



Absolute encoders ARS60 SSI/Parallel

ARS60-H1A01024



Model Name > **ARS60-H1A01024**
Part No. > **1209290**



Illustration may differ

At a glance

- Absolute singleturn encoder
- Resolution: up to 15 bits (32,768 increments)
- Electrical interface: SSI with gray code type or gray capped
- Electrical interface: Parallel with gray, gray capped, binary, BCD code type
- Zero-set function
- Mechanical interfaces: face mount flange, servo flange, blind and through hollow shaft
- Enclosure rating: Up to IP66

Your benefits

- Optical and magnetic variants for the widest range of requirements
- Reduced maintenance costs thanks to magnetic, wearless scanning in single and multiturn design
- High level of productivity due to optical encoders with a high level of precision and fast calculation of positions
- Robust design for maximum system availability, even in extreme environmental conditions
- Absolutely compact - specially suited in cases where installation space is tight
- Flexible integration in all common networks



Performance

Max. number of steps per revolution:	1,024
Max. number of revolutions:	1
Resolution power:	1,024 x 1
Error limits:	0.035 ° (binary number of steps) 0.046 ° (non-binary number of steps)
Repeatability (Ta not constant):	0.005 °
Measuring step deviation:	0.005 °, 0.016 °
Measuring step:	360 ° /number of lines
Initialization time:	80 ms ¹⁾

¹⁾ Valid positional data can be read once this time has elapsed

Mechanical data

Mechanical interface:	Solid shaft, Servo flange
Shaft diameter:	6 mm
Mass:	0.3 kg

Start up torque:	0.25 Ncm
Operating torque:	0.2 Ncm
Permissible Load capacity of shaft:	10 N (axial), 20 N (radial)
Maximum operating speed:	10,000 /min (without shaft seal), 6,000 /min (with shaft seal) ¹⁾
Moment of inertia of the rotor:	48 gcm ²
Bearing lifetime:	3.6 x 10 ⁹ revolutions
Max. angular acceleration:	500,000 rad/s ²
Operation of zero-set:	≥ 100 ms ²⁾

¹⁾ If the shaft seal has been removed by the customer ²⁾ Only with shaft stationary (note initialisation time)

Electrical data

Operating voltage range:	10 V DC ... 32 V DC
Operating power consumption (no load):	90 mA
MTTFd: mean time to dangerous failure:	300 a (EN ISO 13849-1) ¹⁾

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive.

Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All

electronic failures are considered hazardous. For more information, see document no. 8015532.

Interfaces

Electrical interface:	Connector M23, 21-pin, radial
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Ambient data

EMC:	(according to EN 61000-6-2 and EN 61000-6-3) ¹⁾
Enclosure rating:	IP 65 (according to IEC 60529), with mating connector fitted
Permissible relative humidity:	90 % (condensation of the optical scanning not permitted)
Working temperature range:	-20 °C ... 85 °C
Storage temperature range:	-40 °C ... 100 °C
Resistance to shocks:	50 g (according to EN 60068-2-27)
Resistance to vibration:	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

¹⁾

Technical drawing of a 1/2" NPT female adapter with a 1/4" NPT male thread. The drawing includes a front view, a side view, and a detail of the male thread. Dimensions are given in millimeters and inches.

Front View Dimensions:

- Top thread: M4 8 deep (0.31)
- Top hole: $\varnothing 42 \pm 0.1$ (1.65)
- Inner hole: $\varnothing 0.2$ B
- Angle: 120°
- Bottom angle: 25°
- Bottom hole: $\varnothing 60$ (2.36)
- Height from bottom hole to top hole: 66 (2.60)
- Height from bottom hole to bottom flange: 24 (0.94)

Side View Dimensions:

- Length: 54 ± 0.5 (2.13)
- Height from bottom flange to top hole: 90 (3.54)
- Height from bottom flange to bottom hole: 66 (2.60)
- Height from bottom flange to top flange: 24 (0.94)
- Bottom hole: $\varnothing 8$ (0.31)

Detail Dimensions:

- Radius: 10 (0.39)
- Height: 20 (0.79)

Thread Specifications:

- Top thread: 1/4" NPT
- Bottom thread: 1/2" NPT

- Allocation for encoder with 25-pin connector Single, Parallel Interface

PIN	Wire color/cable outlet	Binary	Gray	BCD	Description
1	Blue	2 ⁰	G ₀	2 ⁰ × 10 ⁰	Data lines, outputs
2	White/brown	2 ¹	G ₁	2 ¹ × 10 ⁰	
3	White/green	2 ²	G ₂	2 ² × 10 ⁰	
4	White/yellow	2 ³	G ₃	2 ³ × 10 ⁰	
5	White/gray	2 ⁴	G ₄	2 ⁴ × 10 ⁰	
6	White/pink	2 ⁵	G ₅	2 ⁵ × 10 ⁰	
7	White/blue	2 ⁶	G ₆	2 ⁶ × 10 ⁰	
8	White/red	2 ⁷	G ₇	2 ⁷ × 10 ⁰	
9	White/black	2 ⁸	G ₈	2 ⁸ × 10 ⁰	
10	Brown/green	2 ⁹	G ₉	2 ⁹ × 10 ⁰	
11	Brown/yellow	2 ¹⁰	G ₁₀	2 ¹⁰ × 10 ⁰	
12	Brown/gray	2 ¹¹	G ₁₁	2 ¹¹ × 10 ⁰	
13	Brown/pink	2 ¹²	G ₁₂	2 ¹² × 10 ⁰	
14	Brown/blue	2 ¹³	G ₁₃	2 ¹³ × 10 ⁰	
15	Brown/red	2 ¹⁴	G ₁₄	2 ¹⁴ × 10 ⁰	
16	Green	Parity	Parity	Parity	
17	Pink	Store ₀	Store ₀	Store ₀	
18	Yellow	Enable ₀	Enable ₀	Enable ₀	
19	Brown	V/R ₀	V/R ₀	V/R ₀	
21	Gray	SET	SET	SET	
20	Blue	GND	GND	GND	
21	Red	V _{CC}	V _{CC}	V _{CC}	
Module		Screen	Screen	Screen	

² Not true only possible with a latex cufflet.

- U₁ Supply voltage to the encoder (before commissioning, note must be taken of the type label of the encoder).

GND Zero volt connection to the encoder electrically isolated from the housing. The voltage referred to GND is U_{e} .

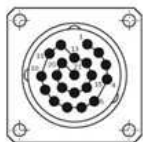
Forward/Reverse: The input programs the counting direction of the encoder, if not connected, this input is **High**. If the encoder shaft, as viewed on the drive shaft, rotates in the clockwise direction, it counts in an increasing sequence, if it should count speeds when the shaft rotates in the anti-clockwise direction, this connection must be connected permanently to **low-level (zero volts)**.

Enable_ This input activates the drive output driver when a drive-level is applied. If not connected, this input is drive-, in the case of a -high- level, the outputs are in

Input: This input activates the auto-capture camera when a input event is applied. It not connected, that input is none, in the case of a right arrow, the output are in the capture mode.

Slave₀ This input stores the encoder data in Gray code when a slave level is applied. This avoids a read error if the output data is requested in binary code. If this input is driven, the data at the encoder input is stable, independent of whether the input shaft rotates. Most manufacturers use input 0 as a slave.

Stable: This output assumes a stable level when the binary thickness of the data bits is even.



View of the connector M23 fitted to the encoder body Single, Parallel

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