosine signals: 0 kHz ... 200 kHz

Operating power consumption (no load): 80 mA

1) Without load

Interfaces

Type of code for the absolute value: Binary

Code sequence: Increasing, for clockwise shaft rotation, looking in direction "A" (see

dimensional drawing)

Parameter channel RS 485: digital, Process data channel SIN, REFSIN, Interface signals:

COS, REFCOS: analog, differential

Ambient data

-30 °C ... +115 °C Working temperature range:

-40 °C ... +125 °C, without package Storage temperature range: Relative humidity/Condensation: 90 %, Condensation not permitted

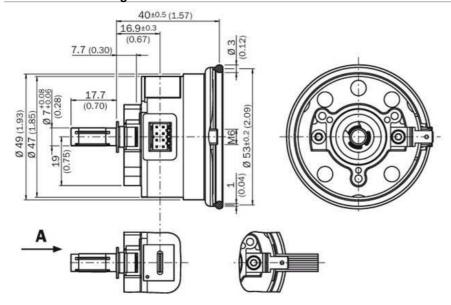
Resistance to shocks: 100 g/10 ms/according to EN 60068-2-27

20 g/10 Hz/2,000 Hz/according to EN 60068-2-6 Resistance to vibration: EMC: (according to EN 61000-6-2 and EN 61000-6-3)

Enclosure rating: IP 40 (according to IEC 60529), with mating connector inserted

¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the power supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Dimensional drawing



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