

CFS50-AEV10X03







Motor feedback systems rotary incremental with commutation CFS50

Model Name > CFS50-AEV10X03

Part No. > 1065229





Illustration may differ

At a glance

- Output driver for incremental and commutation signals as per EIA 422
- Resolution of up to 65,536 lines per revolution
- · Commutation signals up to 32 pole pairs
- Temperature range from -20 °C to +115 °C
- · Various mechanical interfaces

Your benefits

- High level of flexibility due to mechanics already proven in other motor feedback systems
- · High level of compatibility thanks to standard interface
- · Time-saving due to electrical zero adjustment

Performance

Number of lines per revolution: 1,024

Measuring step: 90 ° /number of lines

Commutation signals: 3 pole pairs

Reference signal, number:

Reference signal, position: 90 ° electronically, gated with A and B

Operating speed: 6,000 /min

Mechanical data

Shaft version: Tapered shaft Flange type/stator coupling: Rubber support

Dimensions: See dimensional drawing

Mass: 0.1 kg Moment of inertia of the rotor: 10 gcm² 12,000 /min Maximum operating speed: 200,000 rad/s² Maximum angular acceleration: Operating torque: 0.2 Ncm 0.4 Ncm Start up torque: ± 0.5 mm Permissible shaft movement, radial, static: Permissible shaft movement, radial, dynamic: ± 0.1 mm Permissible shaft movement, axial, static: ± 0.75 mm Permissible shaft movement, axial, dynamic: ± 0.2 mm

Life of ball bearings: 3.6 x 10⁹ revolutions

¹⁾ Number of lines from 1 \dots 1.000 and > 4.096 \dots 65.536 on request

Connection type: Stranded cable, 15-pin, radial

Angular motion perpendicular to the rotational axis,

static:

Angular motion perpendicular to the rotational axis,

dynamic:

± 0.005 mm/mm

. 0.000

± 0.002 mm/mm

Electrical data

Electrical interface: TTL/RS422

Operating voltage range/supply Voltage: 4.5 V DC ... 5.5 V DC

Maximum output frequency: 820 kHz
Operating power consumption (no load): 60 mA 1)

1) Without load

Ambient data

Working temperature range: -20 °C ... 115 °C

Storage temperature range: -40 °C ... 125 °C, without package Relative humidity/Condensation: 90 %, Condensation not permitted

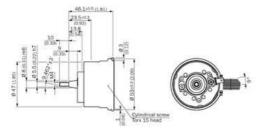
Resistance to shocks: 100 g/10 ms/according to EN 60068-2-27

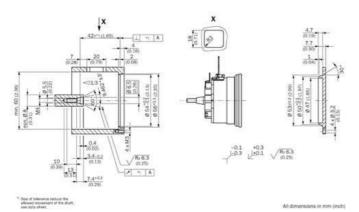
Resistance to vibration: 20 g/10 Hz/2,000 Hz/according to EN 60068-2-6 EMC: (according to EN 61000-6-2 and EN 61000-6-3) 1)

Enclosure rating: IP 40 (according to IEC 60529)

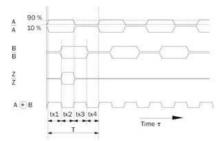
¹⁾ The EMC according to the standards quoted is achieved when the motor feedback system is mounted in an electrically conductive housing, which is connected to the central earthing point of the motor controller via a cable screen. This is also where the GND (0 V) connection of the power supply voltage is linked to earth. Users must perform their own tests when other screen designs are used.

Dimensional drawing





Incremental track



At constant rotational speed with regard to the input shaft and rotation in clockwise direction.

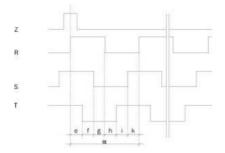
By connecting the two signals A and B, an output signal arises whose period durations tx1 ... tx4 have varying lengths.

The differences are determined:

- by the pulse/pause ratio tolerance of the individual channels
- by the tolerance in the $90\,^\circ$ phase shift between A and B
- · by the frequency

The times $tx1 \dots tx4$ ideally have to amount to 1/4 of the particular period duration T. The typical output frequency of the encoder is defined so that the max. time tx is smaller than $1.5 \times T/4$.

Pulse time diagram



| Polpairs | Number of poles | e, f, g, h, l, k | α | |
|----------|-----------------|------------------|------|--|
| 2 | 4 | 30* | 180* | |
| 3 | 6 | 20* | 120* | |
| 4 | 8 | 15* | 90* | |
| 6 | 12 | 10* | 60* | |
| 8 | 16 | 7.5* | 45* | |

The angle information is related to a mechanical shaft rotation. Fiank precision of the signals R, S, T ± 1 ".

Wire allocation

| PIN | Color | Signal | |
|-----|--------------|--|--|
| 1 | Blue | Ground connection (GND) | |
| 2 | Red | Supply voltage 5 V ± 10 % (U _a) | |
| 3 | Yellow | Reference signal inverted (Z) | |
| 4 | Purple | Reference signal (Z) | |
| 5 | Brown | Increment signal inverted (Ā) | |
| 6 | White | Increment signal (A) | |
| 7 | Black | Increment signal inverted (B) | |
| 8 | Pink | Increment signal (B) | |
| 9 | White/Red | Commutation signal inverted (\overline{T}) | |
| 10 | White/Gray | Commutation signal (T) | |
| 11 | White/Blue | Commutation signal inverted (S) | |
| 12 | White/Yellow | Commutation signal (S) | |
| 13 | White/Pink | Commutation signal inverted (R) | |
| 14 | White/Green | Commutation signal (R) | |
| 15 | Gray | Electronic setting of the commutation signals (SETO) | |

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