



Absolute encoders ARS60 SSI/Parallel

ARS60-H1B08192



Model Name > ARS60-H1B08192
Part No. > 1209034



Illustration may differ

At a glance

- Absolute singleturn encoder
- Resolution: up to 15 bits (32,768 increments)
- Electrical interface: SSI with gray code type or gray capped
- Electrical interface: Parallel with gray, gray capped, binary, BCD code type
- Zero-set function
- Mechanical interfaces: face mount flange, servo flange, blind and through hollow shaft
- Enclosure rating: Up to IP66

Your benefits

- Optical and magnetic variants for the widest range of requirements
- Reduced maintenance costs thanks to magnetic, wearless scanning in single and multiturn design
- High level of productivity due to optical encoders with a high level of precision and fast calculation of positions
- Robust design for maximum system availability, even in extreme environmental conditions
- Absolutely compact - specially suited in cases where installation space is tight
- Flexible integration in all common networks



Performance

Max. number of steps per revolution:	8,192
Max. number of revolutions:	1
Resolution power:	8,192 x 1
Error limits:	0.035 ° (binary number of steps) 0.046 ° (non-binary number of steps)
Repeatability (Ta not constant):	0.005 °
Measuring step deviation:	0.005 °, 0.016 °
Measuring step:	360 ° /number of lines
Initialization time:	80 ms ¹⁾

¹⁾ Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Solid shaft, Servo flange
Shaft diameter:	6 mm
Mass:	0.3 kg

Start up torque:	0.25 Ncm
Operating torque:	0.2 Ncm
Permissible Load capacity of shaft:	10 N (axial), 20 N (radial)
Maximum operating speed:	10,000 /min (without shaft seal), 6,000 /min (with shaft seal) ¹⁾
Moment of inertia of the rotor:	48 gcm ²
Bearing lifetime:	3.6 x 10 ⁹ revolutions
Max. angular acceleration:	500,000 rad/s ²
Operation of zero-set:	≥ 100 ms ²⁾

¹⁾ If the shaft seal has been removed by the customer ²⁾ Only with shaft stationary (note initialisation time)

Electrical data

Operating voltage range:	10 V DC ... 32 V DC
Operating power consumption (no load):	90 mA
MTTFd: mean time to dangerous failure:	300 a (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

Interfaces

Electrical interface:	Connector M23, 21-pin, axial
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Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 65 (according to IEC 60529), with mating connector fitted
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	-20 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C
Resistance to shocks:	50 g (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

¹⁾

* Allocation for encoder with 25-pin connector Single Parallel Interface

PIN	Wire color/cable outlet	Binary	Gray	BCD	Description
1	Blue	2 ⁰	G ₀	2 ⁰ × 10 ⁰	Data lines, outputs
2	White/brown	2 ¹	G ₁	2 ¹ × 10 ⁰	
3	White/green	2 ²	G ₂	2 ² × 10 ⁰	
4	White/yellow	2 ³	G ₃	2 ³ × 10 ⁰	
5	White/gray	2 ⁴	G ₄	2 ⁴ × 10 ⁰	
6	White/pink	2 ⁵	G ₅	2 ⁵ × 10 ⁰	
7	White/blue	2 ⁶	G ₆	2 ⁶ × 10 ⁰	
8	White/red	2 ⁷	G ₇	2 ⁷ × 10 ⁰	
9	White/black	2 ⁸	G ₈	2 ⁸ × 10 ⁰	
10	Brown/green	2 ⁹	G ₉	2 ⁹ × 10 ⁰	
11	Brown/yellow	2 ¹⁰	G ₁₀	2 ¹⁰ × 10 ⁰	
12	Brown/gray	2 ¹¹	G ₁₁	2 ¹¹ × 10 ⁰	
13	Brown/pink	2 ¹²	G ₁₂	2 ¹² × 10 ⁰	
14	Brown/blue	2 ¹³	G ₁₃	2 ¹³ × 10 ⁰	
15	Brown/red	2 ¹⁴	G ₁₄	2 ¹⁴ × 10 ⁰	
16	Green	Parity	Parity		
17	Pink	Strobe	Strobe		
18	Yellow	Enable	Enable		
19	Brown	V/R	V/R	V/R	
20	Gray	SET	SET	SET	
21	Blue	GND	GND	GND	
22	Red	V _{cc}	V _{cc}	V _{cc}	
Housing		Screen	Screen	Screen	

V _{CC}	Supply voltage to the encoder (before commissioning, note must be taken of the type /size of the encoder).
GND	Zero volt connection to the encoder (electrically isolated from the housing). The voltage referred to GND is U ₀ .

Example: This can be achieved by using a state variable to store the current level. If not connected, the level is zero. In the case of a shift, the state variable is incremented or decremented by one, depending on the direction of the shift. If the level is zero, the state variable is set to zero.

Output	This signal indicates the data input when a new state is applied. A not connected, this signal, is zero, in the case of a right shift, the outputs are in the tri-state mode.
Store	This input stores the encoder data in Gray code when a store level is applied. This results a read error if the output data is requested in binary code. If this

Parity This output supplies a high level when the binary checksum of the data bits is even.

SET This input serves to set the zero electronically. If the SET line is connected to I/O for more than 100 ms, the mechanical position corresponds to the value 0.



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