



**Absolute encoders  
AFS/AFM60 SSI**

AFS60E-TDAA004096

**Model Name** > [AFS60E-TDAA004096](#)  
**Part No.** > [1038051](#)



#### At a glance

- High-resolution absolute encoders with up to 30 bits (AFM60) or up to 18 bits (AFS60)
- Face mount flange, servo flange, blind or through hollow shaft
- SSI, SSI + Incremental or SSI + Sin/Cos interface
- Programmable resolution and offset (dependent on type)
- Connection system: M12, M23 connector or cable outlet
- Enclosure rating: IP 67 (housing), IP 65 (shaft)
- Operating temperature: -30 °C to +100 °C (depends on type)

#### Your benefits

- Programmability of the encoders means less storage, greater machine availability and easy installation
- Precise positioning due to high resolutions
- Large selection of mechanical interfaces and electrical contacting possibilities: Suitable for all applications
- Suitable for applications with limited space requirements (extremely short installation depth of 30 mm)
- Very good rotation accuracy due to increased bearing distance
- One programming tool and software with automatic encoder detection for AFS60/AFM60/DFS60



#### Performance

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Max. number of steps per revolution:	4,096
Max. number of revolutions:	1
Resolution power:	4,096 x 1
Error limits:	± 0.3 °
Repeatability (Ta not constant):	0.002 °
Measuring step deviation:	± 0.2 °
Measuring step:	0.09 ° 360 ° / number of steps
Initialization time:	50 ms <sup>1)</sup>

<sup>1)</sup> Valid positional data can be read once this time has elapsed

#### Mechanical data

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Mechanical interface:	Through hollow shaft
Shaft diameter:	10 mm
Mass:	0.2 kg

Start up torque:	0.8 Ncm (20 °C)
Operating torque:	0.6 Ncm (20 °C)
Maximum operating speed:	9,000 /min <sup>1)</sup>
Moment of inertia of the rotor:	40 gcm <sup>2</sup>
Bearing lifetime:	3.0 x 10 <sup>9</sup> revolutions
Max. angular acceleration:	500,000 rad/s <sup>2</sup>
Permissible movement axial static/dynamic:	± 0.5 mm, ± 0.2 mm
Permissible movement radial static/dynamic:	± 0.3 mm, ± 0.1 mm
Type of mounting shaft:	Through hollow shaft

<sup>1)</sup> Self warming of 3.3 K per 1000 revolutions/min when applying note working temperature range

## Electrical data

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Power consumption:	0.5 W (without load)
Operating voltage range:	4.5 V DC ... 32 V DC
MTTFd: mean time to dangerous failure:	250 a (EN ISO 13849-1) <sup>1)</sup>
Connection type:	Connector M23, 12-pin, radial
Code type:	Gray
Code sequence:	CW/CCW, parameter adjustable
Reverse polarity protection:	1

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

## Interfaces

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Electrical interface:	SSI/Gray
Interface signals:	Clock +, Clock -, Data +, Data- <sup>1)</sup>
Clock frequency:	1 MHz
SET (electronic adjustment):	H-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)
CW/CCW (counting sequence when turning):	L-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)

<sup>1)</sup>

## Ambient data

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EMC:	(according to EN 61000-6-2 and EN 61000-6-3) <sup>1)</sup>
Enclosure rating:	IP 65 (according to IEC 60529), housing side, IP 65 (according to IEC 60529), shaft side <sup>2)</sup>
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	0 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C, without package
Resistance to shocks:	50 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

<sup>1)</sup> <sup>2)</sup> With mating connector fitted

## Dimensional drawing



|1| Cable diameter = 5,6 mm  
+/- 2 mm Bending radius = 30 mm

## PIN assignment

Pin	Signal	Explanation
1	GND	Ground connection
2	Data+	Interface signals
3	Clock+	Interface signals
4	N.C.	Not connected
5	N.C.	Not connected
6	N.C.	Not connected
7	N.C.	Not connected
8	V <sub>L</sub>	Supply voltage
9	SET	Electronic adjustment
10	Data-	Interface signals
11	Dock-	Interface signals
12	CW/CCW	Counting sequence when turning
	Screen	Screen on the encoder side connected to the housing. On the control side connected to earth.

