



Absolute encoders AFS/AFM60 SSI, Rotary

AFM60A-TDKK262144



Model Name > [AFM60A-TDKK262144](#)
Part No. > [1065974](#)



Illustration may differ

At a glance

- High-resolution absolute encoders with up to 30 bits (AFM60) or up to 18 bits (AFS60)
- Face mount flange, servo flange, blind or through hollow shaft
- SSI, SSI + Incremental or SSI + Sin/Cos interface
- Programmable resolution and offset (dependent on type)
- Connection system: M12, M23 connector or cable outlet
- Enclosure rating: IP 67 (housing), IP 65 (shaft)
- Operating temperature: -30 °C to +100 °C (depends on type)

Your benefits

- Programmability of the encoders means less storage, greater machine availability and easy installation
- Precise positioning due to high resolutions
- Large selection of mechanical interfaces and electrical contacting possibilities: Suitable for all applications
- Suitable for applications with limited space requirements (extremely short installation depth of 30 mm)
- Very good rotation accuracy due to increased bearing distance
- One programming tool and software with automatic encoder detection for AFS60/AFM60/DFS60



Performance

Max. number of steps per revolution:	262,144
Max. number of revolutions:	4,096
Resolution power:	262,144 x 4,096
Resolution:	18 bit x 12 bit
Error limits:	± 0.03 °
Repeatability (Ta not constant):	0.002 °
Measuring step deviation:	± 0.002 °
Initialization time:	50 ms ¹⁾

¹⁾ Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Through hollow shaft
Shaft diameter:	10 mm
Start up torque:	0.8 Ncm (20 °C)

Operating torque:	0.6 Ncm (20 °C)
Maximum operating speed:	9,000 /min ¹⁾
Moment of inertia of the rotor:	40 gcm ²
Bearing lifetime:	3.0 x 10 ⁹ revolutions
Max. angular acceleration:	500,000 rad/s ²
Permissible movement axial static/dynamic:	± 0.5 mm, ± 0.01 mm
Permissible movement radial static/dynamic:	± 0.3 mm, ± 0.05 mm
Type of mounting shaft:	Through hollow shaft

¹⁾ Self warming of 3.3 K per 1000 revolutions/min when applying note working temperature range

Electrical data

Power consumption:	0.5 W (without load)
Operating voltage range:	4.5 V DC ... 32 V DC
Maximum output frequency:	200 kHz
Load resistance min.:	120 Ω
MTTFd: mean time to dangerous failure:	250 a (EN ISO 13849-1) ¹⁾
Connection type:	Cable, 12-pin, radial, 1.5 m ²⁾
Code type:	Gray
Code sequence:	CW/CCW, parameter adjustable
Reverse polarity protection:	1

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532. ²⁾ Not UL certified

Interfaces

Electrical interface:	SSI/Gray + Sin/Cos, 1.024 Perioden
Interface signals:	Clock +, Clock -, Data +, Data-, Sin +, Sin -, Cos +, Cos -: analog, differential ¹⁾
Clock frequency:	2 MHz
SET (electronic adjustment):	H-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)
CW/CCW (counting sequence when turning):	L-active (L ≡ 0 - 1,5 V, H ≡ 2,0 - Us V)
Signal before differential generation:	± 20 %
Signal offset:	2.5 V ± 10 %

