Motor feedback systems rotary HIPERFACE® SRS/SRM50

SRS50-HEA0-K21







Model Name> SRS50-HEA0-K21Part No.> 1037083



At a glance

- · Motor feedback systems for the top performance range
- 1,024 sine/ cosine periods per revolution
- Absolute position with a resolution of 32,768 increments per revolution and 4,096 revolutions with the multiturn system
- HIPERFACE® interface: Programming of the position value and electronic type label
- · Insert shaft or tapered shaft with various torque supports
- Integrated version, mounted version or stand-alone design
- Certified according to SIL2/PL d (only valid for SRS50S/SRM50S...)
- · Conforms to RoHs

Your benefits

- Motor feedback system with HIPERFACE® interface
- High shock/vibration resistance thanks to built-in metal code disk
- Consistent motor design due to identical size of single and multiturn design
- To use of a motor feedback system certified to SIL2/PL d makes it easier to have your system certified.
- · Very smooth running thanks to maximum ball bearing distance



Performance

I (Singleturn) 32,768
32.768
0.3 angular seconds at interpolation of the sine/cosine signals with e.g. 12 Bit
2 7 angular seconds (Non-linearity within a sine/cosine period)
6,000 /min, up to which the absolute position can be reliably produced
28 Byte, 128 Byte (E2PROM 512)
45 angular seconds (Error limits for evaluating sine/cosine period) without mechanical tension of the stator coupling
E ⊦

Flange type/stator coupling:	Rubber support	
Dimensions:	See dimensional drawing	
Moment of inertia of the rotor:	10 gcm ²	
Maximum operating speed:	12,000 /min	
Maximum angular acceleration:	200,000 rad/s ²	

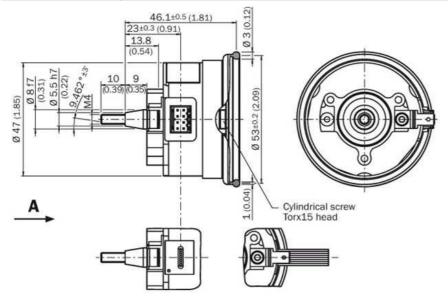
Illustration may differ

Operating torque:	0.2 Ncm
Start up torque:	0.4 Ncm
Permissible shaft movement, radial, static:	± 0.5 mm
Permissible shaft movement, radial, dynamic:	± 0.1 mm
Permissible shaft movement, axial, static:	± 0.75 mm
Permissible shaft movement, axial, dynamic:	± 0.2 mm
Life of ball bearings:	3.6 x 10 [^] 9 revolutions
Connection type:	Connector, 8-pin
Shaft version:	Tapered shaft
Angular motion perpendicular to the rotational axis, static:	± 0.005 mm/mm
Angular motion perpendicular to the rotational axis, dynamic:	± 0.002 mm/mm
GEWICHT01:	0.2 kg
Electrical data	
Electrical interface:	HIPERFACE
Operating voltage range/supply Voltage:	7 V DC 12 V DC
Recommended supply voltage:	8 V DC
Output frequency for sine/cosine signals:	0 kHz 200 kHz
Operating power consumption (no load):	80 mA ¹⁾
¹⁾ Without load	
Interfaces	
Type of code for the absolute value:	Binary
Code sequence:	Increasing, for clockwise shaft rotation, looking in direction "A" (see dimensional drawing)
Interface signals:	Parameter channel RS 485: digital, Process data channel SIN, REFSIN, COS, REFCOS: analog, differential
Ambient data	
Working temperature range:	-30 °C +115 °C
Storage temperature range:	-40 °C +125 °C, without package
Relative humidity/Condensation:	90 %, Condensation not permitted
Resistance to shocks:	100 g/10 ms/according to EN 60068-2-27
Resistance to vibration:	20 g/10 Hz/2,000 Hz/according to EN 60068-2-6
EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 40 (according to IEC 60529), with mating connector inserted
¹⁾ The EMC according to the standards quoted is achieved when the	motor feedback system is mounted in an electrically conductive housing, which is connected to the
	is also where the CND (0.V) connection of the newer supply voltage is linked to earth. Users must

central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the power supply voltage is linked to earth. Users must

perform their own tests when other screen designs are used.

Dimensional drawing



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