



## Incremental encoders DFS60, Rotary

DFS60E-BDAA01250



**Model Name** > [DFS60E-BDAA01250](#)  
**Part No.** > [1068101](#)



*Illustration may differ*

**At a glance**

- Compact installation depth
- High resolution up to 16 bits
- Optionally programmable: Output voltage, zero pulse position, zero pulse width and number of pulses
- Connection: Radial or axial cable outlet, M23 or M12 connector, axial or radial
- Electrical interfaces: 5V & 24V TTL/RS-422, 24 V HTL/push pull
- Mechanical interfaces: face mount or servo flange, blind or through hollow shaft
- Remote zero set possible

**Your benefits**

- Reduced storage costs and downtime due to customer-specific programming
- Variety of different mechanical and electrical interfaces enable the encoder to be optimally adjusted to fit the installation situation
- Excellent concentricity even at high speeds
- High resolution of up to 16 bits ensures precise measurements
- Permanent and safe operation due to a high enclosure rating, temperature resistance and a long bearing lifetime
- Programmability via the PGT-08 programming software and the PGT-10-S display programming tool allow the encoder to be adapted flexibly and quickly according to customer needs
- Programmable zero pulse position simplifies installation



**Performance**

Error limits:	± 0.3 °
Measuring step:	Electronically/number of lines
Initialization time:	40 ms
Pulses per revolution:	1,250

**Mechanical data**

Mechanical interface:	Blind hollow shaft
Shaft diameter:	10 mm
Mass:	0.2 kg
Start up torque:	0.8 Ncm (+20 °C)
Operating torque:	0.6 Ncm (+20 °C)
Permissible movement radial static/dynamic:	± 0.3 mm, ± 0.1 mm
Maximum operating speed:	6,000 /min
Moment of inertia of the rotor:	40 gcm <sup>2</sup>

Bearing lifetime: 3.6 x 10<sup>10</sup> revolutions  
Max. angular acceleration: 500,000 rad/s<sup>2</sup>  
Shaft material: Metal

#### Electrical data

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Electrical interface: 4.5 V ... 5.5 V, TTL/RS422, Connector M23, 12-pin, radial  
Electrical connection: Connector M23, 12-pin, radial  
Maximum output frequency: 300 kHz  
Reference signal, number: 1  
Reference signal, position: 90 °, electronically, gated with A and B  
Operating voltage range: 4.5 V ... 5.5 V  
Load current max.: 30 mA  
Power consumption: Without load  
MTTFd: mean time to dangerous failure: 300 a (EN ISO 13849-1) <sup>1)</sup>

<sup>1)</sup> This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

#### Ambient data

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EMC: (according to EN 61000-6-2 and EN 61000-6-3)  
Working temperature range: 0 °C ... +85 °C  
Storage temperature range: -40 °C ... +100 °C, without package  
Resistance to shocks: 50 g (according to EN 60068-2-27)  
Resistance to vibration: 20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)  
Enclosure rating: IP 65 (according to IEC 60529), shaft side, IP 67 (according to IEC 60529), housing side  
Permissible relative humidity: 90 % (condensation of the optical scanning not permitted)

<sup>1)</sup> With mating connector fitted

## Dimensional drawing



## PIN assignment

### 5-core cable

View of M12 device connector on encoder



View of M23 device connector on encoder



PIN, 5-pin, M12 connector	PIN, 12-pin, M23 connector	Core colors of encoders with cable outlet	TTL/HTL signal	Explanation
1	6	Brown	A	Signal cable
2	5	White	A	Signal cable
3	1	Black	B	Signal cable
4	8	Pink	B	Signal cable
5	4	Yellow	Z	Signal cable
6	3	Lilac	Z	Signal cable
7	10	Blue	GND	Ground connection of the encoder
8	12	Red	+U <sub>s</sub>	Supply voltage (volt-free to housing)
-	9	-	N.C.	Not assigned
-	2	-	N.C.	Not assigned
-	11	-	N.C.	Not assigned
-	7 <sup>a</sup>	-	SET	Zero pulse teach
Shield	Shield	Shield	Shield	Shield connected to housing on side of encoder. Connected to ground on side of control.

<sup>a</sup> Only at 4.5 ... 32 V, TTL/HTL programmable

The SET input serves to carry out the zero pulse teach function. If the SET input is applied to U<sub>s</sub> for longer than 250 ms, after it has been open for at least 1,000 ms or applied to GND, the current shaft position is assigned the zero pulse signal "Z".

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Drehzahlbetrachtung



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