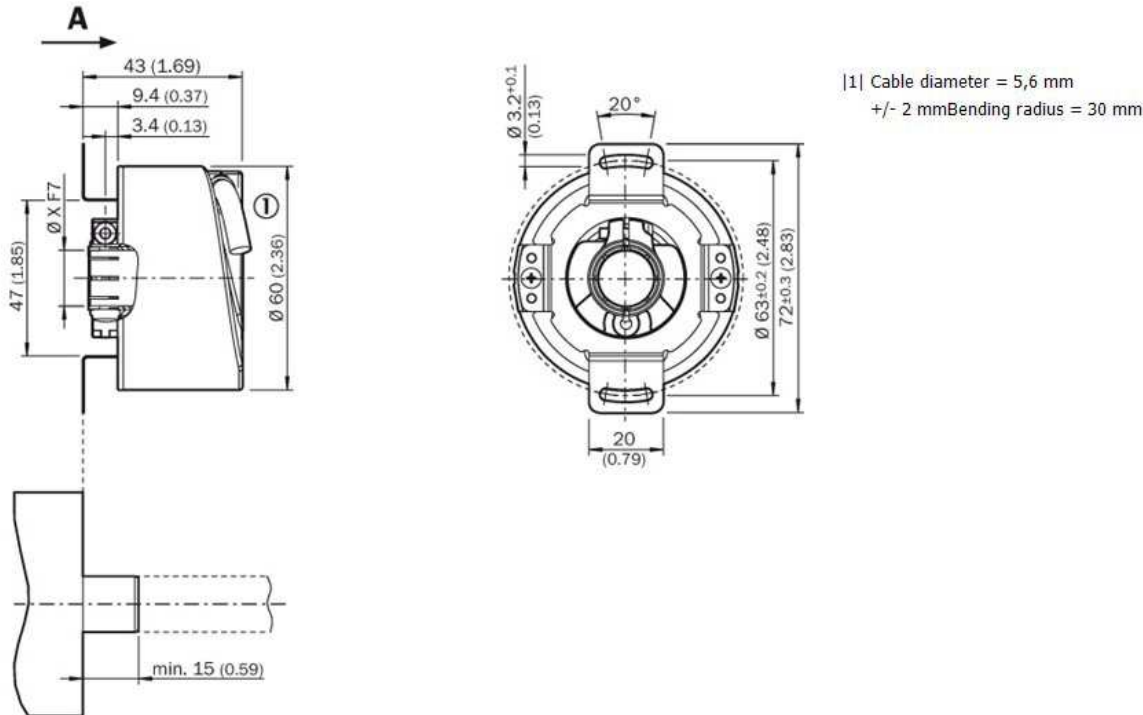
¹⁾

Ambient data

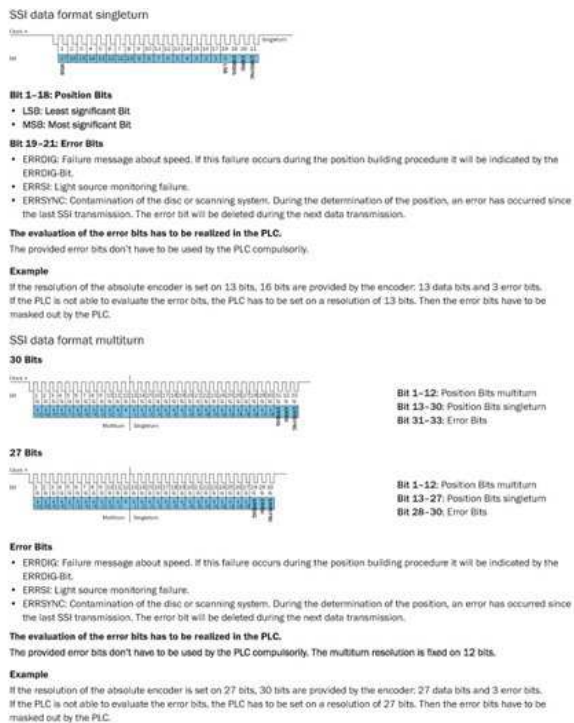
EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 65 (according to IEC 60529), shaft side, IP 67 (according to IEC 60529), housing side
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	-30 °C ... 100 °C
Storage temperature range:	-40 °C ... 100 °C, without package
Resistance to shocks:	60 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

1)

Dimensional drawing

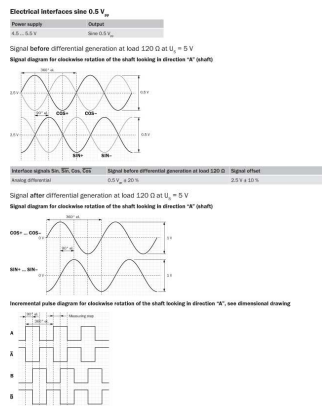


Signalausgänge



The graph illustrates the relationship between speed and steps per revolution. The y-axis, labeled 'Steps per revolution', ranges from 16384 to 262144. The x-axis, labeled 'Speed N [min⁻¹]', ranges from 0 to 12000. A blue curve shows that as speed increases, the number of steps per revolution decreases, approaching a minimum value of 16384.

Interfaces

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