Pin	Color wires	Signal	Explanation
1	Red	V <sub>L</sub>	Supply voltage
2	Blue	GND	Ground connection
3	Yellow	Clock+	Interface signal
4	White	Data+	Interface signal
5	Orange	SET	Electronic adjustment
6	Brown	Data-	Interface signal
7	Violet	Dock-	Interface signal
8	Black	B	Signal line
9	Orange/black	CW/CCW	Counting sequence when turning
10	Green	A	Signal line
11	Gray	A	Signal line
12	Pink	B	Signal line
	Screen	Screen on the encoder side connected to the housing. On the control side connected to earth.	

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7	Violet	Dock-	Interface signal
8	Black	Sn-	Signal line
9	Orange/black	CW/CCW	Counting sequence when turning
10	Green	Co-	Signal line
11	Gray	Co+	Signal line
12	Pink	Sn+	Signal line
	Screen	Screen on the encoder side connected to the housing. On the control side connected to earth.	

# Signalausgänge

**SSI data format singleturn**

**Bit 1-16: Position Bits**

- LSD: Least significant Bit
- MSB: Most significant Bit

**Bit 17-19: Error Bits**

- ERRDIG: Failure message about speed. If this failure occurs during the position building procedure it will be indicated by the ERRDIG-Bit.
- ERRSL: Light source monitoring failure.
- ERRSYNC: Contamination of the disc or scanning system. During the determination of the position, an error has occurred since the last SSI transmission. The error bit will be deleted during the next data transmission.

**The evaluation of the error bits has to be realized in the PLC.**  
The provided error bits don't have to be used by the PLC compulsorily.

**Example**  
If the resolution of the absolute encoder is set on 13 bits, 16 bits are provided by the encoder: 13 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 13 bits. Then the error bits have to be masked out by the PLC.

**SSI data format multiturn**

**30 Bits**

**Bit 1-12: Position Bits multiturn**  
**Bit 13-24: Position Bits singleturn**  
**Bit 25-30: Error Bits**

**27 Bits**

**Bit 1-12: Position Bits multiturn**  
**Bit 13-27: Position Bits singleturn**  
**Bit 28-30: Error Bits**

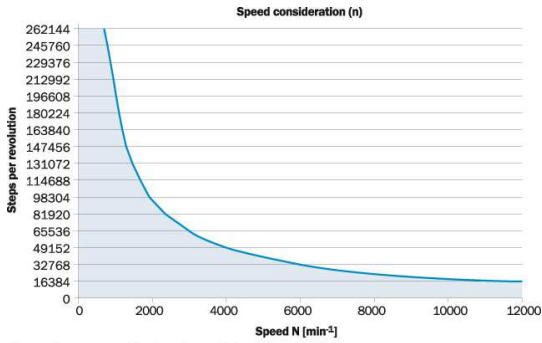
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**The evaluation of the error bits has to be realized in the PLC.**  
The provided error bits don't have to be used by the PLC compulsorily. The multiturn resolution is fixed on 12 bits.

**Example**  
If the resolution of the absolute encoder is set on 27 bits, 30 bits are provided by the encoder: 27 data bits and 3 error bits. If the PLC is not able to evaluate the error bits, the PLC has to be set on a resolution of 27 bits. Then the error bits have to be masked out by the PLC.

# Drehzahlbetrachtung



The maximum speed is also dependent on the shaft type.

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# Interfaces

**Electrical interfaces sine 0.5 V<sub>r</sub>**

Power supply: Output: 5V ± 0.5 V<sub>r</sub>

Signal before differential generation at load 120 Ω at U<sub>r</sub> = 5 V

Signal diagram for absolute rotation of the shaft looking in direction "X" (shaft)

Direction signal Sin, Cos, ZOC, ZOC Signal before differential generation at load 120 Ω

Timing differential: 2.0 V<sub>r</sub> ± 20%

Signal after differential generation at load 120 Ω at U<sub>r</sub> = 5 V

Signal diagram for absolute rotation of the shaft looking in direction "X" (shaft)

**Incremental pulse diagram for absolute rotation of the shaft looking in direction "X", see dimensional drawing**

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